

Package: momentuHMM (via r-universe)

October 12, 2024

Type Package

Title Maximum Likelihood Analysis of Animal Movement Behavior Using Multivariate Hidden Markov Models

Version 2.0.0

Date 2024-09-09

Depends R (>= 2.10)

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Description Extended tools for analyzing telemetry data using generalized hidden Markov models. Features of momentuHMM (pronounced ``momentum'') include data pre-processing and visualization, fitting HMMs to location and auxiliary biotelemetry or environmental data, biased and correlated random walk movement models, discrete- or continuous-time HMMs, continuous- or discrete-space movement models, approximate Langevin diffusion models, hierarchical HMMs, multiple imputation for incorporating location measurement error and missing data, user-specified design matrices and constraints for covariate modelling of parameters, random effects, decoding of the state process, visualization of fitted models, model checking and selection, and simulation. See McClintock and Michelot (2018) <[doi:10.1111/2041-210X.12995](https://doi.org/10.1111/2041-210X.12995)>.

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LazyData TRUE

Imports Rcpp, doParallel, foreach, numDeriv, CircStats, crawl (>= 2.2.1), mvtnorm, sp, MASS, Brodningnag, doRNG, rlang, raster, expm, TMB (>= 1.9.2)

LinkingTo Rcpp, RcppArmadillo, TMB, RcppEigen

Suggests testthat, setRNG, splines, splines2 (>= 0.2.8), R.rsp, conicfit, ggplot2, ggmap, lubridate, dplyr, magrittr, scatterplot3d, BB, matrixcalc, moveHMM, extraDistr, data.tree (>= 1.0.0), geosphere, mitools, doFuture, future, car,

survival, prodlim, nleqslv, qdapRegex, ctmcmove, Matrix,
gdistance, methods, mgcv, optimx, pracma

RoxygenNote 7.3.2

Encoding UTF-8

NeedsCompilation yes

VignetteBuilder R.rsp

URL <https://github.com/bmcclintock/momentuHMM>,
<https://github.com/bmcclintock/momentuHMM/discussions>

BugReports <https://github.com/bmcclintock/momentuHMM/issues>

Repository <https://bmcclintock.r-universe.dev>

RemoteUrl <https://github.com/bmcclintock/momentuHMM>

RemoteRef develop

RemoteSha 22b8141b6969365f4265e17ee9dcd486b19095b

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addSmoothGradient *Add smoothed gradient terms to data*

Description

Adds smoothed gradients to [momentuHMMDData](#) or [momentuHierHMMDData](#) objects, which can help reduce bias in gradient-based habitat selection coefficients

Usage

```
addSmoothGradient(
  data,
  spatialCovs,
  weights = c(1/2, 1/8, 1/8, 1/8, 1/8),
  scale = NULL
)
```

Arguments

| | |
|-------------|---|
| data | A momentuHMMData object (as returned by prepData or simData). |
| spatialCovs | List of raster objects for spatio-temporally referenced covariates. Covariates specified by <code>spatialCovs</code> are extracted from the raster layer(s) based on the location data (and the z values for a raster stack or brick) for each time step. If an element of <code>spatialCovs</code> is a raster stack or brick , then z values must be set using <code>raster::setZ</code> and data must include column(s) of the corresponding z value(s) for each observation (e.g., 'time'). |
| weights | Numeric vector indicating the weight for the points in a smoothed version of the gradient, where $\text{length}(\text{weights}) \in \{5, 9\}$ defines the number of points and $\text{sum}(\text{weights})=1$. Default: <code>c(1/2, 1/8, 1/8, 1/8, 1/8)</code> , where the first weight (1/2) corresponds to the gradient at the observed location, with the remaining weights (1/8, 1/8, 1/8, 1/8) corresponding to clockwise points around the observed location (i.e. northeast, southeast, southwest, northwest). The smoothed gradients are returned with ".xs" (easting gradient) and ".ys" (northing gradient) suffixes added to the names of <code>spatialCovs</code> . |
| scale | Numeric scalar indicating the distance from the observed location to each smoothing point (before adjusting by time step for continuous-time HMMs). Default: NULL, in which case the square root of the mean squared step lengths (divided by the time step for continuous-time HMMs) across all individuals is used, that is, $\text{scale} = \sqrt{0.5 * \text{mean}(\text{step}^2 / dt)}$, where <i>step</i> is step length and <i>dt</i> is the time step (note $dt = 1$ for discrete-time HMMs). The smoothing points are placed at a distance of $\text{scale}\sqrt{2dt}$ from the observed locations. |

Value

A [momentuHMM](#) or [momentuHierHMM](#) object, with the smooth gradients added for each spatial covariate.

References

Blackwell, P. G. and J. Matthiopoulos. 2024. Joint inference for telemetry and spatial survey data. *Ecology*

| | |
|----------------|------------|
| AIC.momentuHMM | <i>AIC</i> |
|----------------|------------|

Description

Akaike information criterion of momentuHMM model(s).

Usage

```
## S3 method for class 'momentuHMM'
AIC(object, ..., k = 2, n = NULL)
```

Arguments

| | |
|--------|---|
| object | A momentuHMM object. |
| ... | Optional additional momentuHMM objects, to compare AICs of the different models. These can be passed as a list using the !!! operator (see rlang and example in AICweights). |
| k | Penalty per parameter. Default: 2 ; for classical AIC. |
| n | Optional sample size. If specified, the small sample correction AIC is used (i.e., $AICc = AIC + kp(p+1)/(n-p-1)$ where p is the number of parameters). |

Value

The AIC of the model(s) provided. If several models are provided, the AICs are output in ascending order.

Examples

```
# m is a momentuHMM object (as returned by fitHMM), automatically loaded with the package
m <- example$m
AIC(m)

## Not run:
# HMM specifications
nbStates <- 2
stepDist <- "gamma"
angleDist <- "vm"
mu0 <- c(20,70)
sigma0 <- c(10,30)
kappa0 <- c(1,1)
stepPar0 <- c(mu0,sigma0)
anglePar0 <- c(-pi/2,pi/2,kappa0)
formula <- ~cov1+cov2

# example$m is a momentuHMM object (as returned by fitHMM), automatically loaded with the package
mod1 <- fitHMM(example$m$data,nbStates=nbStates,dist=list(step=stepDist,angle=angleDist),
               Par0=list(step=stepPar0,angle=anglePar0),
```

```

        formula=~1,estAngleMean=list(angle=TRUE))

Par0 <- getPar0(mod1,formula=formula)
mod2 <- fitHMM(example$m$data,nbStates=nStates,dist=list(step=stepDist,angle=angleDist),
              Par0=Par0$Par,beta0=Par0$beta,
              formula=formula,estAngleMean=list(angle=TRUE))

AIC(mod1,mod2)

Par0nA <- getPar0(mod1,estAngleMean=list(angle=FALSE))
mod3 <- fitHMM(example$m$data,nbStates=nStates,dist=list(step=stepDist,angle=angleDist),
              Par0=Par0nA$Par,beta0=Par0nA$beta,
              formula=~1)

AIC(mod1,mod2,mod3)

# add'l models provided as a list using the !!! operator
AIC(mod1, !!!list(mod2,mod3))

## End(Not run)

```

AICweights

Calculate Akaike information criterion model weights

Description

Calculate Akaike information criterion model weights

Usage

```
AICweights(..., k = 2, n = NULL)
```

Arguments

| | |
|-----|--|
| ... | momentuHMM , HMMfits , or miHMM objects, to compare AIC weights of the different models. The first object must be a momentuHMM , HMMfits , or miHMM object, but additional model objects can be passed as a list using the <code>!!!</code> operator (see rlang). |
| k | Penalty per parameter. Default: 2 ; for classical AIC. |
| n | Optional sample size. If specified, the small sample correction AIC is used (i.e., $AICc = AIC + kp(p+1)/(n-p-1)$ where p is the number of parameters). |

Details

- Model objects must all be either of class [momentuHMM](#) or multiple imputation model objects (of class [HMMfits](#) and/or [miHMM](#)).
- AIC is only valid for comparing models fitted to the same data. The data for each model fit must therefore be identical. For multiple imputation model objects, respective model fits must have identical data.

Value

The AIC weights of the models. If multiple imputation objects are provided, then the mean model weights (and standard deviations) are provided.

Examples

```
## Not run:
# HMM specifications
nbStates <- 2
stepDist <- "gamma"
angleDist <- "vm"
mu0 <- c(20,70)
sigma0 <- c(10,30)
kappa0 <- c(1,1)
stepPar0 <- c(mu0,sigma0)
anglePar0 <- c(-pi/2,pi/2,kappa0)
formula <- ~cov1+cov2

# example$m is a momentuHMM object (as returned by fitHMM), automatically loaded with the package
mod1 <- fitHMM(example$m$data,nbStates=nbStates,dist=list(step=stepDist,angle=angleDist),
               Par0=list(step=stepPar0,angle=anglePar0),
               formula=~1,estAngleMean=list(angle=TRUE))

Par0 <- getPar0(mod1,formula=formula)
mod2 <- fitHMM(example$m$data,nbStates=nbStates,dist=list(step=stepDist,angle=angleDist),
               Par0=Par0$Par,beta0=Par0$beta,
               formula=formula,estAngleMean=list(angle=TRUE))

AICweights(mod1,mod2)

Par0nA <- getPar0(mod1,estAngleMean=list(angle=FALSE))
mod3 <- fitHMM(example$m$data,nbStates=nbStates,dist=list(step=stepDist,angle=angleDist),
               Par0=Par0nA$Par,beta0=Par0nA$beta,
               formula=~1)

AICweights(mod1,mod2,mod3)

# add'l models provided as a list using the !!! operator
AICweights(mod1, !!!list(mod2,mod3))

## End(Not run)
```

allProbs

Matrix of all probabilities

Description

Used in functions [viterbi](#), [logAlpha](#), [logBeta](#).

Usage

```
allProbs(m)
```

Arguments

m Object [momentuHMM](#) or [miSum](#).

Value

Matrix of all probabilities.

Examples

```
## Not run:  
P <- momentuHMM:::allProbs(m=example$m)  
  
## End(Not run)
```

checkPar0

Check parameter length and order for a [fiTHMM](#) (or [MIfiTHMM](#)) model

Description

Prints parameters with labels based on DM, formula, and/or formulaDelta. See [fiTHMM](#) for further argument details.

Usage

```
checkPar0(data, ...)  
  
## Default S3 method:  
checkPar0(  
  data,  
  nbStates,  
  dist,  
  Par0 = NULL,  
  beta0 = NULL,  
  delta0 = NULL,  
  estAngleMean = NULL,  
  circularAngleMean = NULL,  
  formula = ~1,  
  formulaDelta = NULL,  
  stationary = FALSE,  
  mixtures = 1,  
  formulaPi = NULL,  
  DM = NULL,
```

```

userBounds = NULL,
workBounds = NULL,
betaCons = NULL,
betaRef = NULL,
deltaCons = NULL,
stateNames = NULL,
optMethod = "nlm",
fixPar = NULL,
prior = NULL,
...
)

## S3 method for class 'hierarchical'
checkPar0(
  data,
  hierStates,
  hierDist,
  Par0 = NULL,
  hierBeta = NULL,
  hierDelta = NULL,
  estAngleMean = NULL,
  circularAngleMean = NULL,
  hierFormula = NULL,
  hierFormulaDelta = NULL,
  mixtures = 1,
  formulaPi = NULL,
  DM = NULL,
  userBounds = NULL,
  workBounds = NULL,
  betaCons = NULL,
  deltaCons = NULL,
  optMethod = "nlm",
  fixPar = NULL,
  prior = NULL,
  ...
)

```

Arguments

| | |
|-----------------------|--|
| <code>data</code> | <code>momentuHMMDData</code> object, <code>momentuHierHMMDData</code> object, or a data frame containing the data stream and covariate values |
| <code>...</code> | further arguments passed to or from other methods |
| <code>nbStates</code> | Number of states of the HMM. |
| <code>dist</code> | A named list indicating the probability distributions of the data streams. |
| <code>Par0</code> | Optional named list containing vectors of state-dependent probability distribution parameters for each data stream specified in <code>dist</code> . If <code>Par0</code> is not provided, then ordered parameter indices are returned. |

| | |
|-------------------|--|
| beta0 | Optional matrix of regression coefficients for the transition probabilities. If beta0 is not provided, then ordered parameter indices are returned. |
| delta0 | Optional values or regression coefficients for the initial distribution of the HMM. If delta0 is not provided, then ordered parameter indices are returned. |
| estAngleMean | An optional named list indicating whether or not to estimate the angle mean for data streams with angular distributions ('vm' and 'wrpcauchy'). |
| circularAngleMean | An optional named list indicating whether to use circular-linear or circular-circular regression on the mean of circular distributions ('vm' and 'wrpcauchy') for turning angles. |
| formula | Regression formula for the transition probability covariates. |
| formulaDelta | Regression formula for the initial distribution. |
| stationary | FALSE if there are time-varying covariates in formula or any covariates in formulaDelta. If TRUE, the initial distribution is considered equal to the stationary distribution. Default: FALSE. |
| mixtures | Number of mixtures for the state transition probabilities. |
| formulaPi | Regression formula for the mixture distribution probabilities. Note that only the covariate values from the first row for each individual ID in data are used (i.e. time-varying covariates cannot be used for the mixture probabilities). |
| DM | An optional named list indicating the design matrices to be used for the probability distribution parameters of each data stream. |
| userBounds | An optional named list of 2-column matrices specifying bounds on the natural (i.e. real) scale of the probability distribution parameters for each data stream. |
| workBounds | An optional named list of 2-column matrices specifying bounds on the working scale of the probability distribution, transition probability, and initial distribution parameters. |
| betaCons | Matrix of the same dimension as beta0 composed of integers identifying any equality constraints among the t.p.m. parameters. |
| betaRef | Numeric vector of length nbStates indicating the reference elements for the t.p.m. multinomial logit link. |
| deltaCons | Matrix of the same dimension as delta0 composed of integers identifying any equality constraints among the initial distribution working scale parameters. Ignored unless a formula is provided in formulaDelta. |
| stateNames | Optional character vector of length nbStates indicating state names. |
| optMethod | The optimization method to be used. Can be "nlm" (the default; see nlm), "TMB" (using Template Model Builder; see optimx for control parameters), "Nelder-Mead" (see optim), or "SANN" (see optim). |
| fixPar | An optional list of vectors indicating parameters which are assumed known prior to fitting the model. |
| prior | A function that returns the log-density of the working scale parameter prior distribution(s). |
| hierStates | A hierarchical model structure Node for the states ('state'). See fitHMM . |
| hierDist | A hierarchical data structure Node for the data streams ('dist'). See fitHMM . |

| | |
|------------------|---|
| hierBeta | A hierarchical data structure Node for the initial matrix of regression coefficients for the transition probabilities at each level of the hierarchy ('beta'). See fitHMM . |
| hierDelta | A hierarchical data structure Node for the initial values for the initial distribution at each level of the hierarchy ('delta'). See fitHMM . |
| hierFormula | A hierarchical formula structure for the transition probability covariates for each level of the hierarchy ('formula'). See fitHMM . |
| hierFormulaDelta | A hierarchical formula structure for the initial distribution covariates for each level of the hierarchy ('formulaDelta'). See fitHMM . Default: NULL (no covariate effects and fixPar\$delta is specified on the working scale). |

See Also

[fitHMM](#), [MIfitHMM](#)

Examples

```
m <- example$m
checkPar0(data=m$data, nbStates=2, dist=m$conditions$dist,
           estAngleMean = m$conditions$estAngleMean,
           formula = m$conditions$formula)

par <- getPar(m)
checkPar0(data=m$data, nbStates=2, dist=m$conditions$dist,
           estAngleMean = m$conditions$estAngleMean,
           formula = m$conditions$formula,
           Par0=par$Par, beta0=par$beta, delta0=par$delta)

dummyDat <- data.frame(step=0, angle=0, cov1=0, cov2=0)
checkPar0(data=dummyDat, nbStates=2, dist=m$conditions$dist,
           estAngleMean = m$conditions$estAngleMean,
           formula = m$conditions$formula)

## Not run:
simDat <- simData(nbStates=2, dist=m$conditions$dist, Par = par$Par,
                 spatialCovs = list(forest=forest),
                 centers = matrix(0,1,2),
                 nbCovs = 2)
checkPar0(data = simDat, nbStates=2, dist=m$conditions$dist,
           formula = ~forest,
           DM = list(step=list(mean=~cov1, sd=~cov2),
                    angle=list(mean=~center1.angle, concentration=~1)),
           estAngleMean=list(angle=TRUE),
           circularAngleMean=list(angle=TRUE))

par <- list(step=rnorm(8), angle=rnorm(4))
beta0 <- matrix(rnorm(4),2,2)
delta0 <- c(0.5,0.5)
checkPar0(data = simDat, nbStates=2, dist=m$conditions$dist,
           Par0 = par, beta0 = beta0, delta0 = delta0,
           formula = ~forest,
```

```

DM = list(step=list(mean=~cov1, sd=~cov2),
          angle=list(mean=~center1.angle, concentration=~1)),
estAngleMean=list(angle=TRUE),
circularAngleMean=list(angle=TRUE))

## End(Not run)

```

CIbeta

Confidence intervals for working (i.e., beta) parameters

Description

Computes the standard errors and confidence intervals on the beta (i.e., working) scale of the data stream probability distribution parameters, as well as for the transition probabilities regression parameters. Working scale depends on the real (i.e., natural) scale of the parameters. For non-circular distributions or for circular distributions with `estAngleMean=FALSE`:

Usage

```
CIbeta(m, alpha = 0.95)
```

Arguments

| | |
|--------------------|---|
| <code>m</code> | A <code>momentuHMM</code> object |
| <code>alpha</code> | Significance level of the confidence intervals. Default: 0.95 (i.e. 95% CIs). |

Details

1) if both lower and upper bounds are finite then logit is the working scale; 2) if lower bound is finite and upper bound is infinite then log is the working scale.

For circular distributions with `estAngleMean=TRUE` and no constraints imposed by a design matrix (DM) or bounds (`userBounds`), then the working parameters are complex functions of both the angle mean and concentrations/sd natural parameters (in this case, it's probably best just to focus on the real parameter estimates!). However, if constraints are imposed by DM or `userBounds` on circular distribution parameters with `estAngleMean=TRUE` and `circularAngleMean=FALSE`:

1) if the natural bounds are $(-\pi, \pi]$ then tangent is the working scale, otherwise if both lower and upper bounds are finite then logit is the working scale; 2) if lower bound is finite and upper bound is infinite then log is the working scale.

When circular-circular regression is specified using `circularAngleMean`, the working scale for the mean turning angle is not as easily interpretable, but the link function is $\text{atan2}(\sin(X)*B, 1+\cos(X)*B)$, where X are the angle covariates and B the angle coefficients. Under this formulation, the reference turning angle is 0 (i.e., movement in the same direction as the previous time step). In other words, the mean turning angle is zero when the coefficient(s) $B=0$.

Value

A list of the following objects:

| | |
|------|---|
| ... | List(s) of estimates ('est'), standard errors ('se'), and confidence intervals ('lower', 'upper') for the working parameters of the data streams |
| beta | List of estimates ('est'), standard errors ('se'), and confidence intervals ('lower', 'upper') for the working parameters of the transition probabilities |

Examples

```
# m is a momentuHMM object (as returned by fitHMM), automatically loaded with the package
m <- example$m
```

```
CIbeta(m)
```

| | |
|------------|--|
| circAngles | <i>Convert standard direction angles (in radians relative to the x-axis) to turning angle covariates suitable for circular-circular regression on the angle mean</i> |
|------------|--|

Description

This function can be used to convert angular covariates (e.g., ocean currents, wind direction) measured in radians relative to the x-axis to turning angle covariates suitable for circular-circular regression in [fitHMM](#) or [MIfitHMM](#).

Usage

```
circAngles(refAngle, data, coordNames = c("x", "y"))
```

Arguments

| | |
|------------|---|
| refAngle | Numeric vector of standard direction angles (in radians) relative to the x-axis, where 0 = east, pi/2 = north, pi = west, -pi/2 = south |
| data | data frame containing fields for the x- and y-coordinates (identified by coordNames) and 'ID' (if more than one individual) |
| coordNames | Names of the columns of coordinates in data. Default: c("x", "y"). |

Value

A vector of turning angles between the movement direction at time step t-1 and refAngle at time t

Examples

```
# extract data from momentuHMM example
data<-example$m$data

# generate fake angle covariates
u <- rnorm(nrow(data)) # horizontal component
v <- rnorm(nrow(data)) # vertical component
refAngle <- atan2(v,u)

# add turning angle covariate to data
data$cov3 <- circAngles(refAngle=refAngle,data=data)
```

CIreal

Confidence intervals for the natural (i.e., real) parameters

Description

Computes the standard errors and confidence intervals on the real (i.e., natural) scale of the data stream probability distribution parameters, as well as for the transition probabilities parameters. If covariates are included in the probability distributions or TPM formula, the mean values of non-factor covariates are used for calculating the natural parameters. For any covariate(s) of class 'factor', then the value(s) from the first observation in the data are used.

Usage

```
CIreal(m, alpha = 0.95, covs = NULL, parms = NULL)

## Default S3 method:
CIreal(m, alpha = 0.95, covs = NULL, parms = NULL)

## S3 method for class 'hierarchical'
CIreal(m, alpha = 0.95, covs = NULL, parms = NULL)
```

Arguments

| | |
|-------|---|
| m | A momentuHMM, momentuHierHMM, miHMM, or miSum object |
| alpha | Significance level of the confidence intervals. Default: 0.95 (i.e. 95% CIs). |
| covs | Data frame consisting of a single row indicating the covariate values to be used in the calculations. By default, no covariates are specified. |
| parms | Optional character vector indicating which groups of real parameters to calculate confidence intervals for (e.g., 'step', 'angle', 'gamma', 'delta', etc.). Default: NULL, in which case confidence intervals are calculated for all groups of parameters in the model. |

Details

For any covariates that are not specified using covs, the means of the covariate(s) are used (unless the covariate is a factor, in which case the first factor in the data is used).

Value

A list of the following objects:

| | |
|-----------|--|
| ... | List(s) of estimates ('est'), standard errors ('se'), and confidence intervals ('lower', 'upper') for the natural parameters of the data streams |
| gamma | List of estimates ('est'), standard errors ('se'), and confidence intervals ('lower', 'upper') for the transition probabilities |
| delta | List of estimates ('est'), standard errors ('se'), and confidence intervals ('lower', 'upper') for the initial state probabilities |
| hierGamma | A hierarchical data structure Node including a list of estimates ('est'), standard errors ('se'), and confidence intervals ('lower', 'upper') for the transition probabilities for each level of the hierarchy (only applies if m is a hierarchical model object) |
| hierDelta | A hierarchical data structure Node including a list of estimates ('est'), standard errors ('se'), and confidence intervals ('lower', 'upper') for the initial state probabilities for each level of the hierarchy (only applies if m is a hierarchical model object) |

Examples

```
# m is a momentuHMM object (as returned by fitHMM), automatically loaded with the package
m <- example$m

ci1<-CIreal(m)

# specify 'covs'
ci2<-CIreal(m,covs=data.frame(cov1=mean(m$data$cov1),cov2=mean(m$data$cov2)))

all.equal(ci1,ci2)
```

| | |
|----------------|---|
| collapseRaster | <i>Transform a raster into a (x,y,z) list</i> |
|----------------|---|

Description

Transform a raster into a (x,y,z) list

Usage

```
collapseRaster(rast)
```


Arguments

rast raster layer object for spatially referenced covariates.

Value

List of three elements: x (grid of x values), y (grid of y values), and z (matrix of values).

| | |
|------------|---|
| crawlMerge | <i>Merge crwData or crwHierData object with additional data streams and/or covariates</i> |
|------------|---|

Description

This function can be used to merge `crwData` or `crwHierData` objects (as returned by `crawlWrap`) with additional data streams and/or covariates that are unrelated to location.

Usage

```
crawlMerge(crwData, data, Time.name)
```

Arguments

crwData A `crwData` or `crwHierData` object

data A data frame containing required columns `ID`, `Time.name`, and, if `crwData` is hierarchical, `level`, plus any additional data streams and/or covariates to merge with `crwData`.

Time.name Character string indicating name of the time column to be used for merging

Details

Specifically, the function merges the `crwData$crwPredict` data frame with data based on the `ID`, `Time.name`, and, if `crwData` is hierarchical, `level` columns. Thus data must contain `ID`, `Time.name`, and, if `crwData` is hierarchical, `level` columns.

Only rows of data with `ID`, `Time.name`, and, if `crwData` is hierarchical, `level` values that exactly match `crwData$crwPredict` are merged. Typically, the `Time.name` column in data should match predicted times of locations in `crwData$crwPredict` (i.e. those corresponding to `crwData$crwPredict$locType=="p"`)

Value

A `crwData` object

Examples

```
## Not run:
# extract simulated obsData from example data
obsData <- miExample$obsData

# error ellipse model
err.model <- list(x= ~ ln.sd.x - 1, y = ~ ln.sd.y - 1, rho = ~ error.corr)

# Fit crwMLE models to obsData and predict locations
# at default intervals for both individuals
crwOut <- crawlWrap(obsData=obsData,
  theta=c(4,0),fixPar=c(1,1,NA,NA),
  err.model=err.model,attempts=100)

# create data frame with fake data stream
data <- data.frame(ID=rep(factor(c(1,2)),times=c(753,652)),
  time=c(1:753,1:652),
  fake=rpois(753+652,5))

# merge fake data stream with crwOut
crwOut <- crawlMerge(crwOut,data,"time")

## End(Not run)
```

crawlWrap

Fit and predict tracks for using crawl

Description

Wrapper function for fitting `crawl::crwMLE` models and predicting locations with `crawl::crwPredict` for multiple individuals.

Usage

```
crawlWrap(
  obsData,
  timeStep = 1,
  ncores = 1,
  retryFits = 0,
  retrySD = 1,
  retryParallel = FALSE,
  mov.model = ~1,
  err.model = NULL,
  activity = NULL,
  drift = NULL,
  coord = c("x", "y"),
  proj = NULL,
```

```

    Time.name = "time",
    time.scale = "hours",
    theta,
    fixPar,
    method = "L-BFGS-B",
    control = NULL,
    constr = NULL,
    prior = NULL,
    need.hess = TRUE,
    initialSANN = list(maxit = 200),
    attempts = 1,
    predTime = NULL,
    fillCols = FALSE,
    coordLevel = NULL,
    ...
  )

```

Arguments

| | |
|-----------|--|
| obsData | data.frame object containing fields for animal ID ('ID'), time of observation (identified by <code>Time.name</code> , must be numeric or <code>POSIXct</code>), and observed locations (x- and y- coordinates identified by <code>coord</code>), such as that returned by <code>simData</code> when temporally-irregular observed locations or measurement error are included. Alternatively, a <code>SpatialPointsDataFrame</code> or <code>sf</code> object will also be accepted, in which case the <code>coord</code> values will be taken from the spatial data set and ignored in the arguments. Note that <code>crwMLE</code> requires that longitude/latitude coordinates be projected to UTM (i.e., easting/northing). If times identified by <code>Time.name</code> are <code>POSIXct</code> , a time zone must be specified. For further details see <code>crwMLE</code> . |
| timeStep | Length of the time step at which to predict regular locations from the fitted model. Unless <code>predTime</code> is specified, the sequence of times is <code>seq(a_i, b_i, timeStep)</code> where <code>a_i</code> and <code>b_i</code> are the times of the first and last observations for individual <code>i</code> . <code>timeStep</code> can be numeric (regardless of whether <code>obsData[[Time.name]]</code> is numeric or <code>POSIXct</code>) or a character string (if <code>obsData[[Time.name]]</code> is of class <code>POSIXct</code>) containing one of "sec", "min", "hour", "day", "DSTday", "week", "month", "quarter" or "year". This can optionally be preceded by a positive integer and a space, or followed by "s" (e.g., "2 hours"; see <code>seq.POSIXt</code>). <code>timeStep</code> is not used for individuals for which <code>predTime</code> is specified. |
| ncores | Number of cores to use for parallel processing. Default: 1 (no parallel processing). |
| retryFits | Number of times to attempt to achieve convergence and valid (i.e., not <code>NaN</code>) variance estimates after the initial model fit. |
| retrySD | An optional list of scalars or vectors for each individual indicating the standard deviation to use for normal perturbations of <code>theta</code> when <code>retryFits</code> >0 (or <code>attempts</code> >1). Instead of a list object, <code>retrySD</code> can also be a scalar or a vector, in which case the same values are used for each individual. If a scalar is provided, then the same value is used for each parameter. If a vector is provided, it must be of length <code>length(theta)</code> for the corresponding individual(s). Default: |

| | |
|----------------------------|--|
| | 1, i.e., a standard deviation of 1 is used for all parameters of all individuals. Ignored unless <code>retryFits>0</code> (or <code>attempts>1</code>). |
| <code>retryParallel</code> | Logical indicating whether or not to perform <code>retryFits</code> attempts for each individual in parallel. Default: <code>FALSE</code> . Ignored unless <code>retryFits>0</code> and <code>ncores>1</code> . Note that when attempts are done in parallel (i.e. <code>retryParallel=TRUE</code>), the current value for the log-likelihood of each individual and warnings about convergence are not printed to the console. |
| <code>mov.model</code> | List of <code>mov.model</code> objects (see crwMLE) containing an element for each individual. If only one movement model is provided, then the same movement model is used for each individual. |
| <code>err.model</code> | List of <code>err.model</code> objects (see crwMLE) containing an element for each individual. If only one error model is provided, then the same error model is used for each individual (in which case the names of the <code>err.model</code> components corresponding to easting/longitudinal and northing/latitudinal location error must match <code>coord</code>). |
| <code>activity</code> | List of activity objects (see crwMLE) containing an element for each individual. If only one activity covariate is provided, then the same activity covariate is used for each individual. |
| <code>drift</code> | List of drift objects (see crwMLE) containing an element for each individual. If only one drift component is provided, then the same drift component is used for each individual. |
| <code>coord</code> | A 2-vector of character values giving the names of the "x" and "y" coordinates in data. See crwMLE . |
| <code>proj</code> | A list of valid epsg integer codes or proj4string for <code>obsData</code> that does not inherit either 'sf' or 'sp'. A valid 'crs' list is also accepted. Otherwise, ignored. If only one <code>proj</code> is provided, then the same projection is used for each individual. |
| <code>Time.name</code> | Character indicating name of the location time column. See crwMLE . |
| <code>time.scale</code> | character. Scale for conversion of POSIX time to numeric for modeling. Defaults to "hours". |
| <code>theta</code> | List of <code>theta</code> objects (see crwMLE) containing an element for each individual. If only one <code>theta</code> is provided, then the same starting values are used for each individual. If <code>theta</code> is not specified, then crwMLE default values are used (i.e. each parameter is started at zero). |
| <code>fixPar</code> | List of <code>fixPar</code> objects (see crwMLE) containing an element for each individual. If only one <code>fixPar</code> is provided, then the same parameters are held fixed to the given value for each individual. If <code>fixPar</code> is not specified, then no parameters are fixed. |
| <code>method</code> | Optimization method that is passed to optim . |
| <code>control</code> | Control list which is passed to optim . |
| <code>constr</code> | List of <code>constr</code> objects (see crwMLE) containing an element for each individual. If only one <code>constr</code> is provided, then the same box constraints for the parameters are used for each individual. |
| <code>prior</code> | List of <code>prior</code> objects (see crwMLE) containing an element for each individual. If only one <code>prior</code> is provided, then the same prior is used for each individual. |

| | |
|-------------|---|
| need.hess | A logical value which decides whether or not to evaluate the Hessian for parameter standard errors |
| initialSANN | Control list for optim when simulated annealing is used for obtaining start values. See details |
| attempts | The number of times likelihood optimization will be attempted in cases where the fit does not converge or is otherwise non-valid. Note this is not the same as <code>retryFits</code> because <code>attempts</code> only applies when the current fit clearly does not appear to have converged; <code>retryFits</code> will proceed with additional model fitting attempts regardless of the model output. |
| predTime | List of <code>predTime</code> objects (see crwPredict) containing an element for each individual. <code>predTime</code> can be specified as an alternative to the automatic sequences generated according to <code>timeStep</code> . If only one <code>predTime</code> object is provided, then the same prediction times are used for each individual. |
| fillCols | Logical indicating whether or not to use the <code>crawl::fillCols</code> function for filling in missing values in <code>obsData</code> for which there is a single unique value. Default: FALSE. If the output from <code>crawlWrap</code> is intended for analyses using fithMM or MIfithMM , setting <code>fillCols=TRUE</code> should typically be avoided. |
| coordLevel | Character string indicating the level of the hierarchy for the location data. Ignored unless <code>obsData</code> includes a 'level' field. |
| ... | Additional arguments that are ignored. |

Details

- Consult [crwMLE](#) and [crwPredict](#) for further details about model fitting and prediction.
- Note that the names of the list elements corresponding to each individual in `mov.model`, `err.model`, `activity`, `drift`, `theta`, `fixPar`, `constr`, `prior`, and `predTime` must match the individual IDs in `obsData`. If only one element is provided for any of these arguments, then the same element will be applied to all individuals.

Value

A [crwData](#) or [crwHierData](#) object, i.e. a list of:

| | |
|-------------------------|--|
| <code>crwFits</code> | A list of <code>crwFit</code> objects returned by <code>crawl::crwMLE</code> . See crwMLE |
| <code>crwPredict</code> | A <code>crwPredict</code> data frame with <code>obsData</code> merged with the predicted locations. See crwPredict . |

The [crwData](#) object is used in [MIfithMM](#) analyses that account for temporal irregularity or location measurement error.

See Also

[MIfithMM](#), [simData](#)

Examples

```
## Not run:
# extract simulated obsData from example data
obsData <- miExample$obsData

# error ellipse model
err.model <- list(x= ~ ln.sd.x - 1, y = ~ ln.sd.y - 1, rho = ~ error.corr)

# Fit crwMLE models to obsData and predict locations
# at default intervals for both individuals
crwOut1 <- crawlWrap(obsData=obsData,
  theta=c(4,0),fixPar=c(1,1,NA,NA),
  err.model=err.model,attempts=100)

# Fit the same crwMLE models and predict locations
# at same intervals but specify for each individual using lists
crwOut2 <- crawlWrap(obsData=obsData,
  theta=list(c(4,0),c(4,0)), fixPar=list(c(1,1,NA,NA),c(1,1,NA,NA)),
  err.model=list(err.model,err.model),
  predTime=list('1'=seq(1,633),'2'=seq(1,686)))

## End(Not run)
```

crwData

Constructor of crwData objects

Description

Constructor of crwData objects

Usage

```
crwData(m)
```

Arguments

m A list of attributes of crawl output: crwFits (a list of crwFit objects) and crwPredict (a crwPredict object)

Value

An object crwData.

See Also

[crawlWrap](#), [MIfitHMM](#)

crwHierData *Constructor of crwHierData objects*

Description

Constructor of crwHierData objects

Usage

crwHierData(m)

Arguments

m A list of attributes of crawl output: crwFits (a list of crwFit objects) and crwPredict (a crwPredict object)

Value

An object crwHierData.

See Also

[crawlWrap](#), [MifitHMM](#)

crwHierSim *Constructor of crwHierSim objects*

Description

Constructor of crwHierSim objects

Usage

crwHierSim(m)

Arguments

m A list of attributes required for multiple imputation data generated from a [crwHierData](#) object using [MifitHMM](#): miData (a list of [momentuHMMData](#) objects), and crwSimulator (a list of [crwSimulator](#) objects).
crwHierSim objects are returned by [MifitHMM](#) when argument miData is a [crwHierData](#) object and argument fit=FALSE.

Value

An object crwHierSim.

| | |
|--------|--------------------------------------|
| crwSim | <i>Constructor of crwSim objects</i> |
|--------|--------------------------------------|

Description

Constructor of crwSim objects

Usage

```
crwSim(m)
```

Arguments

| | |
|---|---|
| m | A list of attributes required for multiple imputation data generated from a crwData object using MifitHMM : miData (a list of momentuHMMData objects), and crwSimulator (a list of crwSimulator objects). crwSim objects are returned by MifitHMM when argument miData is a crwData object and argument fit=FALSE. |
|---|---|

Value

An object crwSim.

| | |
|--------|--|
| ctdsUD | <i>Calculate and plot the (state-dependent) stationary (or utilization) distribution from a ctds fitted model object</i> |
|--------|--|

Description

This is essentially a wrapper function for [get.rate.matrix](#) and [get.UD](#) that has been extended for [momentuHMM](#).

Usage

```
ctdsUD(
  ctds,
  spatialCovs,
  spatialCovs.grad,
  zero.idx = integer(),
  method = "lu",
  maxiter,
  start,
  tol,
  log = FALSE
)
```


Arguments

| | |
|------------------|--|
| ctds | A ctds object returned by <code>fitCTHMM</code> |
| spatialCovs | List of <code>raster</code> objects for spatially referenced covariates. Raster <code>stacks</code> or <code>bricks</code> are not currently allowed. |
| spatialCovs.grad | List of <code>raster</code> objects for spatially referenced covariates, where a directional gradient is to be calculated internally using <code>rast.grad</code> . Raster <code>stacks</code> or <code>bricks</code> are not currently allowed. |
| zero.idx | Integer vector of the indices of raster cells that are not passable and should be excluded. These are cells where movement should be impossible. Default is <code>zero.idx=integer()</code> . |
| method | Either "lu" (default) or "limit". See <code>get.UD</code> details for a description of the two methods. |
| maxiter | Total number of iterations for limit method if tolerance not reached first. Defaults to 100. Ignored for <code>method='lu'</code> . |
| start | A value for the starting distribution for the 'limit' method. Defaults to <code>1/num.cells</code> . Ignored for <code>method='lu'</code> . |
| tol | Value used to assess convergence for limit method. If <code>max(abs(pi1-pi0))<tol</code> , limit method has converged. Defaults to <code>sqrt(.Machine\$double.eps)</code> . |
| log | Logical indicating whether or not to return the log UD. Default: <code>FALSE</code> . |

Value

A list of `raster` objects.

dbern_rcpp

Bernoulli density function

Description

Probability density function of the Bernoulli distribution (written in C++)

Usage

```
dbern_rcpp(x, prob, foo)
```

Arguments

| | |
|------|--|
| x | Vector of quantiles |
| prob | success probability |
| foo | Unused (for compatibility with template) |

Value

Vector of densities

`dbeta_rcpp`*Probability density function of the beta distribution (written in C++)*

Description

Probability density function of the beta distribution (written in C++)

Usage

```
dbeta_rcpp(x, shape1, shape2)
```

Arguments

| | |
|---------------------|---------------------|
| <code>x</code> | Vector of quantiles |
| <code>shape1</code> | Shape1 |
| <code>shape2</code> | Shape2 |

Value

Vector of densities

`dcat_rcpp`*Categorical density function*

Description

Probability density function of the categorical distribution (written in C++)

Usage

```
dcat_rcpp(x, prob, foo)
```

Arguments

| | |
|-------------------|--|
| <code>x</code> | Vector of quantiles |
| <code>prob</code> | success probability |
| <code>foo</code> | Unused (for compatibility with template) |

Value

Vector of densities

dcrwrice_rcpp *Correlated random walk Rice distribution*

Description

Probability density function of Rice distribution under the CTCRW model of Johnson et al. (2008) (written in C++)

Usage

```
dcrwrice_rcpp(x, beta, sigma)
```

Arguments

| | |
|-------|--|
| x | numeric data vector of length $n + n$ where the first n entries correspond to the step lengths and the next n entries to the corresponding previous step lengths (the first of which is NA and ignored). |
| beta | correlation parameter |
| sigma | speed parameter |

Value

Vector of densities

dcrwvm_rcpp *Correlated random walk von Mises density function*

Description

Probability density function of the Von Mises distribution under the CTCRW model of Johnson et al. (2008) (written in C++)

Usage

```
dcrwvm_rcpp(x, beta, sigma)
```

Arguments

| | |
|-------|---|
| x | numeric data vector of length $n + n + n$ where the first n entries correspond to angles (von Mises distribution), the next n entries to the corresponding step lengths, and the last n entries to the corresponding previous step lengths. |
| beta | correlation parameter |
| sigma | speed parameter |

Value

Vector of densities

`dexp_rcpp`*Exponential density function*

Description

Probability density function of the exponential distribution (written in C++)

Usage

```
dexp_rcpp(x, rate, foo)
```

Arguments

| | |
|-------------------|--|
| <code>x</code> | Vector of quantiles |
| <code>rate</code> | Rate |
| <code>foo</code> | Unused (for compatibility with template) |

Value

Vector of densities

`dgamma_rcpp`*Gamma density function*

Description

Probability density function of the gamma distribution (written in C++)

Usage

```
dgamma_rcpp(x, mu, sigma)
```

Arguments

| | |
|--------------------|---------------------|
| <code>x</code> | Vector of quantiles |
| <code>mu</code> | Mean |
| <code>sigma</code> | Standard deviation |

Value

Vector of densities

| | |
|-----------|---|
| distAngle | <i>Calculate distance between points y and z and turning angle between points x, y, and z</i> |
|-----------|---|

Description

Calculate distance between points y and z and turning angle between points x, y, and z

Usage

```
distAngle(x, y, z, type = "UTM", angleCov = TRUE)
```

Arguments

| | |
|----------|---|
| x | location 1 |
| y | location 2 |
| z | location 3 |
| type | 'UTM' if easting/northing provided (the default), 'LL' if longitude/latitude |
| angleCov | logical indicating to not return NA when x=y or y=z. Default: TRUE (i.e. NA is not returned if x=y or y=z). |

Details

Used in [prepData](#) and [simData](#) to get distance and turning angle covariates between locations (x1,x2), (y1,y2) and activity center (z1,z2).

If type='LL' then distance is calculated as great circle distance using [spDistsN1](#), and turning angle is calculated based on initial bearings using [bearing](#).

Value

2-vector with first element the distance between y and z and second element the turning angle between (x,y) and (y,z).

| | |
|-------------|------------------------------------|
| dlnorm_rcpp | <i>Log-normal density function</i> |
|-------------|------------------------------------|

Description

Probability density function of the log-normal distribution (written in C++)

Usage

```
dlnorm_rcpp(x, meanlog, sdlog)
```

Arguments

| | |
|---------|---|
| x | Vector of quantiles |
| meanlog | Mean of the distribution on the log-scale |
| sdlog | Standard deviation of the distribution on the log-scale |

Value

Vector of densities

| | |
|-------------|----------------------------------|
| dlogis_rcpp | <i>logistic density function</i> |
|-------------|----------------------------------|

Description

Probability density function of the logistic distribution (written in C++)

Usage

```
dlogis_rcpp(x, location, scale)
```

Arguments

| | |
|----------|--------------------------|
| x | Vector of quantiles |
| location | mean of the distribution |
| scale | Dispersion parameter |

Value

Vector of densities

| | |
|--------------|---|
| dmvnorm_rcpp | <i>C++ implementation of multivariate Normal probability density function for multiple inputs</i> |
|--------------|---|

Description

C++ implementation of multivariate Normal probability density function for multiple inputs

Usage

```
dmvnorm_rcpp(x, mean, varcovM)
```

Arguments

| | |
|---------|---|
| x | data matrix of dimension $p \times n$, p being the dimension of the data and n the number of data points. |
| mean | mean vectors matrix of dimension $p \times n$ |
| varcovM | $(nbStates * (p + (p * p - p)/2)) \times n$ matrix of all sds (sd.x.state1, sd.x.state2, ..., sd.y.state1, ...) and then correlations (corr.xy.state1, corr.xy.state2, ..., corr.xz.state1, corr.xz.state2, ...) from lower triangle of variance-covariance matrix. |

Value

matrix of densities of dimension $K \times n$.

| | |
|--------------|---|
| dnbinom_rcpp | <i>negative binomial density function</i> |
|--------------|---|

Description

Probability density function of the negative binomial distribution (written in C++)

Usage

```
dnbinom_rcpp(x, mu, size)
```

Arguments

| | |
|------|--------------------------|
| x | Vector of quantiles |
| mu | Mean of the distribution |
| size | Dispersion parameter |

Value

Vector of densities

| | |
|------------|--------------------------------|
| dnorm_rcpp | <i>Normal density function</i> |
|------------|--------------------------------|

Description

Probability density function of the normal distribution (written in C++)

Usage

```
dnorm_rcpp(x, mean, sd)
```

Arguments

| | |
|------|--|
| x | Vector of quantiles |
| mean | Mean of the distribution |
| sd | Standard deviation of the distribution |

Value

Vector of densities

| | |
|------------|---------------------------------|
| dpois_rcpp | <i>Poisson density function</i> |
|------------|---------------------------------|

Description

Probability density function of the Poisson distribution (written in C++)

Usage

```
dpois_rcpp(x, rate, foo)
```

Arguments

| | |
|------|--|
| x | Vector of quantiles |
| rate | Rate |
| foo | Unused (for compatibility with template) |

Value

Vector of densities

| | |
|---------|-----------------------------------|
| dt_rcpp | <i>student t density function</i> |
|---------|-----------------------------------|

Description

Probability density function of non-central student t (written in C++)

Usage

```
dt_rcpp(x, df, ncp)
```

Arguments

| | |
|-----|--------------------------|
| x | Vector of quantiles |
| df | degrees of freedom |
| ncp | non-centrality parameter |

Value

Vector of densities

| | |
|----------|-----------------------------------|
| dvm_rcpp | <i>Von Mises density function</i> |
|----------|-----------------------------------|

Description

Probability density function of the Von Mises distribution, defined as a function of the modified Bessel function of order 0 (written in C++)

Usage

```
dvm_rcpp(x, mu, kappa)
```

Arguments

| | |
|-------|---------------------|
| x | Vector of quantiles |
| mu | Mean |
| kappa | Concentration |

Value

Vector of densities

| | |
|---------------|---------------------------------|
| dweibull_rcpp | <i>Weibull density function</i> |
|---------------|---------------------------------|

Description

Probability density function of the Weibull distribution (written in C++)

Usage

```
dweibull_rcpp(x, shape, scale)
```

Arguments

| | |
|-------|---------------------|
| x | Vector of quantiles |
| shape | Shape |
| scale | Scale |

Value

Vector of densities

| | |
|-----------------|--|
| dwrpcauchy_rcpp | <i>Wrapped Cauchy density function</i> |
|-----------------|--|

Description

Probability density function of the wrapped Cauchy distribution (written in C++)

Usage

```
dwrpcauchy_rcpp(x, mu, rho)
```

Arguments

| | |
|-----|---------------------|
| x | Vector of quantiles |
| mu | Mean |
| rho | Concentration |

Value

Vector of densities

| | |
|-------------|------------------------|
| exampleData | <i>Example dataset</i> |
|-------------|------------------------|

Description

These data are used in the examples and tests of functions to keep them as short as possible.

Usage

example

miExample

forest

Details

example is a list of the following objects for demonstrating `fitHMM`:

- `m` A `momentuHMM` object
- `simPar` The parameters used to simulate data
- `par0` The initial parameters in the optimization to fit `m`

miExample is a list of the following objects for demonstrating `crawlWrap`, `MIfitHMM`, and `MIpool`:

- `obsData` Simulated observation data with measurement error and temporal irregularity (generated by `simData`)
- `bPar` initial parameter estimates for `MIfitHMM` examples

forest is a simulated spatial covariate `raster` object of the `RasterLayer` class

| | |
|-----------|--|
| expandPar | <i>Expand vector of free working parameters to vector of all working parameters including any fixed parameters (used in fitHMM.R and nLogLike.R)</i> |
|-----------|--|

Description

Expand vector of free working parameters to vector of all working parameters including any fixed parameters (used in `fitHMM.R` and `nLogLike.R`)

Usage

```

expandPar(
  optPar,
  optInd,
  fixPar,
  wparIndex,
  betaCons,
  deltaCons,
  nbStates,
  nbCovsDelta,
  stationary,
  nbCovs,
  nbRecovs = 0,
  mixtures = 1,
  nbCovsPi = 0,
  TMB = FALSE,
  Par0,
  beta0,
  delta0
)

```

Arguments

| | |
|-------------|--|
| optPar | vector of free working parameters |
| optInd | indices of constrained parameters |
| fixPar | Vector of working parameters which are assumed known prior to fitting the model (NA indicates parameters is to be estimated) |
| wparIndex | Vector of indices for the elements of fixPar that are not NA |
| betaCons | Matrix of the same dimension as beta0 composed of integers identifying any equality constraints among the t.p.m. parameters. |
| deltaCons | Matrix of the same dimension as del ta0 composed of integers identifying any equality constraints among the initial distribution working scale parameters. |
| nbStates | Number of states of the HMM |
| nbCovsDelta | Number of initial distribution covariates |
| stationary | FALSE if there are time-varying covariates in formula or any covariates in formulaDelta. If TRUE, the initial distribution is considered equal to the stationary distribution. Default: FALSE. |
| nbCovs | Number of t.p.m. covariates |
| nbRecovs | Number of recharge covariates |
| mixtures | Number of mixtures for the state transition probabilities |
| nbCovsPi | Number of mixture probability covariates |
| TMB | Logical indicating whether or not optMethod='TMB'. Default: FALSE. |
| Par0 | list of initial data stream parameter values. Ignored unless TMB=TRUE. |
| beta0 | matrix of initial state transition parameter values. Ignored unless TMB=TRUE. |
| delta0 | initial distribution parameter values. Ignored unless TMB=TRUE. |

Value

A vector of all working parameters including any fixed parameters

Examples

```
## Not run:
nbStates <- 2
stepDist <- "gamma" # step distribution
angleDist <- "vm" # turning angle distribution

# extract data from momentuHMM example
data <- example$m$data

### 1. fit the model to the simulated data
# define initial values for the parameters
mu0 <- c(20,70)
sigma0 <- c(10,30)
kappa0 <- c(1,1)
stepPar <- c(mu0,sigma0) # no zero-inflation, so no zero-mass included
anglePar <- kappa0 # not estimating angle mean, so not included
formula <- ~cov1+cos(cov2)

# constrain cov1 effect to state 1 -> 2 and cov2 effect to state 2 -> 1
fixPar <- list(beta=c(NA,NA,0,NA,0,NA))

m <- fitHMM(data=data,nbStates=nbStates,dist=list(step=stepDist,angle=angleDist),
            Par0=list(step=stepPar,angle=anglePar),formula=formula,fixPar=fixPar)

# convert free parameter vector (m$mod$wpar) to full set of working parameters (m$mod$estimate)
est <- momentuHMM:::expandPar(m$mod$wpar,m$conditions$optInd,unlist(m$conditions$fixPar),
                             m$conditions$wparIndex,m$conditions$betaCons,m$conditions$deltaCons,
                             nbStates,
                             ncol(m$covsDelta)-1,m$conditions$stationary,nrow(m$mle$beta)-1)

all(est==m$mod$estimate)

## End(Not run)
```

expmatrix_rcpp

Matrix Exponential

Description

This function computes the exponential of a square matrix A , defined as the sum from $r=0$ to infinity of $A^r/r!$, using the default method of [expm](#).

Usage

```
expmatrix_rcpp(x, kappa = NA_real_, check = FALSE)
```

Arguments

| | |
|-------|--|
| x | a square matrix. |
| kappa | maximum allowed value for the row sums of the off-diagonal elements in the state transition rate matrix, such that the minimum value for the diagonal elements is $-\text{kappa}$. Default: Inf. Setting less than Inf can help avoid numerical issues during optimization. |
| check | logical indicating whether or not to check transition probability matrix for issues |

Value

The matrix exponential of x.

fitCTHMM

Fit a continuous-time multivariate HMM to the data

Description

Fit an approximate continuous-time (multivariate) hidden Markov model to the data provided, using numerical optimization of the log-likelihood function. The discrete-time approximation of the continuous-time model improves as the time between observations decreases. Note that any time-varying covariates are assumed piece-wise constant between observations.

Usage

```
fitCTHMM(data, ...)

## S3 method for class 'momentuHMMDData'
fitCTHMM(
  data,
  nbStates,
  dist,
  Par0,
  beta0 = NULL,
  delta0 = NULL,
  estAngleMean = NULL,
  circularAngleMean = NULL,
  formula = ~1,
  formulaDelta = NULL,
  stationary = FALSE,
  mixtures = 1,
  formulaPi = NULL,
  nlmPar = list(),
  fit = TRUE,
  DM = NULL,
  userBounds = NULL,
  workBounds = NULL,
```

```
betaCons = NULL,
deltaCons = NULL,
mvnCoords = NULL,
stateNames = NULL,
knownStates = NULL,
fixPar = NULL,
retryFits = 0,
retrySD = NULL,
ncores = 1,
optMethod = "nlm",
control = list(),
prior = NULL,
modelName = NULL,
kappa = Inf,
...
)

## S3 method for class 'momentuHierHMMData'
fitCTHMM(
  data,
  hierStates,
  hierDist,
  Par0,
  hierBeta = NULL,
  hierDelta = NULL,
  estAngleMean = NULL,
  circularAngleMean = NULL,
  hierFormula = NULL,
  hierFormulaDelta = NULL,
  mixtures = 1,
  formulaPi = NULL,
  nlmPar = list(),
  fit = TRUE,
  DM = NULL,
  userBounds = NULL,
  workBounds = NULL,
  betaCons = NULL,
  deltaCons = NULL,
  mvnCoords = NULL,
  knownStates = NULL,
  fixPar = NULL,
  retryFits = 0,
  retrySD = NULL,
  ncores = 1,
  optMethod = "nlm",
  control = list(),
  prior = NULL,
  modelName = NULL,
```

```

    kappa = Inf,
    ...
)

```

Arguments

| | |
|--------------|---|
| data | A momentuHMMData (as returned by prepData , simData , prepCTDS , or simCTDS) or a momentuHierHMMData (as returned by prepData or simHierData) object. |
| ... | further arguments passed to or from other methods |
| nbStates | Number of states of the HMM. |
| dist | A named list indicating the probability distributions of the data streams. Currently supported distributions are 'bern', 'beta', 'cat', 'ctds', 'exp', 'gamma', 'lnorm', 'logis', 'negbinom', 'norm', 'mvnorm2' (bivariate normal distribution), 'mvnorm3' (trivariate normal distribution), 'pois', 'rw_norm' (normal random walk), 'rw_mvnorm2' (bivariate normal random walk), 'rw_mvnorm3' (trivariate normal random walk), 't', and 'weibull'. See fitHMM . For continuous-time HMMs, the (multivariate) normal random walk ('rw_norm', 'rw_mvnorm2', 'rw_mvnorm3') and Poisson ('pois') distributions are modeled as a function of the time interval between observations (Δ_t). All other data stream distributions assume observations do not depend on Δ_t , i.e., they are "instantaneous" and only depend on the state active at time t . See details. |
| Par0 | A named list containing vectors of initial state-dependent probability distribution parameters for each data stream specified in <code>dist</code> . The parameters should be in the order expected by the pdfs of <code>dist</code> , and any zero-mass and/or one-mass parameters should be the last (if both are present, then zero-mass parameters must precede one-mass parameters). Note that zero-mass parameters are mandatory if there are zeros in data streams with a 'gamma', 'weibull', 'exp', 'lnorm', or 'beta' distribution, and one-mass parameters are mandatory if there are ones in data streams with a 'beta' distribution. For example, for a 2-state model using the Von Mises (vm) distribution for a data stream named 'angle' and the zero-inflated gamma distribution for a data stream named 'step', the vector of initial parameters would be something like: <code>Par0=list(step=c(mean_1, mean_2, sd_1, sd_2, zeromass_1, zeromass_2), angle=c(mean_1, mean_2, concentration_1, concentration_2))</code> . If DM is not specified for a given data stream, then <code>Par0</code> is on the natural (i.e., real) scale of the parameters. However, if DM is specified for a given data stream, then <code>Par0</code> must be on the working (i.e., beta) scale of the parameters, and the length of <code>Par0</code> must match the number of columns in the design matrix. See details below. |
| beta0 | Initial matrix of regression coefficients for the transition probabilities (more information in 'Details'). Default: NULL. If not specified, <code>beta0</code> is initialized such that the diagonal elements of the transition probability matrix are dominant. |
| delta0 | Initial value for the initial distribution of the HMM. Default: <code>rep(1/nbStates, nbStates)</code> . If <code>formulaDelta</code> includes a formula, then <code>delta0</code> must be specified as a $k \times (nbStates-1)$ matrix, where k is the number of covariates and the columns correspond to states 2:nbStates. See details below. |
| estAngleMean | An optional named list indicating whether or not to estimate the angle mean for data streams with angular distributions ('vm' and 'wrpcauchy'). For example, |

`estAngleMean=list(angle=TRUE)` indicates the angle mean is to be estimated for 'angle'. Default is NULL, which assumes any angle means are fixed to zero and are not to be estimated. Any `estAngleMean` elements corresponding to data streams that do not have angular distributions are ignored. `estAngleMean` is also ignored for any 'vmConsensus' data streams (because the angle mean must be estimated in consensus models).

`circularAngleMean`

An optional named list indicating whether to use circular-linear (FALSE) or circular-circular (TRUE) regression on the mean of circular distributions ('vm' and 'wrpcauchy') for turning angles. For example, `circularAngleMean=list(angle=TRUE)` indicates the angle mean is to be estimated for 'angle' using circular-circular regression. Whenever circular-circular regression is used for an angular data stream, a corresponding design matrix (DM) must be specified for the data stream, and the previous movement direction (i.e., a turning angle of zero) is automatically used as the reference angle (i.e., the intercept). Any circular-circular regression covariates in data should therefore be relative to the previous direction of movement (instead of standard directions relative to the x-axis; see [prepData](#) and [circAngles](#)). See Duchesne et al. (2015) for specifics on the circular-circular regression model using previous movement direction as the reference angle. Default is NULL, which assumes circular-linear regression is used for any angular distributions for which the mean angle is to be estimated. `circularAngleMean` elements corresponding to angular data streams are ignored unless the corresponding element of `estAngleMean` is TRUE. Any `circularAngleMean` elements corresponding to data streams that do not have angular distributions are ignored. `circularAngleMean` is also ignored for any 'vmConsensus' data streams (because the consensus model is a circular-circular regression model). Alternatively, `circularAngleMean` can be specified as a numeric scalar, where the value specifies the coefficient for the reference angle (i.e., directional persistence) term in the circular-circular regression model. For example, setting `circularAngleMean` to 0 specifies a circular-circular regression model with no directional persistence term (thus specifying a biased random walk instead of a biased correlated random walk). Setting `circularAngleMean` to 1 is equivalent to setting it to TRUE, i.e., a circular-circular regression model with a coefficient of 1 for the directional persistence reference angle.

`formula`

Regression formula for the transition probability covariates. Default: ~1 (no covariate effect). In addition to allowing standard functions in R formulas (e.g., `cos(cov)`, `cov1*cov2`, `I(cov^2)`), special functions include `cosinor(cov,period)` for modeling cyclical patterns, spline functions ([bs](#), [ns](#), [bSpline](#), [cSpline](#), [iSpline](#), and [mSpline](#)), and state- or parameter-specific formulas (see details). Any formula terms that are not state- or parameter-specific are included on all of the transition probabilities.

`formulaDelta`

Regression formula for the initial distribution. Default for `fitCTHMM.momentuHMMData`: NULL (no covariate effects; both `delta0` and `fixPar$delta` are specified on the real scale). Default for `fitCTHMM.momentuHierHMMData`: ~1 (both `delta0` and `fixPar$delta` are specified on the working scale). Standard functions in R formulas are allowed (e.g., `cos(cov)`, `cov1*cov2`, `I(cov^2)`). When any formula is provided, then both `delta0` and `fixPar$delta` are specified on the working scale.

| | |
|------------|--|
| stationary | FALSE if there are time-varying covariates in formula or any covariates in formulaDelta. If TRUE, the initial distribution is considered equal to the stationary distribution. Default: FALSE. |
| mixtures | Number of mixtures for the state transition probabilities (i.e. discrete random effects *sensu* DeRuiter et al. 2017). Default: mixtures=1. |
| formulaPi | Regression formula for the mixture distribution probabilities. Default: NULL (no covariate effects; both beta0\$pi and fixPar\$pi are specified on the real scale). Standard functions in R formulas are allowed (e.g., cos(cov), cov1*cov2, I(cov^2)). When any formula is provided, then both beta0\$pi and fixPar\$pi are specified on the working scale. Note that only the covariate values from the first row for each individual ID in data are used (i.e. time-varying covariates cannot be used for the mixture probabilities). |
| nlmPar | List of parameters to pass to the optimization function nlm (which should be either print.level, gradtol, stepmax, steptol, iterlim, or hessian – see nlm’s documentation for more detail). For print.level, the default value of 0 means that no printing occurs, a value of 1 means that the first and last iterations of the optimization are detailed, and a value of 2 means that each iteration of the optimization is detailed. Ignored unless optMethod="nlm". |
| fit | TRUE if an HMM should be fitted to the data, FALSE otherwise. If fit=FALSE, a model is returned with the MLE replaced by the initial parameters given in input. This option can be used to assess the initial parameters, parameter bounds, etc. Default: TRUE. |
| DM | An optional named list indicating the design matrices to be used for the probability distribution parameters of each data stream. Each element of DM can either be a named list of linear regression formulas or a “pseudo” design matrix. For example, for a 2-state model using the gamma distribution for a data stream named ‘step’, DM=list(step=list(mean=~cov1, sd=~1)) specifies the mean parameters as a function of the covariate ‘cov1’ for each state. This model could equivalently be specified as a 4x6 “pseudo” design matrix using character strings for the covariate: DM=list(step=matrix(c(1,0,0,0, 'cov1', 0,0,0,0,1,0,0,0, 'cov1', 0,0,0,0,1,0,0,0), where the 4 rows correspond to the state-dependent parameters (mean_1,mean_2,sd_1,sd_2) and the 6 columns correspond to the regression coefficients. Design matrices specified using formulas allow standard functions in R formulas (e.g., cos(cov), cov1*cov2, I(cov^2)). Special formula functions include cosinor(cov,period) for modeling cyclical patterns, spline functions (bs, ns, bSpline, cSpline, iSpline, and mSpline), angleFormula(cov, strength, by) for the angle mean of circular-circular regression models, and state-specific formulas (see details). Any formula terms that are not state-specific are included on the parameters for all nbStates states. |
| userBounds | An optional named list of 2-column matrices specifying bounds on the natural (i.e. real) scale of the probability distribution parameters for each data stream. For each matrix, the first column pertains to the lower bound and the second column the upper bound. For example, for a 2-state model using the wrapped Cauchy (‘wrpcauchy’) distribution for a data stream named ‘angle’ with estAngleMean\$angle=TRUE, userBounds=list(angle=matrix(c(-pi, -pi, -1, -1, pi, pi, 1, 1), specifies (-1,1) bounds for the concentration parameters instead of the default [0,1) bounds. |

| | |
|-------------|--|
| workBounds | An optional named list of 2-column matrices specifying bounds on the working scale of the probability distribution, transition probability, and initial distribution parameters. For each matrix, the first column pertains to the lower bound and the second column the upper bound. For data streams, each element of workBounds should be a $k \times 2$ matrix with the same name of the corresponding element of Par0, where k is the number of parameters. For transition probability parameters, the corresponding element of workBounds must be a $k \times 2$ matrix named “beta”, where $k = \text{length}(\text{beta}0)$. For initial distribution parameters, the corresponding element of workBounds must be a $k \times 2$ matrix named “delta”, where $k = \text{length}(\text{delta}0)$. workBounds is ignored for any given data stream unless DM is also specified. |
| betaCons | Matrix of the same dimension as beta0 composed of integers identifying any equality constraints among the t.p.m. parameters. See details. |
| deltaCons | Matrix of the same dimension as delta0 composed of integers identifying any equality constraints among the initial distribution working scale parameters. Ignored unless a formula is provided in formulaDelta. See details. |
| mvnCoords | Character string indicating the name of location data that are to be modeled using a multivariate normal distribution. For example, if mu=“mvnorm2” was included in dist and (mu.x, mu.y) are location data, then mvnCoords=“mu” needs to be specified in order for these data to be properly treated as locations in functions such as plot.momentuHMM, plot.miSum, plot.miHMM, plotSpatialCov, and MIpool. |
| stateNames | Optional character vector of length nbStates indicating state names. |
| knownStates | Vector of values of the state process which are known prior to fitting the model (if any). Default: NULL (states are not known). This should be a vector with length the number of rows of 'data'; each element should either be an integer (the value of the known states) or NA if the state is not known. |
| fixPar | An optional list of vectors indicating parameters which are assumed known prior to fitting the model. Default: NULL (no parameters are fixed). For data streams, each element of fixPar should be a vector of the same name and length as the corresponding element of Par0. For transition probability parameters, the corresponding element of fixPar must be named “beta” and have the same dimensions as beta0. For initial distribution parameters, the corresponding element of fixPar must be named “delta” and have the same dimensions as delta0. Each parameter should either be numeric (the fixed value of the parameter) or NA if the parameter is to be estimated. Corresponding fixPar parameters must be on the same scale as Par0 (e.g. if DM is specified for a given data stream, any fixed parameters for this data stream must be on the working scale), beta0, and delta0. If optMethod='TMB' then fixPar is specified differently. In this case, NA instead indicates parameters that are fixed (to the value specified by Par0, beta0, or delta0) and the parameters that are not fixed are sequentially indexed (similar to betaCons) by parameter number (such that parameters can be constrained to be equal). For example, fixPar=list(angle=c(NA,NA,1,2)) indicates the first two parameters of the 'angle' distribution are fixed and the other two parameters are freely estimated. fixPar=list(angle=c(1,NA,2,2,3)) indicates the first angle parameter is freely estimated, the second parameter is fixed, the third and |

fourth parameters are constrained to be equal, and the fifth parameter is freely estimated.

| | |
|------------|--|
| retryFits | Non-negative integer indicating the number of times to attempt to iteratively fit the model using random perturbations of the current parameter estimates as the initial values for likelihood optimization. $\text{Normal}(0, \text{retrySD}^2)$ perturbations are used on the working scale parameters. Default: 0. When $\text{retryFits} > 0$, the model with the largest log likelihood value is returned. Ignored if $\text{fit} = \text{FALSE}$. |
| retrySD | An optional list of scalars or vectors indicating the standard deviation to use for normal perturbations of each working scale parameter when $\text{retryFits} > 0$. For data streams, each element of retrySD should be a vector of the same name and length as the corresponding element of $\text{Par}\theta$ (if a scalar is provided, then this value will be used for all working parameters of the data stream). For transition probability parameters, the corresponding element of retrySD must be named "beta" and have the same dimensions as $\text{beta}\theta$. For initial distribution parameters, the corresponding element of retrySD must be named "delta" and have the same dimensions as $\text{delta}\theta$ (if $\text{delta}\theta$ is on the working scale) or be of length $\text{nbStates} - 1$ (if $\text{delta}\theta$ is on the natural scale). Alternatively retrySD can be a scalar, in which case this value is used for all parameters. Instead of numeric scalars, retrySD can also be specified as "adapt" in which case the standard deviation is adapted as $10^{\lceil \log_{10}(\text{abs}(x)) \rceil}$ (where x is the current value of the corresponding working parameter) Default: NULL (in which case $\text{retrySD} = 1$ for data stream parameters and $\text{retrySD} = 10$ for initial distribution and state transition probabilities). Ignored unless $\text{retryFits} > 0$. |
| ncores | Number of cores to use for parallel processing when $\text{retryFits} > 0$. Default: 1 (no parallel processing). When retryFits attempts are performed in parallel, each attempt uses perturbations of the initial model fit (i.e. they are not iteratively updated as when $\text{ncores} = 1$). |
| optMethod | The optimization method to be used. Can be "nlm" (the default; see nlm), "TMB" (using Template Model Builder; see optimx for control parameters), "Nelder-Mead" (see optim), or "SANN" (see optim). |
| control | A list of control parameters to be passed to optim (ignored unless $\text{optMethod} = \text{"TMB"}$, $\text{optMethod} = \text{"Nelder-Mead"}$, or $\text{optMethod} = \text{"SANN"}$). |
| prior | A function that returns the log-density of the working scale parameter prior distribution(s). See 'Details'. |
| modelName | An optional character string providing a name for the fitted model. If provided, modelName will be returned in print.momentuHMM , AIC.momentuHMM , AICweights , and other functions. |
| kappa | maximum allowed value for the row sums of the off-diagonal elements in the state transition rate matrix, such that the minimum value for the diagonal elements is $-\text{kappa}$. Default: Inf. Setting less than Inf can help avoid numerical issues during optimization, in which case the transition rate parameters beta are on the logit scale (instead of the log scale). |
| hierStates | A hierarchical model structure Node for the states ('state'). See details. |
| hierDist | A hierarchical data structure Node for the data streams ('dist'). See details. |

| | |
|------------------|---|
| hierBeta | A hierarchical data structure Node for the matrix of initial values for the regression coefficients of the transition probabilities at each level of the hierarchy ('beta'). See details. |
| hierDelta | A hierarchical data structure Node for the matrix of initial values for the regression coefficients of the initial distribution at each level of the hierarchy ('delta'). See details. |
| hierFormula | A hierarchical formula structure for the transition probability covariates for each level of the hierarchy ('formula'). Default: NULL (only hierarchical-level effects, with no covariate effects). Any formula terms that are not state- or parameter-specific are included on all of the transition probabilities within a given level of the hierarchy. See details. |
| hierFormulaDelta | A hierarchical formula structure for the initial distribution covariates for each level of the hierarchy ('formulaDelta'). Default: NULL (no covariate effects and <code>fixPar\$delta</code> is specified on the working scale). |

Details

fitCTHMM assumes the snapshot property applies to all data stream distributions (i.e. observations are “instantaneous”) except for the (multivariate) normal random walk (`rw_norm`, `rw_mvnorm2`, `rw_mvnorm3`) and Poisson (`pois`) distributions. For these particular distributions, the observed data are not “instantaneous”; they depend on the time interval between observations (Δ_t) and, hence, the state sequence during the entire interval. When fitting with `fitCTHMM` (or `MIfitCTHMM`), it is critical that the frequency of observations is high relative to the serial correlation in the hidden state process in order for the discrete-time approximation of `fitCTHMM` to be reasonably accurate for these distributions.

`fitCTHMM.momentuHierHMMData` is very similar to `fitCTHMM.momentuHMMData` except that instead of simply specifying the number of states (`nbStates`), distributions (`dist`), and a single t.p.m. formula (`formula`), the `hierStates` argument specifies the hierarchical nature of the states, the `hierDist` argument specifies the hierarchical nature of the data streams, and the `hierFormula` argument specifies a t.p.m. formula for each level of the hierarchy. All are specified as [Node](#) objects from the `data.tree` package.

Value

A `momentuHMM` or `momentuHierHMM` object, i.e. a list of:

| | |
|--------|---|
| mle | A named list of the maximum likelihood estimates of the parameters of the model (if the numerical algorithm has indeed identified the global maximum of the likelihood function). Elements are included for the parameters of each data stream, as well as <code>beta</code> (transition probabilities regression coefficients - more information in 'Details'), <code>gamma</code> (transition probabilities on real scale, based on mean covariate values if formula includes covariates), and <code>delta</code> (initial distribution). |
| CIreal | Standard errors and 95% confidence intervals on the real (i.e., natural) scale of parameters |
| CIbeta | Standard errors and 95% confidence intervals on the beta (i.e., working) scale of parameters |

| | |
|-------------|---|
| data | The momentuHMMDData or momentuHierHMMDData object |
| mod | List object returned by the numerical optimizer <code>nlm</code> or <code>optim</code> . Items in <code>mod</code> include the best set of free working parameters found (<code>wpar</code>), the best full set of working parameters including any fixed parameters (<code>estimate</code>), the value of the likelihood at estimate (<code>minimum</code>), the estimated variance-covariance matrix at estimate (<code>Sigma</code>), and the elapsed time in seconds for the optimization (<code>elapsedTime</code>). |
| conditions | Conditions used to fit the model, e.g., bounds (parameter bounds), distributions, zeroInflation, <code>estAngleMean</code> , stationary, formula, DM, fullDM (full design matrix), etc. |
| rawCovs | Raw covariate values for transition probabilities, as found in the data (if any). Used in <code>plot.momentuHMM</code> . |
| stateNames | The names of the states. |
| knownStates | Vector of values of the state process which are known. |
| covsDelta | Design matrix for initial distribution. |

See Also

[simHierData](#)

fitHMM

Fit a multivariate HMM to the data

Description

Fit a (multivariate) hidden Markov model to the data provided, using numerical optimization of the log-likelihood function.

Usage

```
fitHMM(data, ...)

## S3 method for class 'momentuHMMDData'
fitHMM(
  data,
  nbStates,
  dist,
  Par0,
  beta0 = NULL,
  delta0 = NULL,
  estAngleMean = NULL,
  circularAngleMean = NULL,
  formula = ~1,
  formulaDelta = NULL,
  stationary = FALSE,
```

```
    mixtures = 1,
    formulaPi = NULL,
    nlmPar = list(),
    fit = TRUE,
    DM = NULL,
    userBounds = NULL,
    workBounds = NULL,
    betaCons = NULL,
    betaRef = NULL,
    deltaCons = NULL,
    mvnCoords = NULL,
    stateNames = NULL,
    knownStates = NULL,
    fixPar = NULL,
    retryFits = 0,
    retrySD = NULL,
    ncores = 1,
    optMethod = "nlm",
    control = list(),
    prior = NULL,
    modelName = NULL,
    ...
)

## S3 method for class 'momentuHierHMMData'
fitHMM(
  data,
  hierStates,
  hierDist,
  Par0,
  hierBeta = NULL,
  hierDelta = NULL,
  estAngleMean = NULL,
  circularAngleMean = NULL,
  hierFormula = NULL,
  hierFormulaDelta = NULL,
  mixtures = 1,
  formulaPi = NULL,
  nlmPar = list(),
  fit = TRUE,
  DM = NULL,
  userBounds = NULL,
  workBounds = NULL,
  betaCons = NULL,
  deltaCons = NULL,
  mvnCoords = NULL,
  knownStates = NULL,
  fixPar = NULL,
```

```

    retryFits = 0,
    retrySD = NULL,
    ncores = 1,
    optMethod = "nlm",
    control = list(),
    prior = NULL,
    modelName = NULL,
    ...
)

```

Arguments

| | |
|----------|---|
| data | A momentuHMMData (as returned by prepData or simData) or a momentuHierHMMData (as returned by prepData or simHierData) object. |
| ... | further arguments passed to or from other methods |
| nbStates | Number of states of the HMM. |
| dist | A named list indicating the probability distributions of the data streams. Currently supported distributions are 'bern', 'beta', 'cat', 'exp', 'gamma', 'lnorm', 'logis', 'negbinom', 'norm', 'mvnorm2' (bivariate normal distribution), 'mvnorm3' (trivariate normal distribution), 'pois', 'rw_norm' (normal random walk), 'rw_mvnorm2' (bivariate normal random walk), 'rw_mvnorm3' (trivariate normal random walk), 'vm', 'vmConsensus', 'weibull', and 'wrpcauchy'. For example, <code>dist=list(step='gamma', angle='vm', dives='pois')</code> indicates 3 data streams ('step', 'angle', and 'dives') and their respective probability distributions ('gamma', 'vm', and 'pois'). The names of the data streams (e.g., 'step', 'angle', 'dives') must match component names in data. |
| Par0 | A named list containing vectors of initial state-dependent probability distribution parameters for each data stream specified in <code>dist</code> . The parameters should be in the order expected by the pdfs of <code>dist</code> , and any zero-mass and/or one-mass parameters should be the last (if both are present, then zero-mass parameters must precede one-mass parameters). Note that zero-mass parameters are mandatory if there are zeros in data streams with a 'gamma', 'weibull', 'exp', 'lnorm', or 'beta' distribution, and one-mass parameters are mandatory if there are ones in data streams with a 'beta' distribution. For example, for a 2-state model using the Von Mises (vm) distribution for a data stream named 'angle' and the zero-inflated gamma distribution for a data stream named 'step', the vector of initial parameters would be something like: <code>Par0=list(step=c(mean_1, mean_2, sd_1, sd_2, zeromass_1, zeromass_2), angle=c(mean_1, mean_2, concentration_1, concentration_2))</code> . If DM is not specified for a given data stream, then <code>Par0</code> is on the natural (i.e., real) scale of the parameters. However, if DM is specified for a given data stream, then <code>Par0</code> must be on the working (i.e., beta) scale of the parameters, and the length of <code>Par0</code> must match the number of columns in the design matrix. See details below. |
| beta0 | Initial matrix of regression coefficients for the transition probabilities (more information in 'Details'). Default: NULL. If not specified, <code>beta0</code> is initialized such that the diagonal elements of the transition probability matrix are dominant. |

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| <code>delta0</code> | Initial value for the initial distribution of the HMM. Default: <code>rep(1/nbStates, nbStates)</code> . If <code>formulaDelta</code> includes a formula, then <code>delta0</code> must be specified as a $k \times (nbStates-1)$ matrix, where k is the number of covariates and the columns correspond to states $2:nbStates$. See details below. |
| <code>estAngleMean</code> | An optional named list indicating whether or not to estimate the angle mean for data streams with angular distributions ('vm' and 'wrpcauchy'). For example, <code>estAngleMean=list(angle=TRUE)</code> indicates the angle mean is to be estimated for 'angle'. Default is NULL, which assumes any angle means are fixed to zero and are not to be estimated. Any <code>estAngleMean</code> elements corresponding to data streams that do not have angular distributions are ignored. <code>estAngleMean</code> is also ignored for any 'vmConsensus' data streams (because the angle mean must be estimated in consensus models). |
| <code>circularAngleMean</code> | An optional named list indicating whether to use circular-linear (FALSE) or circular-circular (TRUE) regression on the mean of circular distributions ('vm' and 'wrpcauchy') for turning angles. For example, <code>circularAngleMean=list(angle=TRUE)</code> indicates the angle mean is to be estimated for 'angle' using circular-circular regression. Whenever circular-circular regression is used for an angular data stream, a corresponding design matrix (DM) must be specified for the data stream, and the previous movement direction (i.e., a turning angle of zero) is automatically used as the reference angle (i.e., the intercept). Any circular-circular regression covariates in data should therefore be relative to the previous direction of movement (instead of standard directions relative to the x-axis; see prepData and circAngles). See Duchesne et al. (2015) for specifics on the circular-circular regression model using previous movement direction as the reference angle. Default is NULL, which assumes circular-linear regression is used for any angular distributions for which the mean angle is to be estimated. <code>circularAngleMean</code> elements corresponding to angular data streams are ignored unless the corresponding element of <code>estAngleMean</code> is TRUE. Any <code>circularAngleMean</code> elements corresponding to data streams that do not have angular distributions are ignored. <code>circularAngleMean</code> is also ignored for any 'vmConsensus' data streams (because the consensus model is a circular-circular regression model). Alternatively, <code>circularAngleMean</code> can be specified as a numeric scalar, where the value specifies the coefficient for the reference angle (i.e., directional persistence) term in the circular-circular regression model. For example, setting <code>circularAngleMean</code> to 0 specifies a circular-circular regression model with no directional persistence term (thus specifying a biased random walk instead of a biased correlated random walk). Setting <code>circularAngleMean</code> to 1 is equivalent to setting it to TRUE, i.e., a circular-circular regression model with a coefficient of 1 for the directional persistence reference angle. |
| <code>formula</code> | Regression formula for the transition probability covariates. Default: <code>~1</code> (no covariate effect). In addition to allowing standard functions in R formulas (e.g., <code>cos(cov)</code> , <code>cov1*cov2</code> , <code>I(cov^2)</code>), special functions include <code>cosinor(cov, period)</code> for modeling cyclical patterns, spline functions (bs , ns , bSpline , cSpline , iSpline , and mSpline), and state- or parameter-specific formulas (see details). Any formula terms that are not state- or parameter-specific are included on all of the transition probabilities. |
| <code>formulaDelta</code> | Regression formula for the initial distribution. Default for <code>fitHMM.momentuHMMDData</code> : |

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| | <p>NULL (no covariate effects; both <code>delta0</code> and <code>fixPar\$delta</code> are specified on the real scale). Default for <code>fitHMM.momentuHierHMMData</code>: <code>~1</code> (both <code>delta0</code> and <code>fixPar\$delta</code> are specified on the working scale). Standard functions in R formulas are allowed (e.g., <code>cos(cov)</code>, <code>cov1*cov2</code>, <code>I(cov^2)</code>). When any formula is provided, then both <code>delta0</code> and <code>fixPar\$delta</code> are specified on the working scale.</p> |
| <code>stationary</code> | <p>FALSE if there are time-varying covariates in <code>formula</code> or any covariates in <code>formulaDelta</code>. If TRUE, the initial distribution is considered equal to the stationary distribution. Default: FALSE.</p> |
| <code>mixtures</code> | <p>Number of mixtures for the state transition probabilities (i.e. discrete random effects *sensu* DeRuiter et al. 2017). Default: <code>mixtures=1</code>.</p> |
| <code>formulaPi</code> | <p>Regression formula for the mixture distribution probabilities. Default: NULL (no covariate effects; both <code>beta0\$pi</code> and <code>fixPar\$pi</code> are specified on the real scale). Standard functions in R formulas are allowed (e.g., <code>cos(cov)</code>, <code>cov1*cov2</code>, <code>I(cov^2)</code>). When any formula is provided, then both <code>beta0\$pi</code> and <code>fixPar\$pi</code> are specified on the working scale. Note that only the covariate values from the first row for each individual ID in data are used (i.e. time-varying covariates cannot be used for the mixture probabilities).</p> |
| <code>nlmPar</code> | <p>List of parameters to pass to the optimization function <code>nlm</code> (which should be either <code>print.level</code>, <code>gradtol</code>, <code>stepmax</code>, <code>steptol</code>, <code>iterlim</code>, <code>fscale</code>, or <code>hessian</code> – see <code>nlm</code>'s documentation for more detail). For <code>print.level</code>, the default value of 0 means that no printing occurs, a value of 1 means that the first and last iterations of the optimization are detailed, and a value of 2 means that each iteration of the optimization is detailed. Ignored unless <code>optMethod="nlm"</code>.</p> |
| <code>fit</code> | <p>TRUE if an HMM should be fitted to the data, FALSE otherwise. If <code>fit=FALSE</code>, a model is returned with the MLE replaced by the initial parameters given in input. This option can be used to assess the initial parameters, parameter bounds, etc. Default: TRUE.</p> |
| <code>DM</code> | <p>An optional named list indicating the design matrices to be used for the probability distribution parameters of each data stream. Each element of <code>DM</code> can either be a named list of linear regression formulas or a “pseudo” design matrix. For example, for a 2-state model using the gamma distribution for a data stream named ‘step’, <code>DM=list(step=list(mean=~cov1, sd=~1))</code> specifies the mean parameters as a function of the covariate ‘cov1’ for each state. This model could equivalently be specified as a 4x6 “pseudo” design matrix using character strings for the covariate: <code>DM=list(step=matrix(c(1,0,0,0, 'cov1', 0,0,0,0,1,0,0,0, 'cov1', 0,0,0,0,1,0,0,0), 4, 6))</code> where the 4 rows correspond to the state-dependent parameters (<code>mean_1, mean_2, sd_1, sd_2</code>) and the 6 columns correspond to the regression coefficients.</p> <p>Design matrices specified using formulas allow standard functions in R formulas (e.g., <code>cos(cov)</code>, <code>cov1*cov2</code>, <code>I(cov^2)</code>). Special formula functions include <code>cosinor(cov, period)</code> for modeling cyclical patterns, spline functions (<code>bs</code>, <code>ns</code>, <code>bSpline</code>, <code>cSpline</code>, <code>iSpline</code>, and <code>mSpline</code>), <code>angleFormula(cov, strength, by)</code> for the angle mean of circular-circular regression models, and state-specific formulas (see details). Any formula terms that are not state-specific are included on the parameters for all <code>nbStates</code> states.</p> |
| <code>userBounds</code> | <p>An optional named list of 2-column matrices specifying bounds on the natural (i.e. real) scale of the probability distribution parameters for each data</p> |

stream. For each matrix, the first column pertains to the lower bound and the second column the upper bound. For example, for a 2-state model using the wrapped Cauchy ('wrpcauchy') distribution for a data stream named 'angle' with `estAngleMean$angle=TRUE`, `userBounds=list(angle=matrix(c(-pi,-pi,-1,-1,pi,pi,1,1)` specifies (-1,1) bounds for the concentration parameters instead of the default [0,1) bounds.

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| <code>workBounds</code> | An optional named list of 2-column matrices specifying bounds on the working scale of the probability distribution, transition probability, and initial distribution parameters. For each matrix, the first column pertains to the lower bound and the second column the upper bound. For data streams, each element of <code>workBounds</code> should be a $k \times 2$ matrix with the same name of the corresponding element of <code>Par0</code> , where k is the number of parameters. For transition probability parameters, the corresponding element of <code>workBounds</code> must be a $k \times 2$ matrix named "beta", where $k = \text{length}(\text{beta}\theta)$. For initial distribution parameters, the corresponding element of <code>workBounds</code> must be a $k \times 2$ matrix named "delta", where $k = \text{length}(\text{delta}\theta)$. <code>workBounds</code> is ignored for any given data stream unless <code>DM</code> is also specified. |
| <code>betaCons</code> | Matrix of the same dimension as <code>beta0</code> composed of integers identifying any equality constraints among the t.p.m. parameters. See details. |
| <code>betaRef</code> | Numeric vector of length <code>nbStates</code> indicating the reference elements for the t.p.m. multinomial logit link. Default: <code>NULL</code> , in which case the diagonal elements of the t.p.m. are the reference. See details. |
| <code>deltaCons</code> | Matrix of the same dimension as <code>delta0</code> composed of integers identifying any equality constraints among the initial distribution working scale parameters. Ignored unless a formula is provided in <code>formulaDelta</code> . See details. |
| <code>mvnCoords</code> | Character string indicating the name of location data that are to be modeled using a multivariate normal distribution. For example, if <code>mu="mvnorm2"</code> was included in <code>dist</code> and <code>(mu.x, mu.y)</code> are location data, then <code>mvnCoords="mu"</code> needs to be specified in order for these data to be properly treated as locations in functions such as <code>plot.momentuHMM</code> , <code>plot.miSum</code> , <code>plot.miHMM</code> , <code>plotSpatialCov</code> , and <code>MIpool</code> . |
| <code>stateNames</code> | Optional character vector of length <code>nbStates</code> indicating state names. |
| <code>knownStates</code> | Vector of values of the state process which are known prior to fitting the model (if any). Default: <code>NULL</code> (states are not known). This should be a vector with length the number of rows of 'data'; each element should either be an integer (the value of the known states) or <code>NA</code> if the state is not known. |
| <code>fixPar</code> | An optional list of vectors indicating parameters which are assumed known prior to fitting the model. Default: <code>NULL</code> (no parameters are fixed). For data streams, each element of <code>fixPar</code> should be a vector of the same name and length as the corresponding element of <code>Par0</code> . For transition probability parameters, the corresponding element of <code>fixPar</code> must be named "beta" and have the same dimensions as <code>beta0</code> . For initial distribution parameters, the corresponding element of <code>fixPar</code> must be named "delta" and have the same dimensions as <code>delta0</code> . Each parameter should either be numeric (the fixed value of the parameter) or <code>NA</code> if the parameter is to be estimated. Corresponding <code>fixPar</code> parameters must be on the same scale as <code>Par0</code> (e.g. if <code>DM</code> is specified for a given data stream, any |

fixed parameters for this data stream must be on the working scale), β_0 , and δ_0 .

If `optMethod='TMB'` then `fixPar` is specified differently. In this case, NA instead indicates parameters that are fixed (to the value specified by `Par0`, β_0 , or δ_0) and the parameters that are not fixed are sequentially indexed (similar to `betaCons`) by parameter number (such that parameters can be constrained to be equal). For example, `fixPar=list(angle=c(NA,NA,1,2))` indicates the first two parameters of the 'angle' distribution are fixed and the other two parameters are freely estimated. `fixPar=list(angle=c(1,NA,2,2,3))` indicates the first angle parameter is freely estimated, the second parameter is fixed, the third and fourth parameters are constrained to be equal, and the fifth parameter is freely estimated.

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| <code>retryFits</code> | Non-negative integer indicating the number of times to attempt to iteratively fit the model using random perturbations of the current parameter estimates as the initial values for likelihood optimization. $\text{Normal}(0, \text{retrySD}^2)$ perturbations are used on the working scale parameters. Default: 0. When <code>retryFits</code> >0, the model with the largest log likelihood value is returned. Ignored if <code>fit=FALSE</code> . |
| <code>retrySD</code> | An optional list of scalars or vectors indicating the standard deviation to use for normal perturbations of each working scale parameter when <code>retryFits</code> >0. For data streams, each element of <code>retrySD</code> should be a vector of the same name and length as the corresponding element of <code>Par0</code> (if a scalar is provided, then this value will be used for all working parameters of the data stream). For transition probability parameters, the corresponding element of <code>retrySD</code> must be named "beta" and have the same dimensions as β_0 . For initial distribution parameters, the corresponding element of <code>retrySD</code> must be named "delta" and have the same dimensions as δ_0 (if δ_0 is on the working scale) or be of length <code>nbStates-1</code> (if δ_0 is on the natural scale). Alternatively <code>retrySD</code> can be a scalar, in which case this value is used for all parameters. Instead of numeric scalars, <code>retrySD</code> can also be specified as "adapt" in which case the standard deviation is adapted as $10^{\lceil \log_{10}(\text{abs}(x)) \rceil}$ (where x is the current value of the corresponding working parameter). Default: NULL (in which case <code>retrySD=1</code> for data stream parameters and <code>retrySD=10</code> for initial distribution and state transition probabilities). Ignored unless <code>retryFits</code> >0. |
| <code>ncores</code> | Number of cores to use for parallel processing when <code>retryFits</code> >0. Default: 1 (no parallel processing). When <code>retryFits</code> attempts are performed in parallel, each attempt uses perturbations of the initial model fit (i.e. they are not iteratively updated as when <code>ncores=1</code>). |
| <code>optMethod</code> | The optimization method to be used. Can be "nlm" (the default; see <code>nlm</code>), "TMB" (using Template Model Builder; see <code>optimx</code> for control parameters), "Nelder-Mead" (see <code>optim</code>), or "SANN" (see <code>optim</code>). |
| <code>control</code> | A list of control parameters to be passed to <code>optim</code> (ignored unless <code>optMethod="TMB"</code> , <code>optMethod="Nelder-Mead"</code> , or <code>optMethod="SANN"</code>). |
| <code>prior</code> | Either a function that returns the log-density of the working scale parameter prior distribution(s) (if <code>optMethod!='TMB'</code>) or, if <code>optMethod='TMB'</code> , a named list with optional entries matching the names of the data streams (i.e. <code>names(dist)</code>) or "beta" (state transition parameters), where each entry is a 2-column matrix (first column = mean, second column = sd) specifying the mean and standard |

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| | deviation of the normal priors for each working parameter (any rows with NAs indicate no prior for the corresponding parameter). See 'Details'. |
| modelName | An optional character string providing a name for the fitted model. If provided, modelName will be returned in <code>print.momentuHMM</code> , <code>AIC.momentuHMM</code> , <code>AICweights</code> , and other functions. |
| hierStates | A hierarchical model structure <code>Node</code> for the states ('state'). See details. |
| hierDist | A hierarchical data structure <code>Node</code> for the data streams ('dist'). See details. |
| hierBeta | A hierarchical data structure <code>Node</code> for the matrix of initial values for the regression coefficients of the transition probabilities at each level of the hierarchy ('beta'). See details. |
| hierDelta | A hierarchical data structure <code>Node</code> for the matrix of initial values for the regression coefficients of the initial distribution at each level of the hierarchy ('delta'). See details. |
| hierFormula | A hierarchical formula structure for the transition probability covariates for each level of the hierarchy ('formula'). Default: NULL (only hierarchical-level effects, with no covariate effects). Any formula terms that are not state- or parameter-specific are included on all of the transition probabilities within a given level of the hierarchy. See details. |
| hierFormulaDelta | A hierarchical formula structure for the initial distribution covariates for each level of the hierarchy ('formulaDelta'). Default: NULL (no covariate effects and <code>fixPar\$delta</code> is specified on the working scale). |

Details

- By default the matrix `beta0` of regression coefficients for the transition probabilities has one row for the intercept, plus one row for each covariate, and one column for each non-diagonal element of the transition probability matrix. For example, in a 3-state HMM with 2 formula covariates, the matrix `beta` has three rows (intercept + two covariates) and six columns (six non-diagonal elements in the 3x3 transition probability matrix - filled in row-wise). In a covariate-free model (default), `beta0` has one row, for the intercept. While the diagonal elements are by default the reference elements, other elements can serve as the reference using the `betaRef` argument. For example, in a 3-state model, setting `betaRef=c(3,2,3)` changes the reference elements to state transition 1 -> 3 for state 1 (instead of 1 -> 1), state transition 2 -> 2 for state 2 (same as default), and state transition 3 -> 3 for state 3 (same as default).
- When covariates are not included in `formulaDelta` (i.e. `formulaDelta=NULL`), then `delta0` (and `fixPar$delta`) are specified as a vector of length `nbStates` that sums to 1. When any formula is specified for `formulaDelta` (e.g. `formulaDelta=~1`, `formulaDelta=~cov1`), then `delta0` (and `fixPar$delta`) must be specified as a `k x (nbStates-1)` matrix of working parameters, where `k` is the number of regression coefficients and the columns correspond to states 2:nbStates. For example, in a 3-state HMM with `formulaDelta=~cov1+cov2`, the matrix `delta0` has three rows (intercept + two covariates) and 2 columns (corresponding to states 2 and 3). The initial distribution working parameters are transformed to the real scale as $\exp(\text{covsDelta} * \text{Delta}) / \text{rowSums}(\exp(\text{covsDelta} * \text{Delta}))$, where `covsDelta` is the `N x k` design matrix, `Delta=cbind(rep(0,k),delta0)` is a `k x nbStates` matrix of working parameters, and `N=length(unique(data$ID))`.

- The choice of initial parameters (particularly Par_0 and beta_0) is crucial to fit a model. The algorithm might not find the global optimum of the likelihood function if the initial parameters are poorly chosen.
- If DM is specified for a particular data stream, then the initial values are specified on the working (i.e., beta) scale of the parameters. The working scale of each parameter is determined by the link function used. If a parameter P is bound by (0,Inf) then the working scale is the $\log(P)$ scale. If the parameter bounds are $(-\pi, \pi)$ then the working scale is $\tan(P/2)$ unless circular-circular regression is used. Otherwise if the parameter bounds are finite then $\text{logit}(P)$ is the working scale. However, when both zero- and one-inflation are included, then a multinomial logit link is used because the sum of the zeromass and onemass probability parameters cannot exceed 1. The function `getParDM` is intended to help with obtaining initial values on the working scale when specifying a design matrix and other parameter constraints (see example below). When circular-circular regression is specified using `circularAngleMean`, the working scale for the mean turning angle is not as easily interpretable, but the link function is $\text{atan2}(\sin(X)*B, 1+\cos(X)*B)$, where X are the angle covariates and B the angle coefficients (see Duchesne et al. 2015). Under this formulation, the reference turning angle is 0 (i.e., movement in the same direction as the previous time step). In other words, the mean turning angle is zero when the coefficient(s) $B=0$.

- Circular-circular regression in `momentuHMM` is designed for turning angles (not bearings) as computed by `simData` and `prepData`. Any circular-circular regression angle covariates for time step t should therefore be relative to the previous direction of movement for time step t-1. In other words, circular-circular regression covariates for time step t should be the turning angle between the direction of movement for time step t-1 and the standard direction of the covariate relative to the x-axis for time step t. If provided standard directions in radians relative to the x-axis (where 0 = east, $\pi/2$ = north, π = west, and $-\pi/2$ = south), `circAngles` or `prepData` can perform this calculation for you.

When the circular-circular regression model is used, the special function `angleFormula(cov, strength, by)` can be used in DM for the mean of angular distributions (i.e. 'vm', 'vmConsensus', and 'wrpcauchy'), where cov is an angle covariate (e.g. wind direction), strength is an optional positive real covariate (e.g. wind speed), and by is an optional factor variable for individual- or group-level effects (e.g. ID, sex). The strength argument allows angle covariates to be weighted based on their relative strength or importance at time step t as in Rivest et al. (2016). In this case, the link function for the mean angle is $\text{atan2}((Z * \sin(X)) \%*\% B, 1+(Z * \cos(X)) \%*\% B)$, where X are the angle covariates, Z the strength covariates, and B the angle coefficients (see Rivest et al. 2016).

- State-specific formulas can be specified in DM using special formula functions. These special functions can take the names `paste0("state", 1:nbStates)` (where the integer indicates the state-specific formula). For example, `DM=list(step=list(mean=~cov1+state1(cov2), sd=~cov2+state2(cov1)))` includes cov1 on the mean parameter for all states, cov2 on the mean parameter for state 1, cov2 on the sd parameter for all states, and cov1 on the sd parameter for state 2.
- State- and parameter-specific formulas can be specified for transition probabilities in formula using special formula functions. These special functions can take the names `paste0("state", 1:nbStates)` (where the integer indicates the current state from which transitions occur), `paste0("toState", 1:nbStates)` (where the integer indicates the state to which transitions occur), or `paste0("betaCol", nbStates*(nbStates-1))` (where the integer indicates the column of the beta matrix). For example with `nbStates=3`, `formula=~cov1+betaCol1(cov2)+state3(cov3)+toState1(cov4)` includes cov1 on all transition probability parameters, cov2 on the beta column corresponding to the transition from

state 1->2, cov3 on transition probabilities from state 3 (i.e., beta columns corresponding to state transitions 3->1 and 3->2), and cov4 on transition probabilities to state 1 (i.e., beta columns corresponding to state transitions 2->1 and 3->1).

- betaCons can be used to impose equality constraints among the t.p.m. parameters. It must be a matrix of the same dimension as beta0 and be composed of integers, where each beta parameter is sequentially indexed in a column-wise fashion (see [checkPar0](#)). Parameter indices in betaCons must therefore be integers between 1 and nbStates*(nbStates-1).

Use of betaCons is perhaps best demonstrated by example. If no constraints are imposed (the default), then `betaCons=matrix(1:length(beta0),nrow(beta0),ncol(beta0))` such that each beta parameter is (column-wise) sequentially identified by a unique integer. Suppose we wish to fit a model with `nbStates=3` states and a covariate ('cov1') on the t.p.m. With no constraints on the t.p.m., we would have `betaCons=matrix(1:(2*(nbStates*(nbStates-1))),nrow=2,ncol=nbStates->2","1->3","2->1","2->3","3->1","3->2"))`. If we then wanted to constrain the t.p.m. such that the covariate effect is identical for transitions from state 1 to states 2 and 3 (and vice versa), we have `betaCons=matrix(c(1,2,3,2,5,6,7,8,9,6,11,12),nrow=2,ncol=nbStates*(nbStates->2)","1->3","2->1","2->3","3->1","3->2"))`; this results in 10 estimated beta parameters (instead of 12), the "cov1" effects indexed by a "2" ("1->2" and "1->3") constrained to be equal, and the "cov1" effects indexed by a "6" ("2->1" and "3->1") constrained to be equal.

Now suppose we instead wish to constrain these sets of state transition probabilities to be equal, i.e., $\Pr(1 \rightarrow 2) = \Pr(1 \rightarrow 3)$ and $\Pr(2 \rightarrow 1) = \Pr(3 \rightarrow 1)$; then we have `betaCons=matrix(c(1,2,1,2,5,6,7,8,5,6->2","1->3","2->1","2->3","3->1","3->2"))`

- Cyclical relationships (e.g., hourly, monthly) may be modeled in DM or formula using the `cosinor(x,period)` special formula function for covariate x and sine curve period of time length period. For example, if the data are hourly, a 24-hour cycle can be modeled using `~cosinor(cov1,24)`, where the covariate cov1 is a repeating sequential series of integers indicating the hour of day (0,1,...,23,0,1,...,23,0,1,...) (note that fitHMM will not do this for you, the appropriate covariate must be included in data; see example below). The `cosinor(x,period)` function converts x to 2 covariates `cosinorCos(x)=cos(2*pi*x/period)` and `cosinorSin(x)=sin(2*pi*x/period)` for inclusion in the model (i.e., 2 additional parameters per state). The amplitude of the sine wave is thus `sqrt(B_cos^2 + B_sin^2)`, where `B_cos` and `B_sin` are the working parameters corresponding to `cosinorCos(x)` and `cosinorSin(x)`, respectively (e.g., see Cornelissen 2014).
- Similar to that used in [crawlWrap](#), the prior argument is a user-specified function that returns the log-density of the working scale parameter prior distribution(s). In addition to including prior information about parameters, one area where priors can be particularly useful is for handling numerical issues that can arise when parameters are near a boundary. When parameters are near boundaries, they can wander into the "nether regions" of the parameter space during optimization. For example, setting `prior=function(par) {sum(dnorm(par,0,sd,log=TRUE))}` with a reasonably large sd (e.g. 100 or 1000) can help prevent working parameters from straying too far along the real line. Here par is the vector of working scale parameters (as returned by fitHMM, e.g., see `examplemmod$estimate`) in the following order: data stream working parameters (in order `names(dist)`), beta working parameters, and delta working parameters. Instead of specifying the same prior on all parameters, different priors could be specified on different parameters (and not all parameters must have user-specified priors). For example, `prior=function(par){dnorm(par[3],0,100,log=TRUE)}` would only specify a prior for the third working parameter. Note that the prior function must return a scalar on the log

scale. See 'harbourSealExample.R' in the "vignettes" source directory for an example using the prior argument.

- `fitHMM.momentuHierHMMDData` is very similar to `fitHMM.momentuHMMDData` except that instead of simply specifying the number of states (`nbStates`), distributions (`dist`), and a single t.p.m. formula (`formula`), the `hierStates` argument specifies the hierarchical nature of the states, the `hierDist` argument specifies the hierarchical nature of the data streams, and the `hierFormula` argument specifies a t.p.m. formula for each level of the hierarchy. All are specified as `Node` objects from the `data.tree` package.

Value

A `momentuHMM` or `momentuHierHMM` object, i.e. a list of:

| | |
|--------------------------|---|
| <code>mle</code> | A named list of the maximum likelihood estimates of the parameters of the model (if the numerical algorithm has indeed identified the global maximum of the likelihood function). Elements are included for the parameters of each data stream, as well as <code>beta</code> (transition probabilities regression coefficients - more information in 'Details'), <code>gamma</code> (transition probabilities on real scale, based on mean covariate values if formula includes covariates), and <code>delta</code> (initial distribution). |
| <code>CIreal</code> | Standard errors and 95% confidence intervals on the real (i.e., natural) scale of parameters |
| <code>CIbeta</code> | Standard errors and 95% confidence intervals on the beta (i.e., working) scale of parameters |
| <code>data</code> | The <code>momentuHMMDData</code> or <code>momentuHierHMMDData</code> object |
| <code>mod</code> | List object returned by the numerical optimizer <code>nlm</code> or <code>optim</code> . Items in <code>mod</code> include the best set of free working parameters found (<code>wpar</code>), the best full set of working parameters including any fixed parameters (<code>estimate</code>), the value of the likelihood at <code>estimate</code> (<code>minimum</code>), the estimated variance-covariance matrix at <code>estimate</code> (<code>Sigma</code>), and the elapsed time in seconds for the optimization (<code>elapsedTime</code>). |
| <code>conditions</code> | Conditions used to fit the model, e.g., <code>bounds</code> (parameter bounds), <code>distributions</code> , <code>zeroInflation</code> , <code>estAngleMean</code> , <code>stationary</code> , <code>formula</code> , <code>DM</code> , <code>fullDM</code> (full design matrix), etc. |
| <code>rawCovs</code> | Raw covariate values for transition probabilities, as found in the data (if any). Used in <code>plot.momentuHMM</code> . |
| <code>stateNames</code> | The names of the states. |
| <code>knownStates</code> | Vector of values of the state process which are known. |
| <code>covsDelta</code> | Design matrix for initial distribution. |

References

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See Also

[getParDM](#), [prepData](#), [simData](#)
[simHierData](#)

Examples

```
nbStates <- 2
stepDist <- "gamma" # step distribution
angleDist <- "vm" # turning angle distribution

# extract data from momentuHMM example
data <- example$m$data

### 1. fit the model to the simulated data
# define initial values for the parameters
mu0 <- c(20,70)
sigma0 <- c(10,30)
kappa0 <- c(1,1)
stepPar <- c(mu0,sigma0) # no zero-inflation, so no zero-mass included
anglePar <- kappa0 # not estimating angle mean, so not included
formula <- ~cov1+cos(cov2)
```

```

m <- fithMM(data=data,nbStates=nbStates,dist=list(step=stepDist,angle=angleDist),
            Par0=list(step=stepPar,angle=anglePar),formula=formula)

print(m)

## Not run:
### 2. fit the exact same model to the simulated data using DM formulas
# Get initial values for the parameters on working scale
Par0 <- getParDM(data=data,nbStates=nbStates,dist=list(step=stepDist,angle=angleDist),
                Par=list(step=stepPar,angle=anglePar),
                DM=list(step=list(mean=~1,sd=~1),angle=list(concentration=~1)))

mDMf <- fithMM(data=data,nbStates=nbStates,dist=list(step=stepDist,angle=angleDist),
               Par0=Par0,formula=formula,
               DM=list(step=list(mean=~1,sd=~1),angle=list(concentration=~1)))

print(mDMf)

### 3. fit the exact same model to the simulated data using DM matrices
# define DM
DMm <- list(step=diag(4),angle=diag(2))

# user-specified dimnames not required but are recommended
dimnames(DMm$step) <- list(c("mean_1","mean_2","sd_1","sd_2"),
                          c("mean_1:(Intercept)","mean_2:(Intercept)",
                            "sd_1:(Intercept)","sd_2:(Intercept)"))
dimnames(DMm$angle) <- list(c("concentration_1","concentration_2"),
                            c("concentration_1:(Intercept)","concentration_2:(Intercept)"))

mDMm <- fithMM(data=data,nbStates=nbStates,dist=list(step=stepDist,angle=angleDist),
               Par0=Par0,formula=formula,
               DM=DMm)

print(mDMm)

### 4. fit step mean parameter covariate model to the simulated data using DM
stepDMf <- list(mean=~cov1,sd=~1)
Par0 <- getParDM(data,nbStates,list(step=stepDist,angle=angleDist),
                 Par=list(step=stepPar,angle=anglePar),
                 DM=list(step=stepDMf,angle=DMm$angle))
mDMfcov <- fithMM(data=data,nbStates=nbStates,dist=list(step=stepDist,angle=angleDist),
                  Par0=Par0,
                  formula=formula,
                  DM=list(step=stepDMf,angle=DMm$angle))

print(mDMfcov)

### 5. fit the exact same step mean parameter covariate model using DM matrix
stepDMm <- matrix(c(1,0,0,0,"cov1",0,0,0,0,1,0,0,0,"cov1",0,0,
                    0,0,1,0,0,0,0,1),4,6,dimnames=list(c("mean_1","mean_2","sd_1","sd_2"),
                                                       c("mean_1:(Intercept)","mean_1:cov1","mean_2:(Intercept)","mean_2:cov1",
                                                         "sd_1:(Intercept)","sd_2:(Intercept)")))
Par0 <- getParDM(data,nbStates,list(step=stepDist,angle=angleDist),

```

```

        Par=list(step=stepPar,angle=anglePar),
        DM=list(step=stepDMm,angle=DMm$angle))
mDMmcov <- fitHMM(data=data,nbStates=nbStates,dist=list(step=stepDist,angle=angleDist),
        Par0=Par0,
        formula=formula,
        DM=list(step=stepDMm,angle=DMm$angle))

print(mDMmcov)

### 6. fit circular-circular angle mean covariate model to the simulated data using DM

# Generate fake circular covariate using circAngles
data$cov3 <- circAngles(refAngle=2*atan(rnorm(nrow(data))),data)

# Fit circular-circular regression model for angle mean
# Note no intercepts are estimated for angle means because these are by default
# the previous movement direction (i.e., a turning angle of zero)
mDMcircf <- fitHMM(data=data,nbStates=nbStates,dist=list(step=stepDist,angle=angleDist),
        Par0=list(step=stepPar,angle=c(0,0,Par0$angle)),
        formula=formula,
        estAngleMean=list(angle=TRUE),
        circularAngleMean=list(angle=TRUE),
        DM=list(angle=list(mean=~cov3,concentration=~1)))

print(mDMcircf)

### 7. fit the exact same circular-circular angle mean model using DM matrices

# Note no intercept terms are included in DM for angle means because the intercept is
# by default the previous movement direction (i.e., a turning angle of zero)
mDMcircm <- fitHMM(data=data,nbStates=nbStates,dist=list(step=stepDist,angle=angleDist),
        Par0=list(step=stepPar,angle=c(0,0,Par0$angle)),
        formula=formula,
        estAngleMean=list(angle=TRUE),
        circularAngleMean=list(angle=TRUE),
        DM=list(angle=matrix(c("cov3",0,0,0,0,"cov3",0,0,0,0,1,0,0,0,0,1),4,4)))

print(mDMcircm)

### 8. Cosinor and state-dependent formulas
nbStates<-2
dist<-list(step="gamma")
Par<-list(step=c(100,1000,50,100))

# include 24-hour cycle on all transition probabilities
# include 12-hour cycle on transitions from state 2
formula=~cosinor(hour24,24)+state2(cosinor(hour12,12))

# specify appropriate covariates
covs<-data.frame(hour24=0:23,hour12=0:11)

beta<-matrix(c(-1.5,1,1,NA,NA,-1.5,-1,-1,1,1),5,2)
# row names for beta not required but can be helpful

```

```

rownames(beta)<-c("(Intercept)",
                 "cosinorCos(hour24, 24)",
                 "cosinorSin(hour24, 24)",
                 "cosinorCos(hour12, 12)",
                 "cosinorSin(hour12, 12)")
data.cos<-simData(nbStates=nbStates,dist=dist,Par=Par,
                 beta=beta,formula=formula,covs=covs)

m.cosinor<-fitHMM(data.cos,nbStates=nbStates,dist=dist,Par0=Par,formula=formula)
m.cosinor

### 9. Piecewise constant B-spline on step length mean and angle concentration
nObs <- 1000 # length of simulated track
cov <- data.frame(time=1:nObs) # time covariate for splines
dist <- list(step="gamma",angle="vm")
stepDM <- list(mean=~splines2::bSpline(time,df=2,degree=0),sd=~1)
angleDM <- list(mean=~1,concentration=~splines2::bSpline(time,df=2,degree=0))
DM <- list(step=stepDM,angle=angleDM)
Par <- list(step=c(log(1000),1,-1,log(100)),angle=c(0,log(10),2,-5))

data.spline<-simData(obsPerAnimal=nObs,nbStates=1,dist=dist,Par=Par,DM=DM,covs=cov)

Par0 <- list(step=Par$step,angle=Par$angle[-1])
m.spline<-fitHMM(data.spline,nbStates=1,dist=dist,Par0=Par0,
                 DM=list(step=stepDM,
                         angle=angleDM["concentration"]))

### 10. Initial state (delta) based on covariate
nObs <- 100
dist <- list(step="gamma",angle="vm")
Par <- list(step=c(100,1000,50,100),angle=c(0,0,0.01,0.75))

# create sex covariate
cov <- data.frame(sex=factor(rep(c("F","M"),each=nObs))) # sex covariate
formulaDelta <- ~ sex + 0

# Female begins in state 1, male begins in state 2
delta <- matrix(c(-100,100),2,1,dimnames=list(c("sexF","sexM"),"state 2"))

data.delta<-simData(nbAnimals=2,obsPerAnimal=nObs,nbStates=2,dist=dist,Par=Par,
                  delta=delta,formulaDelta=formulaDelta,covs=cov)

Par0 <- list(step=Par$step, angle=Par$angle[3:4])
m.delta <- fitHMM(data.delta, nbStates=2, dist=dist, Par0 = Par0,
                 formulaDelta=formulaDelta)

### 11. Two mixtures based on covariate
nObs <- 100
nbAnimals <- 20
dist <- list(step="gamma",angle="vm")
Par <- list(step=c(100,1000,50,100),angle=c(0,0,0.1,2))

# create sex covariate

```

```

cov <- data.frame(sex=factor(rep(c("F","M"),each=nObs*nbAnimals/2)))
formulaPi <- ~ sex + 0

# Females more likely in mixture 1, males more likely in mixture 2
beta <- list(beta=matrix(c(-1.5,-0.5,-1.5,-3),2,2),
             pi=matrix(c(-2,2),2,1,dimnames=list(c("sexF","sexM"),"mix2")))

data.mix<-simData(nbAnimals=nbAnimals,obsPerAnimal=nObs,nbStates=2,dist=dist,Par=Par,
                 beta=beta,formulaPi=formulaPi,mixtures=2,covs=cov)

Par0 <- list(step=Par$step, angle=Par$angle[3:4])
m.mix <- fitHMM(data.mix, nbStates=2, dist=dist, Par0 = Par0,
               beta0=beta,formulaPi=formulaPi,mixtures=2)

## End(Not run)

```

formatHierHMM

Convert hierarchical HMM structure to a conventional HMM

Description

Convert hierarchical HMM structure to a conventional HMM

Usage

```

formatHierHMM(
  data,
  hierStates,
  hierDist,
  hierBeta = NULL,
  hierDelta = NULL,
  hierFormula = NULL,
  hierFormulaDelta = NULL,
  mixtures = 1,
  workBounds = NULL,
  betaCons = NULL,
  deltaCons = NULL,
  fixPar = NULL,
  checkData = TRUE,
  ...
)

```

Arguments

data [momentuHierHMMDData](#) object or a data frame containing the data streams and covariates.

hierStates A hierarchical data structure [Node](#) for the states ('state'). See [fitHMM](#).

| | |
|------------------|---|
| hierDist | A hierarchical data structure Node for the data streams ('dist'). See fitHMM . |
| hierBeta | A hierarchical data structure Node for the matrix of initial values for the regression coefficients of the transition probabilities at each level of the hierarchy ('beta'). See fitHMM . |
| hierDelta | A hierarchical data structure Node for the matrix of initial values for the regression coefficients of the initial distribution at each level of the hierarchy ('delta'). See fitHMM . |
| hierFormula | A hierarchical formula structure for the transition probability covariates for each level of the hierarchy ('formula'). See fitHMM . Default: NULL (only hierarchical-level effects, with no covariate effects). |
| hierFormulaDelta | A hierarchical formula structure for the initial distribution covariates for each level of the hierarchy ('formulaDelta'). See fitHMM . Default: NULL (no covariate effects and <code>fixPar\$delta</code> is specified on the working scale). |
| mixtures | Number of mixtures for the state transition probabilities (i.e. discrete random effects <i>sensu</i> DeRuiter et al. 2017). See fitHMM . Default: mixtures=1. |
| workBounds | A list with elements named 'beta' and/or 'delta', where each element is a hierarchical data structure Node indicating t.p.m. and initial distribution working parameter bounds ('workBounds') for parameters in hierBeta and hierDelta, respectively. |
| betaCons | A hierarchical data structure Node indicating t.p.m. constraints ('betaCons') among parameters in hierBeta at each level of the hierarchy. |
| deltaCons | A hierarchical data structure Node indicating initial distribution constraints ('deltaCons') among parameters in hierDelta at each level of the hierarchy. |
| fixPar | A list with elements named 'beta' and/or 'delta', where each element is a hierarchical data structure Node indicating t.p.m. and initial distribution parameters in hierBeta and hierDelta, respectively, which are assumed known. |
| checkData | logical indicating whether or not to check the suitability of data for the specified hierarchy. Ignored unless data is provided. Default: TRUE. |
| ... | further arguments passed to or from other methods |

Value

A list of arguments needed for specifying a hierarchical HMM as a conventional HMM in [fitHMM](#) or [MIfitHMM](#), including:

| | |
|--------------|------------------------------|
| nbStates | See fitHMM . |
| dist | See fitHMM . |
| formula | See fitHMM . |
| formulaDelta | See fitHMM . |
| beta0 | See fitHMM . |
| delta0 | See fitHMM . |
| betaRef | See fitHMM . |
| betaCons | See fitHMM . |

| | |
|------------|------------------------------|
| deltaCons | See fitHMM . |
| fixPar | See fitHMM . |
| workBounds | See fitHMM . |
| stateNames | See fitHMM . |

| | |
|-------------|--|
| getCovNames | <i>Get names of any covariates used in probability distribution parameters</i> |
|-------------|--|

Description

Get names of any covariates used in probability distribution parameters

Usage

```
getCovNames(m, p, distname)
```

Arguments

| | |
|----------|---|
| m | momentuHMM object |
| p | list returned by parDef |
| distname | Name of the data stream |

Value

A list of:

| | |
|-----------|---|
| DMterms | Names of all covariates included in the design matrix for the data stream |
| DMpartems | A list of the names of all covariates for each of the probability distribution parameters |

| | |
|------------|--------------------------|
| getDM_rcpp | <i>Get design matrix</i> |
|------------|--------------------------|

Description

Loop for creating full design matrix (X) from pseudo-design matrix (DM). Written in C++. Used in `getDM`.

Usage

```
getDM_rcpp(X, covs, DM, nr, nc, cov, nbObs)
```

Arguments

| | |
|-------|-----------------------------------|
| X | full design matrix |
| covs | matrix of covariates |
| DM | pseudo design matrix |
| nr | number of rows in design matrix |
| nc | number of column in design matrix |
| cov | covariate names |
| nbObs | number of observations |

Value

full design matrix (X)

| | |
|--------------|--|
| getGradients | <i>Calculate gradient of spatial covariates using bilinear interpolation</i> |
|--------------|--|

Description

Calculate gradient of spatial covariates using bilinear interpolation

Usage

```
getGradients(data, spatialCovs, collapseRast, coordNames = c("x", "y"))
```

Arguments

| | |
|--------------|---|
| data | Data frame of data streams. At a minimum, it must contain fields matching coordNames |
| spatialCovs | List of raster layer objects for spatially referenced covariates. Covariates specified by spatialCovs are extracted from the raster layer(s) based on the location data for each time step. |
| collapseRast | List of collapsed raster layer objects (see collapseRaster). Ignored unless spatialCovs is missing. |
| coordNames | Names of the coordinates in data. Default: c("x", "y"). |

Value

The gradients are appended to data with “.x” (easting gradient) and “.y” (northing gradient) suffixes added to the names of spatialCovs. For example, if cov1 is the name of a spatial covariate, then the returned data object will include the fields “cov1.x” and “cov1.y”.

| | |
|--------|--|
| getPar | <i>Get starting values from momentuHMM, miHMM, or miSum object returned by fitHMM, MIfitHMM, or MIpool</i> |
|--------|--|

Description

Get starting values from momentuHMM, miHMM, or miSum object returned by fitHMM, MIfitHMM, or MIpool

Usage

```
getPar(m)
```

Arguments

`m` A `momentuHMM`, `miHMM`, or `miSum` object.

Value

A list of parameter values (Par, beta, delta) that can be used as starting values in `fitHMM` or `MIfitHMM`

See Also

`getPar0`, `getParDM`

Examples

```
# m is a momentuHMM object (as returned by fitHMM), automatically loaded with the package
m <- example$m
Par <- getPar(m)
```

| | |
|---------|---|
| getPar0 | <i>Get starting values for new model from existing momentuHMM or momentuHierHMM model fit</i> |
|---------|---|

Description

For nested models, this function will extract starting parameter values (i.e., `Par0` in `fitHMM` or `MIfitHMM`) from an existing `momentuHMM` or `momentuHierHMM` model fit based on the provided arguments for the new model. Any parameters that are not in common between model and the new model (as specified by the arguments) are set to 0. This function is intended to help users incrementally build and fit more complicated models from simpler nested models (and vice versa).

Usage

```

getPar0(model, ...)

## Default S3 method:
getPar0(
  model,
  nbStates = length(model$stateNames),
  estAngleMean = model$conditions$estAngleMean,
  circularAngleMean = model$conditions$circularAngleMean,
  formula = model$conditions$formula,
  formulaDelta = model$conditions$formulaDelta,
  stationary = model$conditions$stationary,
  mixtures = model$conditions$mixtures,
  formulaPi = model$conditions$formulaPi,
  DM = model$conditions$DM,
  betaRef = model$conditions$betaRef,
  stateNames = model$stateNames,
  ...
)

## S3 method for class 'hierarchical'
getPar0(
  model,
  hierStates = model$conditions$hierStates,
  estAngleMean = model$conditions$estAngleMean,
  circularAngleMean = model$conditions$circularAngleMean,
  hierFormula = model$conditions$hierFormula,
  hierFormulaDelta = model$conditions$hierFormulaDelta,
  mixtures = model$conditions$mixtures,
  formulaPi = model$conditions$formulaPi,
  DM = model$conditions$DM,
  ...
)

```

Arguments

| | |
|-------------------|--|
| model | A momentuHMM , momentuHierHMM , miHMM , or miSum object (as returned by fitHMM , MIfitHMM , or MIpool) |
| ... | further arguments passed to or from other methods |
| nbStates | Number of states in the new model. Default: <code>nbStates=length(model\$stateNames)</code> |
| estAngleMean | Named list indicating whether or not the angle mean for data streams with angular distributions ('vm' and 'wrpcauchy') are to be estimated in the new model. Default: <code>estAngleMean=model\$conditions\$estAngleMean</code> |
| circularAngleMean | Named list indicating whether circular-linear or circular-circular regression on the mean of circular distributions ('vm' and 'wrpcauchy') for turning angles are to be used in the new model. See fitHMM . Default: <code>circularAngleMean=model\$conditions\$circularA</code> |

| | |
|------------------|---|
| formula | Regression formula for the transition probability covariates of the new model (see fitHMM). Default: formula=model\$conditions\$formula. |
| formulaDelta | Regression formula for the initial distribution covariates of the new model (see fitHMM). Default: formulaDelta=model\$conditions\$formulaDelta. |
| stationary | FALSE if there are time-varying covariates in formula or any covariates in formulaDelta. If TRUE, the initial distribution is considered equal to the stationary distribution. Default: FALSE. |
| mixtures | Number of mixtures for the state transition probabilities (see fitHMM). Default: formula=model\$conditions\$mixtures. |
| formulaPi | Regression formula for the mixture distribution probabilities (see fitHMM). Default: formula=model\$conditions\$formulaPi. |
| DM | Named list indicating the design matrices to be used for the probability distribution parameters of each data stream in the new model (see fitHMM). Only parameters with design matrix column names that match those in model\$conditions\$fullDM are extracted, so care must be taken in naming columns if any elements of DM are specified as matrices instead of formulas. Default: DM=model\$conditions\$DM. |
| betaRef | Numeric vector of length nbStates indicating the reference elements for the t.p.m. multinomial logit link. Default: formula=model\$conditions\$betaRef. |
| stateNames | Character vector of length nbStates indicating the names and order of the states in the new model. Default: stateNames=model\$stateNames[1:nbStates]. |
| hierStates | A hierarchical model structure Node for the states (see fitHMM). Default: hierStates=model\$conditions\$ |
| hierFormula | A hierarchical formula structure for the transition probability covariates for each level of the hierarchy (see fitHMM). Default: hierFormula=model\$conditions\$hierFormula. |
| hierFormulaDelta | A hierarchical formula structure for the initial distribution covariates for each level of the hierarchy ('formulaDelta'). Default: NULL (no covariate effects and fixPar\$delta is specified on the working scale). |

Details

All other [fitHMM](#) (or [MIfitHMM](#)) model specifications (e.g., `dist`, `hierDist`, `userBounds`, `workBounds`, etc.) and data are assumed to be the same for `model` and the new model (as specified by `nbStates`, `hierStates`, `estAngleMean`, `circularAngleMean`, `formula`, `hierFormula`, `formulaDelta`, `hierFormulaDelta`, `DM`, etc.).

Note that for hierarchical models, `getPar0` will return hierarchical `data.tree` objects (`hierBeta` and `hierDelta`) with the default values for `fixPar`, `betaCons`, and `deltaCons`; if hierarchical t.p.m. or initial distribution parameters are subject to constraints, then these must be set manually on the list object returned by `getPar0`.

Value

A named list containing starting values suitable for `Par0` and `beta0` arguments in [fitHMM](#) or [MIfitHMM](#):

| | |
|------|---|
| Par | A list of vectors of state-dependent probability distribution parameters for each data stream specified in <code>model\$conditions\$dist</code> |
| beta | Matrix of regression coefficients for the transition probabilities |


```

                                rep(c(":(Intercept)", ":(cov1)", 2*nbStates))
Par0 <- getPar0(model, DM=newDM2)

## Not run:
newModel2 <- fitHMM(model$data, dist=dist, nbStates=nbStates,
                    Par0=Par0$Par, beta0=Par0$beta,
                    formula=model$conditions$formula,
                    estAngleMean=estAngleMean,
                    DM=newDM2)

## End(Not run)

```

| | |
|----------|--|
| getParDM | <i>Get starting values on working scale based on design matrix and other parameter constraints</i> |
|----------|--|

Description

Convert starting values on the natural scale of data stream probability distributions to a feasible set of working scale parameters based on a design matrix and other parameter constraints.

Usage

```

getParDM(data, ...)

## Default S3 method:
getParDM(
  data = data.frame(),
  nbStates,
  dist,
  Par,
  zeroInflation = NULL,
  oneInflation = NULL,
  estAngleMean = NULL,
  circularAngleMean = NULL,
  DM = NULL,
  userBounds = NULL,
  workBounds = NULL,
  optMethod = "nlm",
  ...
)

## S3 method for class 'hierarchical'
getParDM(
  data = data.frame(),
  hierStates,
  hierDist,

```

```

Par,
zeroInflation = NULL,
oneInflation = NULL,
estAngleMean = NULL,
circularAngleMean = NULL,
DM = NULL,
userBounds = NULL,
workBounds = NULL,
...
)

```

Arguments

| | |
|---------------|---|
| data | Optional momentuHMMDData object, momentuHierHMMDData object, or a data frame containing the covariate values. data must be specified if covariates are included in DM. If a data frame is provided, then either nbStates and dist must be specified (for a regular HMM) or hierStates and hierDist must be specified (for a hierarchical HMM). |
| ... | further arguments passed to or from other methods |
| nbStates | Number of states of the HMM. |
| dist | A named list indicating the probability distributions of the data streams. Currently supported distributions are 'bern', 'beta', 'exp', 'gamma', 'lnorm', 'norm', 'mvnorm2' (bivariate normal distribution), 'mvnorm3' (trivariate normal distribution), 'pois', 'rw_norm' (normal random walk), 'rw_mvnorm2' (bivariate normal random walk), 'rw_mvnorm3' (trivariate normal random walk), 'vm', 'vm-Consensus', 'weibull', and 'wrpcauchy'. For example, <code>dist=list(step='gamma', angle='vm', dives='pois')</code> indicates 3 data streams ('step', 'angle', and 'dives') and their respective probability distributions ('gamma', 'vm', and 'pois'). |
| Par | A named list containing vectors of state-dependent probability distribution parameters for each data stream specified in dist. The parameters should be on the natural scale, in the order expected by the pdfs of dist, and any zero-mass parameters should be the last. |
| zeroInflation | A named list of logicals indicating whether the probability distributions of the data streams should be zero-inflated. If zeroInflation is TRUE for a given data stream, then values for the zero-mass parameters should be included in the corresponding element of Par. Ignored if data is a momentuHMMDData or momentuHierHMMDData object. |
| oneInflation | Named list of logicals indicating whether the probability distributions of the data streams are one-inflated. If oneInflation is TRUE for a given data stream, then values for the one-mass parameters should be included in the corresponding element of Par. Ignored if data is a momentuHMMDData or momentuHierHMMDData object. |
| estAngleMean | An optional named list indicating whether or not to estimate the angle mean for data streams with angular distributions ('vm' and 'wrpcauchy'). Any estAngleMean elements corresponding to data streams that do not have angular distributions are ignored. |

| | |
|-------------------|---|
| circularAngleMean | An optional named list indicating whether to use circular-linear or circular-circular regression on the mean of circular distributions ('vm' and 'wrpcauchy') for turning angles. See fitHMM . circularAngleMean elements corresponding to angular data streams are ignored unless the corresponding element of estAngleMean is TRUE. Any circularAngleMean elements corresponding to data streams that do not have angular distributions are ignored. |
| DM | A named list indicating the design matrices to be used for the probability distribution parameters of each data stream. Each element of DM can either be a named list of linear regression formulas or a matrix. For example, for a 2-state model using the gamma distribution for a data stream named 'step', <code>DM=list(step=list(mean=~cov1, sd=~1))</code> specifies the mean parameters as a function of the covariate 'cov1' for each state. This model could equivalently be specified as a 4x6 matrix using character strings for the covariate: <code>DM=list(step=matrix(c(1,0,0,0, 'cov1', 0,0,0,0,1,0,0,0, 'cov1', 0,0,0,0,1,0,0,0,0,1), 4, 6))</code> where the 4 rows correspond to the state-dependent parameters (mean_1, mean_2, sd_1, sd_2) and the 6 columns correspond to the regression coefficients. |
| userBounds | An optional named list of 2-column matrices specifying bounds on the natural (i.e. real) scale of the probability distribution parameters for each data stream. For example, for a 2-state model using the wrapped Cauchy ('wrpcauchy') distribution for a data stream named 'angle' with <code>estAngleMean\$angle=TRUE</code> , <code>userBounds=list(angle=matrix(c(-pi, -pi, -1, -1, pi, pi, 1, 1), 4, 2))</code> specifies (-1,1) bounds for the concentration parameters instead of the default [0,1) bounds. |
| workBounds | An optional named list of 2-column matrices specifying bounds on the working scale of the probability distribution, transition probability, and initial distribution parameters. For each matrix, the first column pertains to the lower bound and the second column the upper bound. For data streams, each element of workBounds should be a k x 2 matrix with the same name of the corresponding element of Par0, where k is the number of parameters. For transition probability parameters, the corresponding element of workBounds must be a k x 2 matrix named "beta", where <code>k=length(beta0)</code> . For initial distribution parameters, the corresponding element of workBounds must be a k x 2 matrix named "delta", where <code>k=length(delta0)</code> . |
| optMethod | The optimization method to be used. Can be "nlm" (the default; see nlm), "TMB" (using Template Model Builder; see optimx for control parameters), "Nelder-Mead" (see optim), or "SANN" (see optim). |
| hierStates | A hierarchical model structure Node for the states. See fitHMM . |
| hierDist | A hierarchical data structure Node for the data streams. See fitHMM . |

Details

If design matrix includes non-factor covariates, then natural scale parameters are assumed to correspond to the mean value(s) for the covariate(s) (if `nrow(data)>1`) and `getParDM` simply returns one possible solution to the system of linear equations defined by `Par`, `DM`, and any other constraints using singular value decomposition. This can be helpful for exploring relationships between the natural and working scale parameters when covariates are included, but `getParDM` will not necessarily return "good" starting values (i.e., `Par0`) for [fitHMM](#) or [MifitHMM](#).

Value

A list of parameter values that can be used as starting values (Par0) in [fithMM](#) or [MIfithMM](#)

See Also

[getPar](#), [getPar0](#), [fithMM](#), [MIfithMM](#)

Examples

```
# data is a momentuHMMData object, automatically loaded with the package
data <- example$m$data
stepDist <- "gamma"
angleDist <- "vm"
nbStates <- 2
stepPar0 <- c(15,50,10,20) # natural scale mean_1, mean_2, sd_1, sd_2
anglePar0 <- c(0.7,1.5) # natural scale concentration_1, concentration_2

# get working parameters for 'DM' that constrains step length mean_1 < mean_2
stepDM <- matrix(c(1,1,0,0,0,1,0,0,0,0,1,0,0,0,0,1),4,4,
  dimnames=list(NULL,c("mean:(Intercept)", "mean_2",
    "sd_1:(Intercept)", "sd_2:(Intercept)")))
stepworkBounds <- matrix(c(-Inf,Inf),4,2,byrow=TRUE,
  dimnames=list(colnames(stepDM),c("lower", "upper")))
stepworkBounds["mean_2", "lower"] <- 0 #coefficient for 'mean_2' constrained to be positive
wPar0 <- getParDM(nbStates=2,dist=list(step=stepDist),
  Par=list(step=stepPar0),
  DM=list(step=stepDM),workBounds=list(step=stepworkBounds))

## Not run:
# Fit HMM using wPar0 as initial values for the step data stream
mPar <- fithMM(data,nbStates=2,dist=list(step=stepDist,angle=angleDist),
  Par0=list(step=wPar0$step,angle=anglePar0),
  DM=list(step=stepDM),workBounds=list(step=stepworkBounds))

## End(Not run)

# get working parameters for 'DM' using 'cov1' and 'cov2' covariates
stepDM2 <- list(mean=~cov1,sd=~cov2)
wPar20 <- getParDM(data,nbStates=2,dist=list(step=stepDist),
  Par=list(step=stepPar0),
  DM=list(step=stepDM2))

## Not run:
# Fit HMM using wPar20 as initial values for the step data stream
mPar2 <- fithMM(data,nbStates=2,dist=list(step=stepDist,angle=angleDist),
  Par0=list(step=wPar20$step,angle=anglePar0),
  DM=list(step=stepDM2))

## End(Not run)
```

| | |
|------------|--------------------------------------|
| getTrProbs | <i>Transition probability matrix</i> |
|------------|--------------------------------------|

Description

Computation of the transition probability matrix for each time step as a function of the covariates and the regression parameters.

Usage

```
getTrProbs(data, ...)  
  
## Default S3 method:  
getTrProbs(  
  data,  
  nbStates,  
  beta,  
  workBounds = NULL,  
  formula = ~1,  
  mixtures = 1,  
  betaRef = NULL,  
  stateNames = NULL,  
  getCI = FALSE,  
  covIndex = NULL,  
  alpha = 0.95,  
  Time.name = NULL,  
  Time.unit = "auto",  
  rateMatrix = FALSE,  
  kappa = Inf,  
  ...  
)  
  
## S3 method for class 'hierarchical'  
getTrProbs(  
  data,  
  hierStates,  
  hierBeta,  
  workBounds = NULL,  
  hierFormula = NULL,  
  mixtures = 1,  
  hierDist,  
  getCI = FALSE,  
  covIndex = NULL,  
  alpha = 0.95,  
  Time.name = NULL,  
  Time.unit = "auto",  
  rateMatrix = FALSE,
```

```

    kappa = Inf,
    ...
  )

```

Arguments

| | |
|------------|--|
| data | <p>momentuHMM object, momentuHierHMM object, miSum object, miHMM object, momentuHMMDData object, momentuHierHMMDData object, or a data frame containing the covariate values.</p> <p>If a data frame is provided, then either <code>nbStates</code> must be specified (for a regular HMM) or <code>hierStates</code> and <code>hierDist</code> must be specified (for a hierarchical HMM).</p> |
| ... | further arguments passed to or from other methods; most are ignored if data is a momentuHMM or momentuHierHMM object |
| nbStates | Number of states. Ignored unless data is a data frame. |
| beta | Matrix of regression coefficients for the transition probabilities |
| workBounds | An optional named list of 2-column matrices specifying bounds on the working scale of the transition probability parameters ('beta' and, for recharge models, 'g0' and 'theta'). <code>workBounds\$beta</code> must be a $k \times 2$ matrix, where $k = \text{length}(\text{beta})$. The first column pertains to the lower bound and the second column the upper bound. Ignored unless data is a data frame. |
| formula | Regression formula for the transition probability covariates. Ignored unless data is a data frame. |
| mixtures | Number of mixtures for the state transition probabilities. Ignored unless data is a data frame. |
| betaRef | Indices of reference elements for t.p.m. multinomial logit link. Ignored unless data is a data frame. |
| stateNames | Optional character vector of length <code>nbStates</code> indicating state names. Ignored unless data is a data frame. |
| getCI | Logical indicating whether to calculate standard errors and logit-transformed confidence intervals based on fitted momentuHMM or momentuHierHMM object. Default: FALSE. |
| covIndex | Integer vector indicating specific rows of the data to be used in the calculations. This can be useful for reducing unnecessarily long computation times (particularly when <code>getCI=TRUE</code>), e.g., when <code>formula</code> includes factor covariates (such as ID) but no temporal covariates. Ignored if data is not a momentuHMM , momentuHierHMM , miSum , or miHMM object. |
| alpha | Significance level of the confidence intervals (if <code>getCI=TRUE</code>). Default: 0.95 (i.e. 95% CIs). |
| Time.name | Character string indicating name of the time column in data (for continuous-time HMMs). Default: 'NULL' (discrete time). Ignored unless data is a <code>data.frame</code> , momentuHMMDData object, or momentuHierHMMDData object (i.e. not a momentuHMM object, momentuHierHMM object, miSum object, or a miHMM object). |

| | |
|-------------|---|
| Time.unit | Character string indicating units for time difference between observations (e.g. 'auto', 'secs', 'mins', 'hours', 'days', 'weeks'). Ignored unless data[[Time.name]] is of class date-time or date . Default: 'auto'. Ignored if data is a ctds object returned by prepCTDS . |
| rateMatrix | Logical indicating whether to return the transition rate matrix. Default: FALSE. Ignored unless data is a continuous-time model or Time.name is specified. |
| kappa | maximum allowed value for the row sums of the off-diagonal elements in the state transition rate matrix, such that the minimum value for the diagonal elements is -kappa. Default: Inf. Setting less than Inf can help avoid numerical issues during optimization, in which case the transition rate parameters beta are on the logit scale (instead of the log scale). Ignored unless data is a data.frame , momentuHMMData object, or momentuHierHMMData object (i.e. not a momentuHMM object, momentuHierHMM object, miSum object, or a miHMM object). |
| hierStates | A hierarchical model structure Node for the states ('state'). See fitHMM . |
| hierBeta | A hierarchical data structure Node for the matrix of regression coefficients for the transition probabilities at each level of the hierarchy, including initial values ('beta'), parameter equality constraints ('betaCons'), fixed parameters ('fixPar'), and working scale bounds ('workBounds'). See details. |
| hierFormula | A hierarchical formula structure for the transition probability covariates for each level of the hierarchy ('formula'). See fitHMM . |
| hierDist | A hierarchical data structure Node for the data streams ('dist'). See fitHMM . |

Value

If mixtures=1, an array of dimension nbStates x nbStates x nrow(data) containing the t.p.m for each observation in data. If mixtures>1, a list of length mixtures, where each element is an array of dimension nbStates x nbStates x nrow(data) containing the t.p.m for each observation in data.

If getCI=TRUE then a list of arrays is returned (with elements est, se, lower, and upper).

If a hierarchical HMM structure is provided, then a hierarchical data structure containing the state transition probabilities for each time step at each level of the hierarchy ('gamma') is returned.

Examples

```
m <- example$m
trProbs <- getTrProbs(m)

# equivalent
trProbs <- getTrProbs(m$data,nbStates=2,beta=m$mle$beta,formula=m$conditions$formula)

## Not run:
# calculate SEs and 95% CIs
trProbsSE <- getTrProbs(m, getCI=TRUE)

# plot estimates and CIs for each state transition
par(mfrow=c(2,2))
for(i in 1:2){
```

```

for(j in 1:2){
  plot(trProbsSE$est[i,j,],type="l",
       ylim=c(0,1), ylab=paste(i,"->",j))
  arrows(1:dim(trProbsSE$est)[3],
        trProbsSE$lower[i,j,],
        1:dim(trProbsSE$est)[3],
        trProbsSE$upper[i,j,],
        length=0.025, angle=90, code=3, col=gray(.5), lwd=1.3)
}
}

# limit calculations to first 10 observations
trProbsSE_10 <- getTrProbs(m, getCI=TRUE, covIndex=1:10)

## End(Not run)

```

HMMfits

Constructor of HMMfits objects

Description

Constructor of HMMfits objects

Usage

```
HMMfits(m)
```

Arguments

`m` A list of [momentuHMM](#) objects.
HMMfits objects are returned by [MIfitHMM](#) when arguments `fit=TRUE` and `poolEstimates=FALSE`.

Value

An object HMMfits.

is.crwData

Is crwData

Description

Check that an object is of class [crwData](#). Used in [MIfitHMM](#).

Usage

```
is.crwData(x)
```

Arguments

x An R object

Value

TRUE if x is of class `crwData`, FALSE otherwise.

is.crwHierData *Is crwHierData*

Description

Check that an object is of class `crwHierData`. Used in `MIfitHMM`.

Usage

```
is.crwHierData(x)
```

Arguments

x An R object

Value

TRUE if x is of class `crwHierData`, FALSE otherwise.

is.crwHierSim *Is crwHierSim*

Description

Check that an object is of class `crwHierSim`.

Usage

```
is.crwHierSim(x)
```

Arguments

x An R object

Value

TRUE if x is of class `crwHierSim`, FALSE otherwise.

`is.crwSim`*Is crwSim*

Description

Check that an object is of class `crwSim`.

Usage

```
is.crwSim(x)
```

Arguments

`x` An R object

Value

TRUE if `x` is of class `crwSim`, FALSE otherwise.

`is.HMMfits`*Is HMMfits*

Description

Check that an object is of class `HMMfits`.

Usage

```
is.HMMfits(x)
```

Arguments

`x` An R object

Value

TRUE if `x` is of class `HMMfits`, FALSE otherwise.

`is.miHMM`*Is miHMM*

Description

Check that an object is of class `miHMM`.

Usage

```
is.miHMM(x)
```

Arguments

`x` An R object

Value

TRUE if `x` is of class `miHMM`, FALSE otherwise.

`is.miSum`*Is miSum*

Description

Check that an object is of class `miSum`.

Usage

```
is.miSum(x)
```

Arguments

`x` An R object

Value

TRUE if `x` is of class `miSum`, FALSE otherwise.

is.momentuHierHMM *Is momentuHierHMM*

Description

Check that an object is of class `momentuHierHMM`. Used in `CIreal`, `CIbeta`, `plotPR`, `plotStates`, `pseudoRes`, `stateProbs`, and `viterbi`.

Usage

```
is.momentuHierHMM(x)
```

Arguments

x An R object

Value

TRUE if x is of class `momentuHierHMM`, FALSE otherwise.

is.momentuHierHMMData *Is momentuHierHMMData*

Description

Check that an object is of class `momentuHierHMMData`. Used in `fitHMM`.

Usage

```
is.momentuHierHMMData(x)
```

Arguments

x An R object

Value

TRUE if x is of class `momentuHierHMMData`, FALSE otherwise.

| | |
|---------------|----------------------|
| is.momentuHMM | <i>Is momentuHMM</i> |
|---------------|----------------------|

Description

Check that an object is of class `momentuHMM`. Used in `CIreal`, `CIbeta`, `plotPR`, `plotStates`, `pseudoRes`, `stateProbs`, and `viterbi`.

Usage

```
is.momentuHMM(x)
```

Arguments

x An R object

Value

TRUE if x is of class `momentuHMM`, FALSE otherwise.

| | |
|-------------------|--------------------------|
| is.momentuHMMData | <i>Is momentuHMMData</i> |
|-------------------|--------------------------|

Description

Check that an object is of class `momentuHMMData`. Used in `fitHMM`.

Usage

```
is.momentuHMMData(x)
```

Arguments

x An R object

Value

TRUE if x is of class `momentuHMMData`, FALSE otherwise.

| | |
|----------|----------------------------------|
| logAlpha | <i>Forward log-probabilities</i> |
|----------|----------------------------------|

Description

Used in [stateProbs](#) and [pseudoRes](#).

Usage

```
logAlpha(m)
```

Arguments

`m` A [momentuHMM](#), [miHMM](#), or [miSum](#) object.

Value

A list of length `model$conditions$mixtures` where each element is a matrix of forward log-probabilities for each mixture.

Examples

```
## Not run:  
# m is a momentuHMM object (as returned by fitHMM), automatically loaded with the package  
m <- example$m  
  
la <- momentuHMM:::logAlpha(m)  
  
## End(Not run)
```

| | |
|---------|-----------------------------------|
| logBeta | <i>Backward log-probabilities</i> |
|---------|-----------------------------------|

Description

Used in [stateProbs](#).

Usage

```
logBeta(m)
```

Arguments

`m` A [momentuHMM](#), [miHMM](#), or [miSum](#) object.

Value

A list of length `model$conditions$mixtures` where each element is a matrix of backward log-probabilities for each mixture.

Examples

```
## Not run:
# m is a momentuHMM object (as returned by fitHMM), automatically loaded with the package
m <- example$m

lb <- momentuHMM::logBeta(m)

## End(Not run)
```

MIfitCTHMM

Fit continuous-time multivariate HMMs to multiple imputation data

Description

Fit an approximate continuous-time (multivariate) hidden Markov model to multiple imputation data. Multiple imputation is a method for accommodating missing data, temporal-irregularity, or location measurement error in hidden Markov models, where pooled parameter estimates reflect uncertainty attributable to observation error. The discrete-time approximation of the continuous-time model improves as the time between observations decreases. Note that any time-varying covariates are assumed piece-wise constant between observations.

Usage

```
MIfitCTHMM(miData, ...)

## Default S3 method:
MIfitCTHMM(
  miData,
  nSims,
  ncores = 1,
  poolEstimates = TRUE,
  alpha = 0.95,
  na.rm = FALSE,
  Time.name = "time",
  Time.unit = "auto",
  CTDS = FALSE,
  nbStates,
  dist,
  Par0,
  beta0 = NULL,
  delta0 = NULL,
  estAngleMean = NULL,
```

```
circularAngleMean = NULL,  
formula = ~1,  
formulaDelta = NULL,  
stationary = FALSE,  
mixtures = 1,  
formulaPi = NULL,  
nlmPar = NULL,  
fit = TRUE,  
useInitial = FALSE,  
DM = NULL,  
userBounds = NULL,  
workBounds = NULL,  
betaCons = NULL,  
deltaCons = NULL,  
mvnCoords = NULL,  
stateNames = NULL,  
knownStates = NULL,  
fixPar = NULL,  
retryFits = 0,  
retrySD = NULL,  
optMethod = "nlm",  
control = list(),  
prior = NULL,  
modelName = NULL,  
kappa = Inf,  
covNames = NULL,  
spatialCovs = NULL,  
centers = NULL,  
centroids = NULL,  
angleCovs = NULL,  
altCoordNames = NULL,  
gradient = FALSE,  
smoothGradient = FALSE,  
weights = c(1/2, 1/8, 1/8, 1/8, 1/8),  
scaleGrad = NULL,  
method = "IS",  
parIS = 1000,  
dfSim = Inf,  
grid.eps = 1,  
crit = 2.5,  
scaleSim = 1,  
quad.ask = FALSE,  
force.quad = TRUE,  
fullPost = TRUE,  
dfPostIS = Inf,  
scalePostIS = 1,  
thetaSamp = NULL,  
export = NULL,
```

```
    rast,
    directions = 4,
    zero.idx = integer(),
    interpMethod = "ShortestPath",
    spatialCovs.grad = NULL,
    crw = TRUE,
    normalize.gradients = FALSE,
    grad.point.decreasing = FALSE,
    ...
)

## S3 method for class 'hierarchical'
MifitCTHMM(
  miData,
  nSims,
  ncores = 1,
  poolEstimates = TRUE,
  alpha = 0.95,
  na.rm = FALSE,
  Time.name = "time",
  Time.unit = "auto",
  CTDS = FALSE,
  hierStates,
  hierDist,
  Par0,
  hierBeta = NULL,
  hierDelta = NULL,
  estAngleMean = NULL,
  circularAngleMean = NULL,
  hierFormula = NULL,
  hierFormulaDelta = NULL,
  mixtures = 1,
  formulaPi = NULL,
  nlmPar = NULL,
  fit = TRUE,
  useInitial = FALSE,
  DM = NULL,
  userBounds = NULL,
  workBounds = NULL,
  betaCons = NULL,
  deltaCons = NULL,
  mvnCoords = NULL,
  knownStates = NULL,
  fixPar = NULL,
  retryFits = 0,
  retrySD = NULL,
  optMethod = "nlm",
  control = list(),
```

```

prior = NULL,
modelName = NULL,
kappa = Inf,
covNames = NULL,
spatialCovs = NULL,
centers = NULL,
centroids = NULL,
angleCovs = NULL,
altCoordNames = NULL,
gradient = FALSE,
smoothGradient = FALSE,
weights = c(1/2, 1/8, 1/8, 1/8, 1/8),
scaleGrad = NULL,
method = "IS",
parIS = 1000,
dfSim = Inf,
grid.eps = 1,
crit = 2.5,
scaleSim = 1,
quad.ask = FALSE,
force.quad = TRUE,
fullPost = TRUE,
dfPostIS = Inf,
scalePostIS = 1,
thetaSamp = NULL,
export = NULL,
rast,
directions = 4,
zero.idx = integer(),
interpMethod = "ShortestPath",
spatialCovs.grad = NULL,
crw = TRUE,
normalize.gradients = FALSE,
grad.point.decreasing = FALSE,
...
)

```

Arguments

| | |
|---------------------|--|
| <code>miData</code> | A <code>crwData</code> object, a <code>crwHierData</code> object, a <code>crwSim</code> object, a <code>crwHierSim</code> object, a list of <code>momentuHMMData</code> objects, or a list of <code>momentuHierHMMData</code> objects. |
| <code>...</code> | further arguments passed to or from other methods |
| <code>nSims</code> | Number of imputations in which to fit the HMM using <code>fitCTHMM</code> . If <code>miData</code> is a list of <code>momentuHMMData</code> objects, <code>nSims</code> cannot exceed the length of <code>miData</code> . |
| <code>ncores</code> | Number of cores to use for parallel processing. Default: 1 (no parallel processing). |

| | |
|--------------------------------|--|
| <code>poolEstimates</code> | Logical indicating whether or not to calculate pooled parameter estimates across the <code>nSims</code> imputations using <code>MIpool</code> . Default: <code>TRUE</code> . |
| <code>alpha</code> | Significance level for calculating confidence intervals of pooled estimates when <code>poolEstimates=TRUE</code> (see <code>MIpool</code>). Default: <code>0.95</code> . |
| <code>na.rm</code> | Logical indicating whether or not to exclude model fits with NA parameter estimates or standard errors from pooling when <code>poolEstimates=TRUE</code> (see <code>MIpool</code>). Default: <code>FALSE</code> . |
| <code>Time.name</code> | Character string indicating name of the time column. Default: <code>'time'</code> . Ignored if <code>miData</code> is a <code>crwData</code> object. |
| <code>Time.unit</code> | Character string indicating units for time difference between observations (e.g. <code>'auto'</code> , <code>'secs'</code> , <code>'mins'</code> , <code>'hours'</code> , <code>'days'</code> , <code>'weeks'</code>). Ignored unless <code>data[[Time.name]]</code> is of class <code>date-time</code> or <code>date</code> . Default: <code>'auto'</code> . |
| <code>CTDS</code> | Logical indicating whether multiple imputation location data should be prepared for a continuous-time, discrete-space analysis. See <code>prepCTDS</code> . Default: <code>FALSE</code> . Ignored unless <code>miData</code> is a <code>crwData</code> object. |
| <code>nbStates</code> | Number of states of the HMM. See <code>fitCTHMM</code> . |
| <code>dist</code> | A named list indicating the probability distributions of the data streams. See <code>fitCTHMM</code> . |
| <code>Par0</code> | A named list containing vectors of initial state-dependent probability distribution parameters for each data stream specified in <code>dist</code> . See <code>fitCTHMM</code> . <code>Par0</code> may also be a list of length <code>nSims</code> , where each element is a named list containing vectors of initial state-dependent probability distribution parameters for each imputation. Note that if <code>useInitial=TRUE</code> then <code>Par0</code> is ignored after the first imputation. |
| <code>beta0</code> | Initial matrix of regression coefficients for the transition probabilities. See <code>fitCTHMM</code> . <code>beta0</code> may also be a list of length <code>nSims</code> , where each element is an initial matrix of regression coefficients for the transition probabilities for each imputation. |
| <code>delta0</code> | Initial values for the initial distribution of the HMM. See <code>fitCTHMM</code> . <code>delta0</code> may also be a list of length <code>nSims</code> , where each element is the initial values for the initial distribution of the HMM for each imputation. |
| <code>estAngleMean</code> | An optional named list indicating whether or not to estimate the angle mean for data streams with angular distributions (<code>'vm'</code> and <code>'wrpcauchy'</code>). See <code>fitCTHMM</code> . |
| <code>circularAngleMean</code> | An optional named list indicating whether to use circular-linear or circular-circular regression on the mean of circular distributions (<code>'vm'</code> and <code>'wrpcauchy'</code>) for turning angles. See <code>fitCTHMM</code> . |
| <code>formula</code> | Regression formula for the transition probability covariates. See <code>fitCTHMM</code> . |
| <code>formulaDelta</code> | Regression formula for the initial distribution. See <code>fitCTHMM</code> . |
| <code>stationary</code> | <code>FALSE</code> if there are time-varying covariates in <code>formula</code> or any covariates in <code>formulaDelta</code> . If <code>TRUE</code> , the initial distribution is considered equal to the stationary distribution. See <code>fitCTHMM</code> . |
| <code>mixtures</code> | Number of mixtures for the state transition probabilities (i.e. discrete random effects <i>sensu</i> DeRuiter et al. 2017). Default: <code>mixtures=1</code> . |

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| <code>formulaPi</code> | Regression formula for the mixture distribution probabilities. See fitCTHMM . |
| <code>nlmPar</code> | List of parameters to pass to the optimization function <code>nlm</code> (which should be either <code>print.level</code> , <code>gradtol</code> , <code>stepmax</code> , <code>steptol</code> , <code>iterlim</code> , or <code>hessian</code> – see <code>nlm</code> 's documentation for more detail). For <code>print.level</code> , the default value of 0 means that no printing occurs, a value of 1 means that the first and last iterations of the optimization are detailed, and a value of 2 means that each iteration of the optimization is detailed. Ignored unless <code>optMethod="nlm"</code> . |
| <code>fit</code> | TRUE if the HMM should be fitted to the data, FALSE otherwise. See fitCTHMM . If <code>fit=FALSE</code> and <code>miData</code> is a crwData object, then <code>MIfitCTHMM</code> returns a list containing a momentuHMMData object (if <code>nSims=1</code>) or, if <code>nSims>1</code> , a crwSim object. |
| <code>useInitial</code> | Logical indicating whether or not to use parameter estimates for the first model fit as initial values for all subsequent model fits. If <code>ncores>1</code> then the first model is fit on a single core and then used as the initial values for all subsequent model fits on each core (in this case, the progress of the initial model fit can be followed using the <code>print.level</code> option in <code>nlmPar</code>). Default: FALSE. Ignored if <code>nSims<2</code> . |
| <code>DM</code> | An optional named list indicating the design matrices to be used for the probability distribution parameters of each data stream. See fitCTHMM . |
| <code>userBounds</code> | An optional named list of 2-column matrices specifying bounds on the natural (i.e., real) scale of the probability distribution parameters for each data stream. See fitCTHMM . |
| <code>workBounds</code> | An optional named list of 2-column matrices specifying bounds on the working scale of the probability distribution, transition probability, and initial distribution parameters. See fitCTHMM . |
| <code>betaCons</code> | Matrix of the same dimension as <code>beta0</code> composed of integers identifying any equality constraints among the t.p.m. parameters. See fitCTHMM . |
| <code>deltaCons</code> | Matrix of the same dimension as <code>delta0</code> composed of integers identifying any equality constraints among the initial distribution working scale parameters. Ignored unless a formula is provided in <code>formulaDelta</code> . See fitCTHMM . |
| <code>mvnCoords</code> | Character string indicating the name of location data that are to be modeled using a multivariate normal distribution. For example, if <code>mu="mvnorm2"</code> was included in <code>dist</code> and <code>(mu.x, mu.y)</code> are location data, then <code>mvnCoords="mu"</code> needs to be specified in order for these data to be properly treated as locations in functions such as plot.momentuHMM , plot.miSum , plot.miHMM , plotSpatialCov , and MIpool . |
| <code>stateNames</code> | Optional character vector of length <code>nbStates</code> indicating state names. |
| <code>knownStates</code> | Vector of values of the state process which are known prior to fitting the model (if any). See fitCTHMM . If <code>miData</code> is a list of momentuHMMData objects, then <code>knownStates</code> can alternatively be a list of vectors containing the known values for the state process for each element of <code>miData</code> . |
| <code>fixPar</code> | An optional list of vectors indicating parameters which are assumed known prior to fitting the model. See fitCTHMM . |
| <code>retryFits</code> | Non-negative integer indicating the number of times to attempt to iteratively fit the model using random perturbations of the current parameter estimates as the initial values for likelihood optimization. See fitCTHMM . |

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| retrySD | An optional list of scalars or vectors indicating the standard deviation to use for normal perturbations of each working scale parameter when <code>retryFits>0</code> . See fitCTHMM . |
| optMethod | The optimization method to be used. Can be “nlm” (the default; see nlm), “TMB” (using Template Model Builder; see optimx for control parameters), “Nelder-Mead” (see optim), or “SANN” (see optim). |
| control | A list of control parameters to be passed to optim (ignored unless <code>optMethod="TMB"</code> , <code>optMethod="Nelder-Mead"</code> , or <code>optMethod="SANN"</code>). |
| prior | A function that returns the log-density of the working scale parameter prior distribution(s). See fitCTHMM . |
| modelName | An optional character string providing a name for the fitted model. If provided, <code>modelName</code> will be returned in print.momentuHMM , AIC.momentuHMM , AICweights , and other functions. |
| kappa | maximum allowed value for the row sums of the off-diagonal elements in the state transition rate matrix, such that the minimum value for the diagonal elements is <code>-kappa</code> . Default: <code>Inf</code> . Setting less than <code>Inf</code> can help avoid numerical issues during optimization, in which case the transition rate parameters <code>beta</code> are on the logit scale (instead of the log scale). |
| covNames | Names of any covariates in <code>miData\$crwPredict</code> (if <code>miData</code> is a crwData object; otherwise <code>covNames</code> is ignored). See prepData . |
| spatialCovs | List of raster layer(s) for any spatial covariates. See prepData . |
| centers | 2-column matrix providing the x-coordinates (column 1) and y-coordinates (column 2) for any activity centers (e.g., potential centers of attraction or repulsion) from which distance and angle covariates will be calculated based on realizations of the position process. See prepData . Ignored unless <code>miData</code> is a crwData object. |
| centroids | List where each element is a data frame containing the x-coordinates (‘x’), y-coordinates (‘y’), and times (with user-specified name, e.g., ‘time’) for centroids (i.e., dynamic activity centers where the coordinates can change over time) from which distance and angle covariates will be calculated based on the location data. See prepData . Ignored unless <code>miData</code> is a crwData object. |
| angleCovs | Character vector indicating the names of any circular-circular regression angular covariates in <code>miData\$crwPredict</code> that need conversion from standard direction (in radians relative to the x-axis) to turning angle (relative to previous movement direction) See prepData . Ignored unless <code>miData</code> is a crwData or crwHierData object. |
| altCoordNames | Character string indicating an alternative name for the returned location data. See prepData . Ignored unless <code>miData</code> is a crwData or crwHierData object. |
| gradient | Logical indicating whether or not to calculate gradients of <code>spatialCovs</code> using bilinear interpolation (e.g. for inclusion in potential functions). Ignored unless <code>miData</code> is a crwData or crwHierData object. See prepData . Default: <code>FALSE</code> . |
| smoothGradient | Logical indicating whether or not to calculate smoothed gradients. See addSmoothGradient . Ignored unless <code>gradient=TRUE</code> . Default: <code>FALSE</code> . |

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| weights | Numeric vector indicating the weight for the points in a smoothed version of the gradient. See addSmoothGradient . Ignored unless <code>smoothGradient=TRUE</code> . Default: <code>c(1/2, 1/8, 1/8, 1/8, 1/8)</code> . |
| scaleGrad | Numeric scalar indicating the distance from the observed location to each smoothing point (before adjusting by time step). See addSmoothGradient . Ignored unless <code>smoothGradient=TRUE</code> . |
| method | Method for obtaining weights for movement parameter samples. See crwSimulator . Ignored unless <code>miData</code> is a crwData object. |
| parIS | Size of the parameter importance sample. See crwSimulator . Ignored unless <code>miData</code> is a crwData object. |
| dfSim | Degrees of freedom for the t approximation to the parameter posterior. See 'df' argument in crwSimulator . Ignored unless <code>miData</code> is a crwData object. |
| grid.eps | Grid size for <code>method="quadrature"</code> . See crwSimulator . Ignored unless <code>miData</code> is a crwData object. |
| crit | Criterion for deciding "significance" of quadrature points (difference in log-likelihood). See crwSimulator . Ignored unless <code>miData</code> is a crwData object. |
| scaleSim | Scale multiplier for the covariance matrix of the t approximation. See 'scale' argument in crwSimulator . Ignored unless <code>miData</code> is a crwData object. |
| quad.ask | Logical, for <code>method='quadrature'</code> . Whether or not the sampler should ask if quadrature sampling should take place. It is used to stop the sampling if the number of likelihood evaluations would be extreme. Default: <code>FALSE</code> . Ignored if <code>ncores>1</code> . |
| force.quad | A logical indicating whether or not to force the execution of the quadrature method for large parameter vectors. See crwSimulator . Default: <code>TRUE</code> . Ignored unless <code>miData</code> is a crwData object and <code>method='quadrature'</code> . |
| fullPost | Logical indicating whether to draw parameter values as well to simulate full posterior. See crwPostIS . Ignored unless <code>miData</code> is a crwData object. |
| dfPostIS | Degrees of freedom for multivariate t distribution approximation to parameter posterior. See 'df' argument in crwPostIS . Ignored unless <code>miData</code> is a crwData object. |
| scalePostIS | Extra scaling factor for t distribution approximation. See 'scale' argument in crwPostIS . Ignored unless <code>miData</code> is a crwData object. |
| thetaSamp | If multiple parameter samples are available in crwSimulator objects, setting <code>thetaSamp=n</code> will use the nth sample. Defaults to the last. See crwSimulator and crwPostIS . Ignored unless <code>miData</code> is a crwData object. |
| export | Character vector of the names of any additional objects or functions in the global environment that are used in <code>DM</code> , <code>formula</code> , <code>formulaDelta</code> , and/or <code>formulaPi</code> . Only necessary if <code>ncores>1</code> so that the needed items will be exported to the workers. |
| rast | A raster object or raster stack object that will define the discrete-space grid cells for the CTDS movement path. See prepCTDS . Ignored unless <code>miData</code> is a crwData object and <code>CTDS</code> is <code>TRUE</code> . |
| directions | Integer. See prepCTDS . Ignored unless <code>miData</code> is a crwData object and <code>CTDS</code> is <code>TRUE</code> . |

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| <code>zero.idx</code> | Integer vector of the indices of raster cells that are not passable and should be excluded. See prepCTDS . Ignored unless <code>miData</code> is a <code>crwData</code> object and <code>CTDS</code> is <code>TRUE</code> . |
| <code>interpMethod</code> | Specifies interpolation method. See prepCTDS . Ignored unless <code>miData</code> is a <code>crwData</code> object and <code>CTDS</code> is <code>TRUE</code> . |
| <code>spatialCovs.grad</code> | List of raster objects for spatio-temporally referenced covariates, where a directional gradient is to be calculated internally using rast.grad . See prepCTDS . Ignored unless <code>miData</code> is a <code>crwData</code> object and <code>CTDS</code> is <code>TRUE</code> . |
| <code>crw</code> | Logical. See prepCTDS . Ignored unless <code>miData</code> is a <code>crwData</code> object and <code>CTDS</code> is <code>TRUE</code> . |
| <code>normalize.gradients</code> | Logical. See prepCTDS . Ignored unless <code>miData</code> is a <code>crwData</code> object and <code>CTDS</code> is <code>TRUE</code> . |
| <code>grad.point.decreasing</code> | Logical. See prepCTDS . Ignored unless <code>miData</code> is a <code>crwData</code> object and <code>CTDS</code> is <code>TRUE</code> . |
| <code>hierStates</code> | A hierarchical model structure Node for the states. See fitCTHMM . |
| <code>hierDist</code> | A hierarchical data structure Node for the data streams. See fitCTHMM . |
| <code>hierBeta</code> | A hierarchical data structure Node for the matrix of initial values for the regression coefficients of the transition probabilities at each level of the hierarchy ('beta'). See fitCTHMM . |
| <code>hierDelta</code> | A hierarchical data structure Node for the matrix of initial values for the regression coefficients of the initial distribution at each level of the hierarchy ('delta'). See fitCTHMM . |
| <code>hierFormula</code> | A hierarchical formula structure for the transition probability covariates for each level of the hierarchy. See fitCTHMM . |
| <code>hierFormulaDelta</code> | A hierarchical formula structure for the initial distribution covariates for each level of the hierarchy ('formulaDelta'). Default: <code>NULL</code> (no covariate effects and <code>fixPar\$delta</code> is specified on the working scale). See fitCTHMM . |

Details

`miData` can either be a [crwData](#) or [crwHierData](#) object (as returned by [crawlWrap](#)), a [crwSim](#) or [crwHierSim](#) object (as returned by [MifitCTHMM](#) when `fit=FALSE`), or a list of [momentuHMMData](#) or [momentuHierHMMData](#) objects (e.g., each element of the list as returned by [prepData](#)).

If `miData` is a `crwData` (or `crwHierData`) object, [MifitCTHMM](#) uses a combination of [crwSimulator](#), [crwPostIS](#), [prepData](#), and [fitCTHMM](#) to draw `nSims` realizations of the position process and fit the specified HMM to each imputation of the data. The vast majority of [MifitCTHMM](#) arguments are identical to the corresponding arguments from these functions.

If `miData` is a `crwData` or `crwHierData` object, `nSims` determines both the number of realizations of the position process to draw (using [crwSimulator](#) and [crwPostIS](#)) as well as the number of HMM fits.

If `miData` is a `crwSim` (or `crwHierSim`) object or a list of `momentuHMMData` (or `momentuHierHMMData`) object(s), the specified HMM will simply be fitted to each of the `momentuHMMData` (or `momentuHierHMMData`) objects and all arguments related to `crwSimulator`, `crwPostIS`, or `prepData` are ignored.

`fitCTHMM` assumes the snapshot property applies to all data stream distributions (i.e. observations are “instantaneous”) except for the (multivariate) normal random walk (`rw_norm`, `rw_mvnorm2`, `rw_mvnorm3`) and Poisson (`pois`) distributions. For these particular distributions, the observed data are not “instantaneous”; they depend on the time interval between observations (Δ_t) and, hence, the state sequence during the entire interval. When fitting with `fitCTHMM` (or `MIfitCTHMM`), it is critical that the frequency of observations is high relative to the serial correlation in the hidden state process in order for the discrete-time approximation of `fitCTHMM` to be reasonably accurate for these distributions.

Value

If `nSims`>1, `poolEstimates`=TRUE, and `fit`=TRUE, a `miHMM` object, i.e., a list consisting of:

`miSum` `miSum` object returned by `MIpool`.
`HMMfits` List of length `nSims` comprised of `momentuHMM` objects.

If `poolEstimates`=FALSE and `fit`=TRUE, a list of length `nSims` consisting of `momentuHMM` objects is returned.

However, if `fit`=FALSE and `miData` is a `crwData` object, then `MIfitCTHMM` returns a `crwSim` object, i.e., a list containing `miData` (a list of `momentuHMMData` objects) and `crwSimulator` (a list of `crwSimulator` objects), and most other arguments related to `fitCTHMM` are ignored.

References

Hooten M.B., Johnson D.S., McClintock B.T., Morales J.M. 2017. Animal Movement: Statistical Models for Telemetry Data. CRC Press, Boca Raton.

McClintock B.T. 2017. Incorporating telemetry error into hidden Markov movement models using multiple imputation. Journal of Agricultural, Biological, and Environmental Statistics.

See Also

`crawlWrap`, `crwPostIS`, `crwSimulator`, `fitCTHMM`, `getParDM`, `MIpool`, `prepData`, `prepCTDS`

MIfitHMM

Fit HMMs to multiple imputation data

Description

Fit a (multivariate) hidden Markov model to multiple imputation data. Multiple imputation is a method for accommodating missing data, temporal-irregularity, or location measurement error in hidden Markov models, where pooled parameter estimates reflect uncertainty attributable to observation error.

Usage

```
MifitHMM(miData, ...)  
  
## Default S3 method:  
MifitHMM(  
  miData,  
  nSims,  
  ncores = 1,  
  poolEstimates = TRUE,  
  alpha = 0.95,  
  na.rm = FALSE,  
  nbStates,  
  dist,  
  Par0,  
  beta0 = NULL,  
  delta0 = NULL,  
  estAngleMean = NULL,  
  circularAngleMean = NULL,  
  formula = ~1,  
  formulaDelta = NULL,  
  stationary = FALSE,  
  mixtures = 1,  
  formulaPi = NULL,  
  nlmPar = NULL,  
  fit = TRUE,  
  useInitial = FALSE,  
  DM = NULL,  
  userBounds = NULL,  
  workBounds = NULL,  
  betaCons = NULL,  
  betaRef = NULL,  
  deltaCons = NULL,  
  mvnCoords = NULL,  
  stateNames = NULL,  
  knownStates = NULL,  
  fixPar = NULL,  
  retryFits = 0,  
  retrySD = NULL,  
  optMethod = "nlm",  
  control = list(),  
  prior = NULL,  
  modelName = NULL,  
  covNames = NULL,  
  spatialCovs = NULL,  
  centers = NULL,  
  centroids = NULL,  
  angleCovs = NULL,  
  altCoordNames = NULL,
```

```

gradient = FALSE,
smoothGradient = FALSE,
weights = c(1/2, 1/8, 1/8, 1/8, 1/8),
scaleGrad = NULL,
method = "IS",
parIS = 1000,
dfSim = Inf,
grid.eps = 1,
crit = 2.5,
scaleSim = 1,
quad.ask = FALSE,
force.quad = TRUE,
fullPost = TRUE,
dfPostIS = Inf,
scalePostIS = 1,
thetaSamp = NULL,
export = NULL,
...
)

```

```
## S3 method for class 'hierarchical'
```

```

MifitHMM(
  miData,
  nSims,
  ncores = 1,
  poolEstimates = TRUE,
  alpha = 0.95,
  na.rm = FALSE,
  hierStates,
  hierDist,
  Par0,
  hierBeta = NULL,
  hierDelta = NULL,
  estAngleMean = NULL,
  circularAngleMean = NULL,
  hierFormula = NULL,
  hierFormulaDelta = NULL,
  mixtures = 1,
  formulaPi = NULL,
  nlmPar = NULL,
  fit = TRUE,
  useInitial = FALSE,
  DM = NULL,
  userBounds = NULL,
  workBounds = NULL,
  betaCons = NULL,
  deltaCons = NULL,
  mvnCoords = NULL,

```

```

knownStates = NULL,
fixPar = NULL,
retryFits = 0,
retrySD = NULL,
optMethod = "nlm",
control = list(),
prior = NULL,
modelName = NULL,
covNames = NULL,
spatialCovs = NULL,
centers = NULL,
centroids = NULL,
angleCovs = NULL,
altCoordNames = NULL,
gradient = FALSE,
smoothGradient = FALSE,
weights = c(1/2, 1/8, 1/8, 1/8, 1/8),
scaleGrad = NULL,
method = "IS",
parIS = 1000,
dfSim = Inf,
grid.eps = 1,
crit = 2.5,
scaleSim = 1,
quad.ask = FALSE,
force.quad = TRUE,
fullPost = TRUE,
dfPostIS = Inf,
scalePostIS = 1,
thetaSamp = NULL,
export = NULL,
...
)

```

Arguments

| | |
|---------------|--|
| miData | A crwData object, a crwHierData object, a crwSim object, a crwHierSim object, a list of momentuHMMData objects, or a list of momentuHierHMMData objects. |
| ... | further arguments passed to or from other methods |
| nSims | Number of imputations in which to fit the HMM using fithmm . If miData is a list of momentuHMMData objects, nSims cannot exceed the length of miData. |
| ncores | Number of cores to use for parallel processing. Default: 1 (no parallel processing). |
| poolEstimates | Logical indicating whether or not to calculate pooled parameter estimates across the nSims imputations using MIpool . Default: TRUE. |
| alpha | Significance level for calculating confidence intervals of pooled estimates when poolEstimates=TRUE (see MIpool). Default: 0.95. |

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| <code>na.rm</code> | Logical indicating whether or not to exclude model fits with NA parameter estimates or standard errors from pooling when <code>poolEstimates=TRUE</code> (see MIPool). Default: FALSE. |
| <code>nbStates</code> | Number of states of the HMM. See fitHMM . |
| <code>dist</code> | A named list indicating the probability distributions of the data streams. See fitHMM . |
| <code>Par0</code> | A named list containing vectors of initial state-dependent probability distribution parameters for each data stream specified in <code>dist</code> . See fitHMM . <code>Par0</code> may also be a list of length <code>nSims</code> , where each element is a named list containing vectors of initial state-dependent probability distribution parameters for each imputation. Note that if <code>useInitial=TRUE</code> then <code>Par0</code> is ignored after the first imputation. |
| <code>beta0</code> | Initial matrix of regression coefficients for the transition probabilities. See fitHMM . <code>beta0</code> may also be a list of length <code>nSims</code> , where each element is an initial matrix of regression coefficients for the transition probabilities for each imputation. |
| <code>delta0</code> | Initial values for the initial distribution of the HMM. See fitHMM . <code>delta0</code> may also be a list of length <code>nSims</code> , where each element is the initial values for the initial distribution of the HMM for each imputation. |
| <code>estAngleMean</code> | An optional named list indicating whether or not to estimate the angle mean for data streams with angular distributions (<code>'vm'</code> and <code>'wrpcauchy'</code>). See fitHMM . |
| <code>circularAngleMean</code> | An optional named list indicating whether to use circular-linear or circular-circular regression on the mean of circular distributions (<code>'vm'</code> and <code>'wrpcauchy'</code>) for turning angles. See fitHMM . |
| <code>formula</code> | Regression formula for the transition probability covariates. See fitHMM . |
| <code>formulaDelta</code> | Regression formula for the initial distribution. See fitHMM . |
| <code>stationary</code> | FALSE if there are time-varying covariates in <code>formula</code> or any covariates in <code>formulaDelta</code> . If TRUE, the initial distribution is considered equal to the stationary distribution. See fitHMM . |
| <code>mixtures</code> | Number of mixtures for the state transition probabilities (i.e. discrete random effects <i>sensu</i> DeRuiter et al. 2017). Default: <code>mixtures=1</code> . |
| <code>formulaPi</code> | Regression formula for the mixture distribution probabilities. See fitHMM . |
| <code>nlmPar</code> | List of parameters to pass to the optimization function <code>nlm</code> (which should be either <code>print.level</code> , <code>gradtol</code> , <code>stepmax</code> , <code>steptol</code> , <code>iterlim</code> , or <code>hessian</code> – see <code>nlm</code> 's documentation for more detail). For <code>print.level</code> , the default value of 0 means that no printing occurs, a value of 1 means that the first and last iterations of the optimization are detailed, and a value of 2 means that each iteration of the optimization is detailed. Ignored unless <code>optMethod="nlm"</code> . |
| <code>fit</code> | TRUE if the HMM should be fitted to the data, FALSE otherwise. See fitHMM . If <code>fit=FALSE</code> and <code>miData</code> is a <code>crwData</code> object, then <code>MIfitHMM</code> returns a list containing a <code>momentuHMMData</code> object (if <code>nSims=1</code>) or, if <code>nSims>1</code> , a <code>crwSim</code> object. |
| <code>useInitial</code> | Logical indicating whether or not to use parameter estimates for the first model fit as initial values for all subsequent model fits. If <code>ncores>1</code> then the first |

model is fit on a single core and then used as the initial values for all subsequent model fits on each core (in this case, the progress of the initial model fit can be followed using the `print.level` option in `nlmPar`). Default: FALSE. Ignored if `nSims`<2.

| | |
|-------------|---|
| DM | An optional named list indicating the design matrices to be used for the probability distribution parameters of each data stream. See fithMM . |
| userBounds | An optional named list of 2-column matrices specifying bounds on the natural (i.e. real) scale of the probability distribution parameters for each data stream. See fithMM . |
| workBounds | An optional named list of 2-column matrices specifying bounds on the working scale of the probability distribution, transition probability, and initial distribution parameters. See fithMM . |
| betaCons | Matrix of the same dimension as <code>beta0</code> composed of integers identifying any equality constraints among the t.p.m. parameters. See fithMM . |
| betaRef | Numeric vector of length <code>nbStates</code> indicating the reference elements for the t.p.m. multinomial logit link. See fithMM . |
| deltaCons | Matrix of the same dimension as <code>delta0</code> composed of integers identifying any equality constraints among the initial distribution working scale parameters. Ignored unless a formula is provided in <code>formulaDelta</code> . See fithMM . |
| mvnCoords | Character string indicating the name of location data that are to be modeled using a multivariate normal distribution. For example, if <code>mu="mvnorm2"</code> was included in <code>dist</code> and <code>(mu.x, mu.y)</code> are location data, then <code>mvnCoords="mu"</code> needs to be specified in order for these data to be properly treated as locations in functions such as plot.momentuHMM , plot.miSum , plot.miHMM , plotSpatialCov , and MIpool . |
| stateNames | Optional character vector of length <code>nbStates</code> indicating state names. |
| knownStates | Vector of values of the state process which are known prior to fitting the model (if any). See fithMM . If <code>miData</code> is a list of momentuHMMData objects, then <code>knownStates</code> can alternatively be a list of vectors containing the known values for the state process for each element of <code>miData</code> . |
| fixPar | An optional list of vectors indicating parameters which are assumed known prior to fitting the model. See fithMM . |
| retryFits | Non-negative integer indicating the number of times to attempt to iteratively fit the model using random perturbations of the current parameter estimates as the initial values for likelihood optimization. See fithMM . |
| retrySD | An optional list of scalars or vectors indicating the standard deviation to use for normal perturbations of each working scale parameter when <code>retryFits</code> >0. See fithMM . |
| optMethod | The optimization method to be used. Can be "nlm" (the default; see nlm), "TMB" (using Template Model Builder; see optimx for control parameters), "Nelder-Mead" (see optim), or "SANN" (see optim). |
| control | A list of control parameters to be passed to optim (ignored unless <code>optMethod="Nelder-Mead"</code> or <code>optMethod="SANN"</code>). |

| | |
|----------------|--|
| prior | Either a function that returns the log-density of the working scale parameter prior distribution(s) (if <code>optMethod!='TMB'</code>) or, if <code>optMethod='TMB'</code> , a named list with optional entries matching the names of the data streams (i.e. <code>names(dist)</code>) or “beta” (state transition parameters), where each entry is a 2-column matrix (first column = mean, second column = sd) specifying the mean and standard deviation of the normal priors for each working parameter (any rows with NAs indicate no prior for the corresponding parameter). See fitHMM . |
| modelName | An optional character string providing a name for the fitted model. If provided, <code>modelName</code> will be returned in print.momentuHMM , AIC.momentuHMM , AICweights , and other functions. |
| covNames | Names of any covariates in <code>miData\$crwPredict</code> (if <code>miData</code> is a crwData object; otherwise <code>covNames</code> is ignored). See prepData . If <code>miData</code> is a crwData object, any covariate in <code>miData\$crwPredict</code> that is used in <code>formula</code> , <code>formulaDelta</code> , <code>formulaPi</code> , or <code>DM</code> must be included in <code>covNames</code> . |
| spatialCovs | List of raster layer(s) for any spatial covariates. See prepData . |
| centers | 2-column matrix providing the x-coordinates (column 1) and y-coordinates (column 2) for any activity centers (e.g., potential centers of attraction or repulsion) from which distance and angle covariates will be calculated based on realizations of the position process. See prepData . Ignored unless <code>miData</code> is a crwData object. |
| centroids | List where each element is a data frame containing the x-coordinates (‘x’), y-coordinates (‘y’), and times (with user-specified name, e.g., ‘time’) for centroids (i.e., dynamic activity centers where the coordinates can change over time) from which distance and angle covariates will be calculated based on the location data. See prepData . Ignored unless <code>miData</code> is a crwData object. |
| angleCovs | Character vector indicating the names of any circular-circular regression angular covariates in <code>miData\$crwPredict</code> that need conversion from standard direction (in radians relative to the x-axis) to turning angle (relative to previous movement direction) See prepData . Ignored unless <code>miData</code> is a crwData or crwHierData object. |
| altCoordNames | Character string indicating an alternative name for the returned location data. See prepData . Ignored unless <code>miData</code> is a crwData or crwHierData object. |
| gradient | Logical indicating whether or not to calculate gradients of <code>spatialCovs</code> using bilinear interpolation (e.g. for inclusion in potential functions). Ignored unless <code>miData</code> is a crwData or crwHierData object. See prepData . Default: FALSE. |
| smoothGradient | Logical indicating whether or not to calculate smoothed gradients. See addSmoothGradient . Ignored unless <code>gradient=TRUE</code> . Default: FALSE. |
| weights | Numeric vector indicating the weight for the points in a smoothed version of the gradient. See addSmoothGradient . Ignored unless <code>smoothGradient=TRUE</code> . Default: <code>c(1/2, 1/8, 1/8, 1/8, 1/8)</code> . |
| scaleGrad | Numeric scalar indicating the distance from the observed location to each smoothing point. See addSmoothGradient . Ignored unless <code>smoothGradient=TRUE</code> . |
| method | Method for obtaining weights for movement parameter samples. See crwSimulator . Ignored unless <code>miData</code> is a crwData object. |

| | |
|------------------|---|
| parIS | Size of the parameter importance sample. See crwSimulator . Ignored unless miData is a crwData object. |
| dfSim | Degrees of freedom for the t approximation to the parameter posterior. See 'df' argument in crwSimulator . Ignored unless miData is a crwData object. |
| grid.eps | Grid size for method="quadrature". See crwSimulator . Ignored unless miData is a crwData object. |
| crit | Criterion for deciding "significance" of quadrature points (difference in log-likelihood). See crwSimulator . Ignored unless miData is a crwData object. |
| scaleSim | Scale multiplier for the covariance matrix of the t approximation. See 'scale' argument in crwSimulator . Ignored unless miData is a crwData object. |
| quad.ask | Logical, for method='quadrature'. Whether or not the sampler should ask if quadrature sampling should take place. It is used to stop the sampling if the number of likelihood evaluations would be extreme. Default: FALSE. Ignored if ncores>1. |
| force.quad | A logical indicating whether or not to force the execution of the quadrature method for large parameter vectors. See crwSimulator . Default: TRUE. Ignored unless miData is a crwData object and method='`quadrature`'. |
| fullPost | Logical indicating whether to draw parameter values as well to simulate full posterior. See crwPostIS . Ignored unless miData is a crwData object. |
| dfPostIS | Degrees of freedom for multivariate t distribution approximation to parameter posterior. See 'df' argument in crwPostIS . Ignored unless miData is a crwData object. |
| scalePostIS | Extra scaling factor for t distribution approximation. See 'scale' argument in crwPostIS . Ignored unless miData is a crwData object. |
| thetaSamp | If multiple parameter samples are available in crwSimulator objects, setting thetaSamp=n will use the nth sample. Defaults to the last. See crwSimulator and crwPostIS . Ignored unless miData is a crwData object. |
| export | Character vector of the names of any additional objects or functions in the global environment that are used in DM, formula, formulaDelta, and/or formulaPi. Only necessary if ncores>1 so that the needed items will be exported to the workers. |
| hierStates | A hierarchical model structure Node for the states. See fithMM . |
| hierDist | A hierarchical data structure Node for the data streams. See fithMM . |
| hierBeta | A hierarchical data structure Node for the matrix of initial values for the regression coefficients of the transition probabilities at each level of the hierarchy ('beta'). See fithMM . |
| hierDelta | A hierarchical data structure Node for the matrix of initial values for the regression coefficients of the initial distribution at each level of the hierarchy ('delta'). See fithMM . |
| hierFormula | A hierarchical formula structure for the transition probability covariates for each level of the hierarchy. See fithMM . |
| hierFormulaDelta | A hierarchical formula structure for the initial distribution covariates for each level of the hierarchy ('formulaDelta'). Default: NULL (no covariate effects and fixPar\$delta is specified on the working scale). See fithMM . |

Details

miData can either be a `crwData` or `crwHierData` object (as returned by `crawlWrap`), a `crwSim` or `crwHierSim` object (as returned by `MIfitHMM` when `fit=FALSE`), or a list of `momentuHMMData` or `momentuHierHMMData` objects (e.g., each element of the list as returned by `prepData`).

If miData is a `crwData` (or `crwHierData`) object, `MIfitHMM` uses a combination of `crwSimulator`, `crwPostIS`, `prepData`, and `fitHMM` to draw `nSims` realizations of the position process and fit the specified HMM to each imputation of the data. The vast majority of `MIfitHMM` arguments are identical to the corresponding arguments from these functions.

If miData is a `crwData` or `crwHierData` object, `nSims` determines both the number of realizations of the position process to draw (using `crwSimulator` and `crwPostIS`) as well as the number of HMM fits.

If miData is a `crwSim` (or `crwHierSim`) object or a list of `momentuHMMData` (or `momentuHierHMMData`) object(s), the specified HMM will simply be fitted to each of the `momentuHMMData` (or `momentuHierHMMData`) objects and all arguments related to `crwSimulator`, `crwPostIS`, or `prepData` are ignored.

Value

If `nSims>1`, `poolEstimates=TRUE`, and `fit=TRUE`, a `miHMM` object, i.e., a list consisting of:

`miSum` `miSum` object returned by `MIpool`.

`HMMfits` List of length `nSims` comprised of `momentuHMM` objects.

If `poolEstimates=FALSE` and `fit=TRUE`, a list of length `nSims` consisting of `momentuHMM` objects is returned.

However, if `fit=FALSE` and miData is a `crwData` object, then `MIfitHMM` returns a `crwSim` object, i.e., a list containing miData (a list of `momentuHMMData` objects) and `crwSimulator` (a list of `crwSimulator` objects), and most other arguments related to `fitHMM` are ignored.

References

Hooten M.B., Johnson D.S., McClintock B.T., Morales J.M. 2017. Animal Movement: Statistical Models for Telemetry Data. CRC Press, Boca Raton.

McClintock B.T. 2017. Incorporating telemetry error into hidden Markov movement models using multiple imputation. Journal of Agricultural, Biological, and Environmental Statistics.

See Also

`crawlWrap`, `crwPostIS`, `crwSimulator`, `fitHMM`, `getParDM`, `MIpool`, `prepData`

Examples

```
# Don't run because it takes too long on a single core
## Not run:
# extract simulated obsData from example data
obsData <- miExample$obsData

# error ellipse model
err.model <- list(x= ~ ln.sd.x - 1, y = ~ ln.sd.y - 1, rho = ~ error.corr)
```

```

# create crwData object by fitting crwMLE models to obsData and predict locations
# at default intervals for both individuals
crwOut <- crawlWrap(obsData=obsData,
  theta=c(4,0),fixPar=c(1,1,NA,NA),
  err.model=err.model)

# HMM specifications
nbStates <- 2
stepDist <- "gamma"
angleDist <- "vm"
mu0 <- c(20,70)
sigma0 <- c(10,30)
kappa0 <- c(1,1)
stepPar0 <- c(mu0,sigma0)
anglePar0 <- c(-pi/2,pi/2,kappa0)
formula <- ~cov1+cos(cov2)
nbCovs <- 2
beta0 <- matrix(c(rep(-1.5,nbStates*(nbStates-1)),rep(0,nbStates*(nbStates-1)*nbCovs)),
  nrow=nbCovs+1,byrow=TRUE)

# first fit HMM to best predicted position process
bestData<-prepData(crwOut,covNames=c("cov1","cov2"))
bestFit<-fitHMM(bestData,
  nbStates=nbStates,dist=list(step=stepDist,angle=angleDist),
  Par0=list(step=stepPar0,angle=anglePar0),beta0=beta0,
  formula=formula,estAngleMean=list(angle=TRUE))

print(bestFit)

# extract estimates from 'bestFit'
bPar0 <- getPar(bestFit)

# Fit nSims=5 imputations of the position process
miFits<-MIfitHMM(miData=crwOut,nSims=5,
  nbStates=nbStates,dist=list(step=stepDist,angle=angleDist),
  Par0=bPar0$Par,beta0=bPar0$beta,delta0=bPar0$delta,
  formula=formula,estAngleMean=list(angle=TRUE),
  covNames=c("cov1","cov2"))

# print pooled estimates
print(miFits)

## End(Not run)

```

miHMM

Constructor of miHMM objects

Description

Constructor of miHMM objects

Usage

```
miHMM(m)
```

Arguments

m A list with attributes `miSum` (a `miSum` object) and `HMMfits` (a list of `momentuHMM` objects).
`miHMM` objects are returned by `MIfitHMM` when arguments `fit=TRUE`, `nSims>1`, and `poolEstimates=TRUE`.

Value

An object `miHMM`.

| | |
|--------|--|
| MIpool | <i>Calculate pooled parameter estimates and states across multiple imputations</i> |
|--------|--|

Description

Calculate pooled parameter estimates and states across multiple imputations

Usage

```
MIpool(im, alpha = 0.95, ncores = 1, covs = NULL, na.rm = FALSE)
```

Arguments

im List comprised of `momentuHMM` or `momentuHierHMM` objects

alpha Significance level for calculating confidence intervals of pooled estimates (including location error ellipses). Default: 0.95.

ncores Number of cores to use for parallel processing. Default: 1 (no parallel processing).

covs Data frame consisting of a single row indicating the covariate values to be used in the calculation of pooled natural parameters. For any covariates that are not specified using `covs`, the means of the covariate(s) across the imputations are used (unless the covariate is a factor, in which case the first factor in the data is used). By default, no covariates are specified.

na.rm Logical indicating whether or not to exclude model fits with NA parameter estimates or standard errors from pooling. Default: FALSE.

Details

Pooled estimates, standard errors, and confidence intervals are calculated using standard multiple imputation formulas. Working scale parameters are pooled using [MIcombine](#) and t-distributed confidence intervals. Natural scale parameters and normally-distributed confidence intervals are calculated by transforming the pooled working scale parameters and, if applicable, are based on covariate means across all imputations (and/or values specified in covs).

The calculation of pooled error ellipses uses [dataEllipse](#) from the `car` package. The suggested package `car` is not automatically imported by `momentuHMM` and must be installed in order to calculate error ellipses. A warning will be triggered if the `car` package is required but not installed.

Note that pooled estimates for `timeInStates` and `stateProbs` do not include within-model uncertainty and are based entirely on across-model variability.

Value

A `miSum` object, i.e., a list comprised of model and pooled parameter summaries, including data (averaged across imputations), conditions, `Par`, and `MIcombine` (as returned by [MIcombine](#) for working parameters).

`miSum$Par` is a list comprised of:

| | |
|-----------------------------|---|
| <code>beta</code> | Pooled estimates for the working parameters |
| <code>real</code> | Estimates for the natural parameters based on pooled working parameters and covariate means (or covs) across imputations (if applicable) |
| <code>timeInStates</code> | The proportion of time steps assigned to each state |
| <code>states</code> | The most frequent state assignment for each time step based on the viterbi algorithm for each model fit |
| <code>stateProbs</code> | Pooled state probability estimates for each time step |
| <code>mixtureProbs</code> | Pooled mixture probabilities for each individual (only applies if <code>mixtures>1</code>) |
| <code>hierStateProbs</code> | Pooled state probability estimates for each time step at each level of the hierarchy (only applies if <code>im</code> is comprised of momentuHierHMM objects) |

Examples

```
## Not run:
# Extract data and crawl inputs from miExample
obsData <- miExample$obsData

# error ellipse model
err.model <- list(x= ~ ln.sd.x - 1, y = ~ ln.sd.y - 1, rho = ~ error.corr)

# Fit crawl to obsData
crwOut <- crawlWrap(obsData, theta=c(4,0), fixPar=c(1,1,NA,NA),
                    err.model=err.model)

# Fit four imputations
bPar <- miExample$bPar
HMMfits <- MIfitHMM(crwOut, nSims=4, poolEstimates=FALSE,
                    nbStates=2, dist=list(step="gamma", angle="vm"),
```

```

Par0=bPar$Par,beta0=bPar$beta,
formula=~cov1+cos(cov2),
estAngleMean=list(angle=TRUE),
covNames=c("cov1","cov2"))

# Pool estimates
miSum <- MIpool(HMMfits)
print(miSum)

## End(Not run)

```

| | |
|-------|-------------------------------------|
| miSum | <i>Constructor of miSum objects</i> |
|-------|-------------------------------------|

Description

Constructor of miSum objects

Usage

```
miSum(m)
```

Arguments

| | |
|---|---|
| m | A list of attributes required for multiple imputation summaries: data (averaged across imputations), Par (the pooled estimates of the parameters of the model), conditions (conditions used to fit the model), and MIcombine (as returned by MIcombine for the working parameters). |
|---|---|

Value

An object miSum.

| | |
|--------------|------------------------------|
| mixtureProbs | <i>Mixture probabilities</i> |
|--------------|------------------------------|

Description

For a fitted model, this function computes the probability of each individual being in a particular mixture

Usage

```
mixtureProbs(m, getCI = FALSE, alpha = 0.95)
```


Arguments

| | |
|-------|--|
| m | momentuHMM or momentuHierHMM object |
| getCI | Logical indicating whether to calculate standard errors and logit-transformed confidence intervals for fitted momentuHMM or momentuHierHMM object. Default: FALSE. |
| alpha | Significance level of the confidence intervals (if getCI=TRUE). Default: 0.95 (i.e. 95% CIs). |

Details

When getCI=TRUE, it can take a while for large data sets and/or a large number of mixtures because the model likelihood for each individual must be repeatedly evaluated in order to numerically approximate the SEs.

Value

The matrix of individual mixture probabilities, with element [i,j] the probability of individual i being in mixture j

References

Maruotti, A., and T. Ryden. 2009. A semiparametric approach to hidden Markov models under longitudinal observations. *Statistics and Computing* 19: 381-393.

Examples

```
## Not run:
nObs <- 100
nbAnimals <- 20
dist <- list(step="gamma",angle="vm")
Par <- list(step=c(100,1000,50,100),angle=c(0,0,0.1,2))

# create sex covariate
cov <- data.frame(sex=factor(rep(c("F","M"),each=nObs*nbAnimals/2)))
formulaPi <- ~ sex + 0

# Females more likely in mixture 1, males more likely in mixture 2
beta <- list(beta=matrix(c(-1.5,-0.5,-1.5,-3),2,2),
             pi=matrix(c(-2,2),2,1,dimnames=list(c("sexF","sexM"),"mix2")))

data.mix<-simData(nbAnimals=nbAnimals,obsPerAnimal=nObs,nbStates=2,dist=dist,Par=Par,
                 beta=beta,formulaPi=formulaPi,mixtures=2,covs=cov)

Par0 <- list(step=Par$step, angle=Par$angle[3:4])
m.mix <- fitHMM(data.mix, nbStates=2, dist=dist, Par0 = Par0,
               beta0=beta,formulaPi=formulaPi,mixtures=2)

mixProbs <- mixtureProbs(m.mix, getCI=TRUE)

## End(Not run)
```

| | |
|----------------|--|
| momentuHierHMM | <i>Constructor of momentuHierHMM objects</i> |
|----------------|--|

Description

Constructor of momentuHierHMM objects

Usage

```
momentuHierHMM(m)
```

Arguments

| | |
|---|--|
| m | A list of attributes of the fitted model: mle (the maximum likelihood estimates of the parameters of the model), data (the fitHMM data), mod (the object returned by the fitHMM numerical optimizer nlm or optim), conditions (conditions used to fit the model: hierStates, hierDist, zeroInflation, estAngleMean, circularAngleMean stationary, formula, userBounds, bounds, workBounds, DM, etc.), stateNames, and rawCovs (optional – only if there are transition probability matrix covariates in the data). |
|---|--|

Value

An object momentuHierHMM.

| | |
|--------------------|--|
| momentuHierHMMData | <i>Constructor of momentuHierHMMData objects</i> |
|--------------------|--|

Description

Constructor of momentuHierHMMData objects

Usage

```
momentuHierHMMData(data)
```

Arguments

| | |
|------|---|
| data | A dataframe containing: ID (the ID(s) of the observed animal(s)), level (the level of the hierarchy for each observation), and the data streams such as step (the step lengths, if any), angle (the turning angles, if any), x (either easting or longitude, if any), y (either northing or latitude, if any), and covariates (if any). |
|------|---|

Value

An object momentuHierHMMData.

| | |
|------------|--|
| momentuHMM | <i>Constructor of momentuHMM objects</i> |
|------------|--|

Description

Constructor of momentuHMM objects

Usage

```
momentuHMM(m)
```

Arguments

| | |
|---|--|
| m | A list of attributes of the fitted model: mle (the maximum likelihood estimates of the parameters of the model), data (the fitHMM data), mod (the object returned by the fitHMM numerical optimizer nlm or optim), conditions (conditions used to fit the model: dist, zeroInflation, estAngleMean, circularAngleMean stationary, formula, userBounds, bounds, workBounds, DM, etc.), stateNames, and rawCovs (optional – only if there are transition probability matrix covariates in the data). |
|---|--|

Value

An object momentuHMM.

| | |
|----------------|--|
| momentuHMMData | <i>Constructor of momentuHMMData objects</i> |
|----------------|--|

Description

Constructor of momentuHMMData objects

Usage

```
momentuHMMData(data)
```

Arguments

| | |
|------|---|
| data | A dataframe containing: ID (the ID(s) of the observed animal(s)) and the data streams such as step (the step lengths, if any), angle (the turning angles, if any), x (either easting or longitude, if any), y (either northing or latitude, if any), and covariates (if any). |
|------|---|

Value

An object momentuHMMData.

n2w

*Scaling function: natural to working parameters.***Description**

Scales each data stream probability distribution parameter from its natural interval to the set of real numbers, to allow for unconstrained optimization. Used during the optimization of the log-likelihood. Parameters of any data streams for which a design matrix is specified are ignored.

Usage

```
n2w(
  par,
  bounds,
  beta,
  delta = NULL,
  nbStates,
  estAngleMean,
  DM,
  Bndind,
  dist,
  TMB = FALSE
)
```

Arguments

| | |
|--------------|--|
| par | Named list of vectors containing the initial parameter values for each data stream. |
| bounds | Named list of 2-column matrices specifying bounds on the natural (i.e, real) scale of the probability distribution parameters for each data stream. |
| beta | List of regression coefficients for the transition probabilities. |
| delta | Initial distribution. Default: NULL ; if the initial distribution is not estimated. |
| nbStates | The number of states of the HMM. |
| estAngleMean | Named list indicating whether or not to estimate the angle mean for data streams with angular distributions ('vm' and 'wrpcauchy'). |
| DM | An optional named list indicating the design matrices to be used for the probability distribution parameters of each data stream. Each element of DM can either be a named list of linear regression formulas or a matrix. |
| Bndind | Named list indicating whether DM is NULL with default parameter bounds for each data stream. |
| dist | A named list indicating the probability distributions of the data streams. |
| TMB | logical indicating whether or not optMethod='TMB'. Default: FALSE. |

Value

A vector of unconstrained parameters.

Examples

```
## Not run:
m<-example$m
nbStates <- 2
nbCovs <- 2
parSize <- list(step=2,angle=2)
par <- list(step=c(t(m$mle$step)),angle=c(t(m$mle$angle)))
bounds <- m$conditions$bounds
beta <- matrix(rnorm(6),ncol=2,nrow=3)
delta <- c(0.6,0.4)

#working parameters
wpar <- momentuHMM:::w2w(par,bounds,list(beta=beta),log(delta[-1]/delta[1]),nbStates,
m$conditions$estAngleMean,NULL,m$conditions$Bndind,
m$conditions$dist)

#natural parameter
p <- momentuHMM:::w2n(wpar,bounds,parSize,nbStates,nbCovs,m$conditions$estAngleMean,
m$conditions$circularAngleMean,lapply(m$conditions$dist,function(x) x=="vmConsensus"),
m$conditions$stationary,m$conditions$fullDM,
m$conditions$DMind,1,m$conditions$dist,m$conditions$Bndind,
matrix(1,nrow=length(unique(m$data$ID)),ncol=1),covsDelta=m$covsDelta,
workBounds=m$conditions$workBounds)

## End(Not run)
```

nLogLike

Negative log-likelihood function

Description

Negative log-likelihood function

Usage

```
nLogLike(
  optPar,
  nbStates,
  formula,
  bounds,
  parSize,
  data,
  dist,
  covs,
  estAngleMean,
  circularAngleMean,
  consensus,
```

```

zeroInflation,
oneInflation,
stationary = FALSE,
fullDM,
DMind,
Bndind,
knownStates,
fixPar,
wparIndex,
nc,
meanind,
covsDelta,
workBounds,
prior = NULL,
betaCons = NULL,
betaRef,
deltaCons = NULL,
optInd = NULL,
recovs = NULL,
g0covs = NULL,
mixtures = 1,
covsPi,
recharge = NULL,
aInd = aInd,
CT = FALSE,
dtIndex = NULL,
kappa = Inf,
crwST = FALSE
)

```

Arguments

| | |
|--------------|---|
| optPar | Vector of working parameters. |
| nbStates | Number of states of the HMM. |
| formula | Regression formula for the transition probability covariates. |
| bounds | Named list of 2-column matrices specifying bounds on the natural (i.e, real) scale of the probability distribution parameters for each data stream. |
| parSize | Named list indicating the number of natural parameters of the data stream probability distributions |
| data | An object momentuHMMData. |
| dist | Named list indicating the probability distributions of the data streams. |
| covs | data frame containing the beta model covariates (if any) |
| estAngleMean | Named list indicating whether or not to estimate the angle mean for data streams with angular distributions ('vm' and 'wrpcauchy'). |

| | |
|-------------------|---|
| circularAngleMean | Named list indicating whether to use circular-linear or circular-circular regression on the mean of circular distributions ('vm' and 'wrpcauchy') for turning angles. See fitHMM . |
| consensus | Named list indicating whether to use the circular-circular regression consensus model |
| zeroInflation | Named list of logicals indicating whether the probability distributions of the data streams are zero-inflated. |
| oneInflation | Named list of logicals indicating whether the probability distributions of the data streams are one-inflated. |
| stationary | FALSE if there are time-varying covariates in formula or any covariates in formulaDelta. If TRUE, the initial distribution is considered equal to the stationary distribution. Default: FALSE. |
| fullDM | Named list containing the full (i.e. not shorthand) design matrix for each data stream. |
| DMind | Named list indicating whether fullDM includes individual- and/or temporal-covariates for each data stream specifies (-1,1) bounds for the concentration parameters instead of the default [0,1) bounds. |
| Bndind | Named list indicating whether DM is NULL with default parameter bounds for each data stream. |
| knownStates | Vector of values of the state process which are known prior to fitting the model (if any). |
| fixPar | Vector of working parameters which are assumed known prior to fitting the model (NA indicates parameters is to be estimated). |
| wparIndex | Vector of indices for the elements of fixPar that are not NA. |
| nc | indicator for zeros in fullDM |
| meanind | index for circular-circular regression mean angles with at least one non-zero entry in fullDM |
| covsDelta | data frame containing the delta model covariates (if any) |
| workBounds | named list of 2-column matrices specifying bounds on the working scale of the probability distribution, transition probability, and initial distribution parameters |
| prior | A function that returns the log-density of the working scale parameter prior distribution(s) |
| betaCons | Matrix of the same dimension as beta0 composed of integers identifying any equality constraints among the t.p.m. parameters. |
| betaRef | Indices of reference elements for t.p.m. multinomial logit link. |
| deltaCons | Matrix of the same dimension as delta0 composed of integers identifying any equality constraints among the initial distribution working scale parameters. |
| optInd | indices of constrained parameters |
| recovs | data frame containing the recharge model theta covariates (if any) |
| g0covs | data frame containing the recharge model g0 covariates (if any) |
| mixtures | Number of mixtures for the state transition probabilities |

| | |
|----------|---|
| covsPi | data frame containing the pi model covariates |
| recharge | recharge model specification (only used for hierarchical models) |
| aInd | vector of indices of first observation for each animal |
| CT | logical indicating whether to fit discrete-time approximation of a continuous-time model |
| dtIndex | time difference index for calculating transition probabilities of hierarchical continuous-time models |
| kappa | maximum allowed value for the row sums of the off-diagonal elements in the state transition rate matrix, such that the minimum value for the diagonal elements is $-\text{kappa}$. Default: Inf. Setting less than Inf can help avoid numerical issues during optimization, in which case the transition rate parameters beta are on the logit scale (instead of the log scale). Ignored unless CT=TRUE. |
| crwST | logical indicating whether to fit a correlated step and turn random walk model |

Value

The negative log-likelihood of the parameters given the data.

Examples

```
## Not run:
# data is a momentuHMMData object (as returned by prepData), automatically loaded with the package
data <- example$m$data
m <- example$m
Par <- getPar(m)
nbStates <- length(m$stateNames)

inputs <- momentuHMM:::checkInputs(nbStates, m$conditions$dist, Par$Par, m$conditions$estAngleMean,
  m$conditions$circularAngleMean, m$conditions$zeroInflation, m$conditions$oneInflation,
  m$conditions$DM, m$conditions$userBounds,
  m$stateNames)

wpar <- momentuHMM:::n2w(Par$Par, m$conditions$bounds, list(beta=Par$beta),
  log(Par$delta[-1]/Par$delta[1]), nbStates, m$conditions$estAngleMean,
  m$conditions$DM, m$conditions$Bndind,
  m$conditions$dist)

l <- momentuHMM:::nLogLike(wpar, nbStates, m$conditions$formula, m$conditions$bounds,
  inputs$p$parSize, data, inputs$dist, model.matrix(m$conditions$formula, data),
  m$conditions$estAngleMean, m$conditions$circularAngleMean, inputs$consensus,
  m$conditions$zeroInflation, m$conditions$oneInflation, m$conditions$stationary,
  m$conditions$fullDM, m$conditions$DMind,
  m$conditions$Bndind, m$knownStates, unlist(m$conditions$fixPar),
  m$conditions$wparIndex, covsDelta=m$covsDelta, workBounds=m$conditions$workBounds,
  betaRef=m$conditions$betaRef, covsPi=m$covsPi)

## End(Not run)
```

nLogLike_rcpp

Negative log-likelihood

Description

Computation of the negative log-likelihood (forward algorithm - written in C++)

Usage

```
nLogLike_rcpp(
  nbStates,
  covs,
  data,
  dataNames,
  dist,
  Par,
  aInd,
  zeroInflation,
  oneInflation,
  stationary,
  knownStates,
  betaRef,
  mixtures,
  dtIndex,
  CT = FALSE,
  kappa = NA_real_
)
```

Arguments

| | |
|---------------|--|
| nbStates | Number of states, |
| covs | Covariates, |
| data | A momentuHMMData object of the observations, |
| dataNames | Character vector containing the names of the data streams, |
| dist | Named list indicating the probability distributions of the data streams. |
| Par | Named list containing the state-dependent parameters of the data streams, matrix of regression coefficients for the transition probabilities ('beta'), and initial distribution ('delta'). |
| aInd | Vector of indices of the rows at which the data switches to another animal |
| zeroInflation | Named list of logicals indicating whether the probability distributions of the data streams are zero-inflated. |
| oneInflation | Named list of logicals indicating whether the probability distributions of the data streams are one-inflated. |

| | |
|-------------|---|
| stationary | false if there are time-varying covariates in formula or any covariates in formulaDelta. If true, the initial distribution is considered equal to the stationary distribution. Default: false. |
| knownStates | Vector of values of the state process which are known prior to fitting the model (if any). Default: NULL (states are not known). This should be a vector with length the number of rows of 'data'; each element should either be an integer (the value of the known states) or NA if the state is not known. |
| betaRef | Indices of reference elements for t.p.m. multinomial logit link. |
| mixtures | Number of mixtures for the state transition probabilities |
| dtIndex | time difference index for calculating transition probabilities of hierarchical continuous-time models |
| CT | logical indicating whether to fit discrete-time approximation of a continuous-time model |
| kappa | maximum allowed value for the row sums of the off-diagonal elements in the state transition rate matrix, such that the minimum value for the diagonal elements is -kappa. Default: Inf. Setting less than Inf can help avoid numerical issues during optimization, in which case the transition rate parameters beta are on the logit scale (instead of the log scale). |

Value

Negative log-likelihood

parDef

Parameters definition

Description

Parameters definition

Usage

```
parDef(
  dist,
  nbStates,
  estAngleMean,
  zeroInflation,
  oneInflation,
  DM,
  userBounds = NULL
)
```

Arguments

| | |
|---------------|---|
| dist | Named list indicating the probability distributions of the data streams. |
| nbStates | Number of states of the HMM. |
| estAngleMean | Named list indicating whether or not to estimate the angle mean for data streams with angular distributions ('vm' and 'wrpcauchy'). |
| zeroInflation | Named list of logicals indicating whether the probability distributions of the data streams should be zero-inflated. |
| oneInflation | Named list of logicals indicating whether the probability distributions of the data streams are one-inflated. |
| DM | An optional named list indicating the design matrices to be used for the probability distribution parameters of each data stream. Each element of DM can either be a named list of linear regression formulas or a matrix. |
| userBounds | An optional named list of 2-column matrices specifying bounds on the natural (i.e, real) scale of the probability distribution parameters for each data stream. For example, for a 2-state model using the wrapped Cauchy ('wrpcauchy') distribution for a data stream named 'angle' with estAngleMean\$angle=TRUE), userBounds=list(angle=matrix(c(-pi, -pi, -1, -1, pi, pi, 1, 1), 4, 2)) specifies (-1,1) bounds for the concentration parameters instead of the default [0,1) bounds. |

Value

A list of:

| | |
|----------|---|
| parSize | Named list indicating the number of natural parameters of the data stream probability distributions. |
| bounds | Named list of 2-column matrices specifying bounds on the natural (i.e, real) scale of the probability distribution parameters for each data stream. |
| parNames | Names of parameters of the probability distribution for each data stream. |
| Bndind | Named list indicating whether DM is NULL with default parameter bounds for each data stream. |

Examples

```
## Not run:
pD<-momentuHMM:::parDef(list(step="gamma", angle="wrpcauchy"),
  nbStates=2, list(step=FALSE, angle=FALSE), list(step=FALSE, angle=FALSE),
  list(step=FALSE, angle=FALSE), NULL, NULL)

## End(Not run)
```

| | |
|--------------|---------------------|
| plot.crwData | <i>Plot</i> crwData |
|--------------|---------------------|

Description

Plot observed locations, error ellipses (if applicable), predicted locations, and prediction intervals from [crwData](#) or [crwHierData](#) object.

Usage

```
## S3 method for class 'crwData'
plot(
  x,
  animals = NULL,
  compact = FALSE,
  ask = TRUE,
  plotEllipse = TRUE,
  crawlPlot = FALSE,
  ...
)
```

Arguments

| | |
|-------------|--|
| x | An object crwData or crwHierData (as returned by crawlWrap). |
| animals | Vector of indices or IDs of animals for which information will be plotted. Default: NULL ; all animals are plotted. |
| compact | TRUE for a compact plot (all individuals at once), FALSE otherwise (default – one individual at a time). Ignored unless crwPredictPlot =FALSE. |
| ask | If TRUE, the execution pauses between each plot. |
| plotEllipse | If TRUE (the default) then error ellipses are plotted (if applicable). Ignored unless crwPredictPlot =FALSE. |
| crawlPlot | Logical indicating whether or not to create individual plots using crwPredictPlot . See crwPredictPlot for details. |
| ... | Further arguments for passing to crwPredictPlot |

Details

In order for error ellipses to be plotted, the names for the semi-major axis, semi-minor axis, and orientation in `x$crwPredict` must respectively be `error_semimajor_axis`, `error_semiminor_axis`, and `error_ellipse_orientation`.

If the [crwData](#) (or [crwHierData](#)) object was created using data generated by [simData](#) (or [simHierData](#)) or [simObsData](#), then the true locations (`mux,muy`) are also plotted.

See Also

[crwPredictPlot](#)

Examples

```
## Not run:
# extract simulated obsData from example data
obsData <- miExample$obsData

# error ellipse model
err.model <- list(x= ~ ln.sd.x - 1, y = ~ ln.sd.y - 1, rho = ~ error.corr)

# create crwData object
crwOut <- crawlWrap(obsData=obsData,
                    theta=c(4,0), fixPar=c(1,1,NA,NA),
                    err.model=err.model)

plot(crwOut, compact=TRUE, ask=FALSE, plotEllipse=FALSE)

## End(Not run)
```

plot.miHMM

Plot miHMM

Description

For multiple imputation analyses, plot the pooled data stream densities over histograms of the data, probability distribution parameters and transition probabilities as functions of the covariates, and maps of the animals' tracks colored by the decoded states.

Usage

```
## S3 method for class 'miHMM'
plot(
  x,
  animals = NULL,
  covs = NULL,
  ask = TRUE,
  breaks = "Sturges",
  hist.ylim = NULL,
  sepAnimals = FALSE,
  sepStates = FALSE,
  col = NULL,
  cumul = TRUE,
  plotTracks = TRUE,
  plotCI = FALSE,
  alpha = 0.95,
  plotStationary = FALSE,
  plotEllipse = TRUE,
  return = FALSE,
  ...
)
```

Arguments

| | |
|----------------|--|
| x | Object miHMM (as returned by <code>MifitHMM</code>) |
| animals | Vector of indices or IDs of animals for which information will be plotted. Default: NULL ; all animals are plotted. |
| covs | Data frame consisting of a single row indicating the covariate values to be used in plots. If none are specified, the means of any covariates appearing in the model are used (unless covariate is a factor, in which case the first factor appearing in the data is used). |
| ask | If TRUE, the execution pauses between each plot. |
| breaks | Histogram parameter. See <code>hist</code> documentation. |
| hist.ylim | Parameter <code>ylim</code> for the step length histograms. See <code>hist</code> documentation. Default: NULL ; the function sets default values. |
| sepAnimals | If TRUE, the data is split by individuals in the histograms. Default: FALSE. |
| sepStates | If TRUE, the data is split by states in the histograms. Default: FALSE. |
| col | Vector or colors for the states (one color per state). |
| cumul | If TRUE, the sum of weighted densities is plotted (default). |
| plotTracks | If TRUE, the Viterbi-decoded tracks are plotted (default). |
| plotCI | Logical indicating whether to include confidence intervals in natural parameter plots (default: FALSE) |
| alpha | Significance level of the confidence intervals (if <code>plotCI=TRUE</code>). Default: 0.95 (i.e. 95% CIs). |
| plotStationary | Logical indicating whether to plot the stationary state probabilities as a function of any covariates (default: FALSE) |
| plotEllipse | Logical indicating whether to plot error ellipses around imputed location means. Default: TRUE. |
| return | Logical indicating whether to return a list containing estimates, SEs, CIs, and covariate values used to create the plots for each mixture and state. Ignored if <code>plotCI=FALSE</code> . Default: FALSE. |
| ... | Additional arguments passed to <code>graphics::plot</code> and <code>graphics::hist</code> functions. These can currently include <code>asp</code> , <code>cex</code> , <code>cex.axis</code> , <code>cex.lab</code> , <code>cex.legend</code> , <code>cex.main</code> , <code>legend.pos</code> , and <code>lwd</code> . See <code>par</code> . <code>legend.pos</code> can be a single keyword from the list “bottomright”, “bottom”, “bottomleft”, “left”, “topleft”, “top”, “topright”, “right”, and “center”. Note that <code>asp</code> and <code>cex</code> only apply to plots of animal tracks. |

Details

The state-dependent densities are weighted by the frequency of each state in the most probable state sequence (decoded with the function `viterbi` for each imputation). For example, if the most probable state sequence indicates that one third of observations correspond to the first state, and two thirds to the second state, the plots of the densities in the first state are weighted by a factor $1/3$, and in the second state by a factor $2/3$.

Examples

```
## Not run:
# Extract data from miExample
obsData <- miExample$obsData

# error ellipse model
err.model <- list(x= ~ ln.sd.x - 1, y = ~ ln.sd.y - 1, rho = ~ error.corr)

# Fit crawl to obsData
crwOut <- crawlWrap(obsData,theta=c(4,0),fixPar=c(1,1,NA,NA),
                    err.model=err.model)

# Fit four imputations
bPar <- miExample$bPar
HMMfits <- MIfitHMM(crwOut,nSims=4,poolEstimates=FALSE,
                   nbStates=2,dist=list(step="gamma",angle="vm"),
                   Par0=bPar$Par,beta0=bPar$beta,
                   formula=~cov1+cos(cov2),
                   estAngleMean=list(angle=TRUE),
                   covNames=c("cov1","cov2"))

miHMM <- momentuHMM:::miHMM(list(miSum=MIPool(HMMfits),HMMfits=HMMfits))
plot(miHMM)

## End(Not run)
```

plot.miSum

Plot miSum

Description

Plot the fitted step and angle densities over histograms of the data, transition probabilities as functions of the covariates, and maps of the animals' tracks colored by the decoded states.

Usage

```
## S3 method for class 'miSum'
plot(
  x,
  animals = NULL,
  covs = NULL,
  ask = TRUE,
  breaks = "Sturges",
  hist.ylim = NULL,
  sepAnimals = FALSE,
  sepStates = FALSE,
  col = NULL,
  cumul = TRUE,
```

```

    plotTracks = TRUE,
    plotCI = FALSE,
    alpha = 0.95,
    plotStationary = FALSE,
    plotEllipse = TRUE,
    return = FALSE,
    ...
)

```

Arguments

| | |
|----------------|---|
| x | Object miSum (as return by MIpool) |
| animals | Vector of indices or IDs of animals for which information will be plotted. Default: NULL ; all animals are plotted. |
| covs | Data frame consisting of a single row indicating the covariate values to be used in plots. If none are specified, the means of any covariates appearing in the model are used (unless covariate is a factor, in which case the first factor appearing in the data is used). |
| ask | If TRUE, the execution pauses between each plot. |
| breaks | Histogram parameter. See hist documentation. |
| hist.ylim | Parameter ylim for the step length histograms. See hist documentation. Default: NULL ; the function sets default values. |
| sepAnimals | If TRUE, the data is split by individuals in the histograms. Default: FALSE. |
| sepStates | If TRUE, the data is split by states in the histograms. Default: FALSE. |
| col | Vector or colors for the states (one color per state). |
| cumul | If TRUE, the sum of weighted densities is plotted (default). |
| plotTracks | If TRUE, the Viterbi-decoded tracks are plotted (default). |
| plotCI | Logical indicating whether to include confidence intervals in natural parameter plots (default: FALSE) |
| alpha | Significance level of the confidence intervals (if plotCI=TRUE). Default: 0.95 (i.e. 95% CIs). |
| plotStationary | Logical indicating whether to plot the stationary state probabilities as a function of any covariates (default: FALSE) |
| plotEllipse | Logical indicating whether to plot error ellipses around imputed location means. Default: TRUE. |
| return | Logical indicating whether to return a list containing estimates, SEs, CIs, and covariate values used to create the plots for each mixture and state. Ignored if plotCI=FALSE. Default: FALSE. |
| ... | Additional arguments passed to <code>graphics::plot</code> and <code>graphics::hist</code> functions. These can currently include <code>asp</code> , <code>cex</code> , <code>cex.axis</code> , <code>cex.lab</code> , <code>cex.legend</code> , <code>cex.main</code> , <code>legend.pos</code> , and <code>lwd</code> . See par . <code>legend.pos</code> can be a single keyword from the list “bottomright”, “bottom”, “bottomleft”, “left”, “topleft”, “top”, “topright”, “right”, and “center”. Note that <code>asp</code> and <code>cex</code> only apply to plots of animal tracks. |

Details

The state-dependent densities are weighted by the frequency of each state in the most probable state sequence (decoded with the function `viterbi` for each imputation). For example, if the most probable state sequence indicates that one third of observations correspond to the first state, and two thirds to the second state, the plots of the densities in the first state are weighted by a factor 1/3, and in the second state by a factor 2/3.

Examples

```
## Not run:
# Extract data from miExample
obsData <- miExample$obsData

# error ellipse model
err.model <- list(x= ~ ln.sd.x - 1, y = ~ ln.sd.y - 1, rho = ~ error.corr)

# Fit crawl to obsData
crwOut <- crawlWrap(obsData, theta=c(4,0), fixPar=c(1,1,NA,NA),
                    err.model=err.model)

# Fit four imputations
bPar <- miExample$bPar
HMMfits <- MIfitHMM(crwOut, nSims=4, poolEstimates=FALSE,
                   nbStates=2, dist=list(step="gamma", angle="vm"),
                   Par0=bPar$Par, beta0=bPar$beta,
                   formula=~cov1+cos(cov2),
                   estAngleMean=list(angle=TRUE),
                   covNames=c("cov1", "cov2"))

# Pool estimates
miSum <- MIpool(HMMfits)
plot(miSum)

## End(Not run)
```

plot.momentuHMM

Plot momentuHMM

Description

Plot the fitted step and angle densities over histograms of the data, transition probabilities as functions of the covariates, and maps of the animals' tracks colored by the decoded states.

Usage

```
## S3 method for class 'momentuHMM'
plot(
  x,
  animals = NULL,
```

```

covs = NULL,
ask = TRUE,
breaks = "Sturges",
hist.ylim = NULL,
sepAnimals = FALSE,
sepStates = FALSE,
col = NULL,
cumul = TRUE,
plotTracks = TRUE,
plotCI = FALSE,
alpha = 0.95,
plotStationary = FALSE,
return = FALSE,
...
)

```

Arguments

| | |
|-----------------------------|---|
| <code>x</code> | Object <code>momentuHMM</code> |
| <code>animals</code> | Vector of indices or IDs of animals for which information will be plotted. Default: <code>NULL</code> ; all animals are plotted. |
| <code>covs</code> | Data frame consisting of a single row indicating the covariate values to be used in plots. If none are specified, the means of any covariates appearing in the model are used (unless covariate is a factor, in which case the first factor in the data is used). |
| <code>ask</code> | If <code>TRUE</code> , the execution pauses between each plot. |
| <code>breaks</code> | Histogram parameter. See <code>hist</code> documentation. |
| <code>hist.ylim</code> | An optional named list of vectors specifying <code>ylim=c(ymin,ymax)</code> for the data stream histograms. See <code>hist</code> documentation. Default: <code>NULL</code> ; the function sets default values for all data streams. |
| <code>sepAnimals</code> | If <code>TRUE</code> , the data is split by individuals in the histograms. Default: <code>FALSE</code> . |
| <code>sepStates</code> | If <code>TRUE</code> , the data is split by states in the histograms. Default: <code>FALSE</code> . |
| <code>col</code> | Vector or colors for the states (one color per state). |
| <code>cumul</code> | If <code>TRUE</code> , the sum of weighted densities is plotted (default). |
| <code>plotTracks</code> | If <code>TRUE</code> , the Viterbi-decoded tracks are plotted (default). |
| <code>plotCI</code> | Logical indicating whether to include confidence intervals in natural parameter plots (default: <code>FALSE</code>) |
| <code>alpha</code> | Significance level of the confidence intervals (if <code>plotCI=TRUE</code>). Default: 0.95 (i.e. 95% CIs). |
| <code>plotStationary</code> | Logical indicating whether to plot the stationary state probabilities as a function of any covariates (default: <code>FALSE</code>). Ignored unless covariate are included in formula. |
| <code>return</code> | Logical indicating whether to return a list containing: 1) estimates, SEs, CIs, and covariate values used to create the plots for each mixture and state (<code>estimates</code>); |

and 2) recorded plots (via `recordPlot`) of the density/histogram and parameter plots (plots). Note that estimates are not returned if `plotCI=FALSE`. Default: `FALSE`.

... Additional arguments passed to `graphics::plot` and `graphics::hist` functions. These can currently include `asp`, `cex`, `cex.axis`, `cex.lab`, `cex.legend`, `cex.main`, `legend.pos`, and `lwd`. See `par`. `legend.pos` can be a single keyword from the list “bottomright”, “bottom”, “bottomleft”, “left”, “topleft”, “top”, “topright”, “right”, and “center”. Note that `asp` and `cex` only apply to plots of animal tracks.

Details

The state-dependent densities are weighted by the frequency of each state in the most probable state sequence (decoded with the function `viterbi`). For example, if the most probable state sequence indicates that one third of observations correspond to the first state, and two thirds to the second state, the plots of the densities in the first state are weighted by a factor 1/3, and in the second state by a factor 2/3.

Confidence intervals for natural parameters are calculated from the working parameter point and covariance estimates using finite-difference approximations of the first derivative for the transformation (see `grad`). For example, if `dN` is the numerical approximation of the first derivative of the transformation $N = \exp(x_1 * B_1 + x_2 * B_2)$ for covariates (x_1, x_2) and working parameters (B_1, B_2) , then $\text{var}(N) = dN \%*\% \text{Sigma} \%*\% dN$, where $\text{Sigma} = \text{cov}(B_1, B_2)$, and normal confidence intervals can be constructed as $N \pm \text{qnorm}(1 - (1 - \alpha) / 2) * \text{se}(N)$.

Examples

```
# m is a momentuHMM object (as returned by fitHMM), automatically loaded with the package
m <- example$m

plot(m, ask=TRUE, animals=1, breaks=20, plotCI=TRUE)
```

plot.momentuHMMData *Plot momentuHMMData or momentuHierHMMData*

Description

Plot `momentuHMMData` or `momentuHierHMMData`

Usage

```
## S3 method for class 'momentuHMMData'
plot(
  x,
  dataNames = c("step", "angle"),
  animals = NULL,
  compact = FALSE,
```

```

    ask = TRUE,
    breaks = "Sturges",
    ...
)

```

Arguments

| | |
|-----------|--|
| x | An object <code>momentuHMMData</code> or <code>momentuHierHMMData</code> |
| dataNames | Names of the variables to plot. Default is <code>dataNames=c("step", "angle")</code> . |
| animals | Vector of indices or IDs of animals for which information will be plotted. Default: <code>NULL</code> ; all animals are plotted. |
| compact | <code>TRUE</code> for a compact plot (all individuals at once), <code>FALSE</code> otherwise (default – one individual at a time). |
| ask | If <code>TRUE</code> , the execution pauses between each plot. |
| breaks | Histogram parameter. See <code>hist</code> documentation. |
| ... | Currently unused. For compatibility with generic method. |

Examples

```

# data is a momentuHMMData object (as returned by prepData), automatically loaded with the package
data <- example$m$data

plotPR(data, dataNames=c("step", "angle", "cov1", "cov2"),
        compact=TRUE, breaks=20, ask=FALSE)

```

plotPR *Plot pseudo-residuals*

Description

Plots time series, qq-plots (against the standard normal distribution) using [qqPlot](#), and sample ACF functions of the pseudo-residuals for each data stream

Usage

```
plotPR(m, lag.max = NULL, ncores = 1)
```

Arguments

| | |
|---------|--|
| m | A momentuHMM , momentuHierHMM , miHMM , HMMfits , or miSum object. |
| lag.max | maximum lag at which to calculate the acf. See acf . |
| ncores | number of cores to use for parallel processing |

Details

- If some turning angles in the data are equal to π , the corresponding pseudo-residuals will not be included. Indeed, given that the turning angles are defined on $(-\pi, \pi]$, an angle of π results in a pseudo-residual of $+\text{Inf}$ (check Section 6.2 of reference for more information on the computation of pseudo-residuals).
- If some data streams are zero-inflated and/or one-inflated, the corresponding pseudo-residuals are shown as segments, because pseudo-residuals for discrete data are defined as segments (see Zucchini and MacDonald, 2009, Section 6.2).
- For multiple imputation analyses, if m is a `miHMM` object or a list of `momentuHMM` objects, then the pseudo-residuals are individually calculated and plotted for each model fit. Note that pseudo-residuals for `miSum` objects (as returned by `MIPool`) are based on pooled parameter estimates and the means of the data values across all imputations (and therefore may not be particularly meaningful).

References

Zucchini, W. and MacDonald, I.L. 2009. Hidden Markov Models for Time Series: An Introduction Using R. Chapman & Hall (London).

Examples

```
# m is a momentuHMM object (as returned by fitHMM), automatically loaded with the package
m <- example$m

plotPR(m)
```

plotSat

Plot observations on satellite image

Description

Plot tracking data on a satellite map. This function plots coordinates in longitude and latitude (not UTM), so if data coordinates are not provided in longitude and latitude, then the coordinate reference system must be provided using the `projargs` argument. This function uses the package `ggmap` to fetch a satellite image from Google. An Internet connection is required to use this function.

Usage

```
plotSat(
  data,
  zoom = NULL,
  location = NULL,
  segments = TRUE,
  compact = TRUE,
  col = NULL,
  alpha = 1,
```

```

    size = 1,
    shape = 16,
    states = NULL,
    animals = NULL,
    ask = TRUE,
    return = FALSE,
    stateNames = NULL,
    projargs = NULL
  )

```

Arguments

| | |
|------------|---|
| data | Data frame or momentuHMMData object, with necessary fields 'x' (longitudinal direction) and 'y' (latitudinal direction). A momentuHMM , miHMM , or miSum object is also permitted, from which the data will be extracted. If <code>states=NULL</code> and a momentuHMM , miHMM , or miSum object is provided, the decoded states are automatically plotted. |
| zoom | The zoom level, as defined for get_map . Integer value between 3 (continent) and 21 (building). |
| location | Location of the center of the map to be plotted (this must be in the same coordinate reference system as data). |
| segments | TRUE if segments should be plotted between the observations (default), FALSE otherwise. |
| compact | FALSE if tracks should be plotted separately, TRUE otherwise (default). |
| col | Palette of colours to use for the dots and segments. If not specified, uses default palette. |
| alpha | Transparency argument for geom_point . |
| size | Size argument for geom_point . |
| shape | Shape argument for geom_point . If <code>states</code> is provided, then shape must either be a scalar or a vector of length <code>length(unique(states))</code> . If <code>states=NULL</code> , then shape must either be a scalar or a vector consisting of a value for each individual to be plotted. |
| states | A sequence of integers, corresponding to the decoded states for these data (such that the observations are colored by states). |
| animals | Vector of indices or IDs of animals/tracks to be plotted. Default: NULL; all animals are plotted. |
| ask | If TRUE, the execution pauses between each plot. |
| return | If TRUE, the function returns a ggplot object (which can be edited and plotted manually). If FALSE, the function automatically plots the map (default). |
| stateNames | Optional character vector of length <code>max(states)</code> indicating state names. Ignored unless <code>states</code> is provided. |
| projargs | A character string of PROJ.4 projection arguments indicating the coordinate reference system for data and location coordinates (if not longitude and latitude). A CRS object is also permitted. If <code>projargs</code> is provided, the coordinates will be internally transformed to longitude and latitude for plotting. |

Details

If the plot displays the message "Sorry, we have no imagery here", try a lower level of zoom.

References

D. Kahle and H. Wickham. ggmap: Spatial Visualization with ggplot2. The R Journal, 5(1), 144-161. URL: <http://journal.r-project.org/archive/2013-1/kahle-wickham.pdf>

| | |
|----------------|--|
| plotSpatialCov | <i>Plot observations on raster image</i> |
|----------------|--|

Description

Plot tracking data over a raster layer.

Usage

```
plotSpatialCov(
  data,
  spatialCov,
  segments = TRUE,
  compact = TRUE,
  col = NULL,
  alpha = 1,
  size = 1,
  shape = 16,
  states = NULL,
  animals = NULL,
  ask = TRUE,
  return = FALSE,
  stateNames = NULL,
  colors = c("darkblue", "lightblue")
)
```

Arguments

| | |
|------------|--|
| data | Data frame or momentuHMMData object, with necessary fields 'x' (longitudinal direction) and 'y' (latitudinal direction). A momentuHMM , miHMM , or miSum object is also permitted, from which the data will be extracted. If states=NULL and a momentuHMM, miHMM, or miSum object is provided, the decoded states are automatically plotted. |
| spatialCov | raster object of the RasterLayer class on which to plot the location data |
| segments | TRUE if segments should be plotted between the observations (default), FALSE otherwise. |
| compact | FALSE if tracks should be plotted separately, TRUE otherwise (default). |

| | |
|------------|---|
| col | Palette of colours to use for the dots and segments. If not specified, uses default palette. |
| alpha | Transparency argument for <code>geom_point</code> . |
| size | Size argument for <code>geom_point</code> . |
| shape | Shape argument for <code>geom_point</code> . If <code>states</code> is provided, then <code>shape</code> must either be a scalar or a vector of length <code>length(unique(states))</code> . If <code>states=NULL</code> , then <code>shape</code> must either be a scalar or a vector consisting of a value for each individual to be plotted. |
| states | A sequence of integers, corresponding to the decoded states for these data. If specified, the observations are colored by states. |
| animals | Vector of indices or IDs of animals/tracks to be plotted. Default: <code>NULL</code> ; all animals are plotted. |
| ask | If <code>TRUE</code> , the execution pauses between each plot. |
| return | If <code>TRUE</code> , the function returns a <code>ggplot</code> object (which can be edited and plotted manually). If <code>FALSE</code> , the function automatically plots the map (default). |
| stateNames | Optional character vector of length <code>max(states)</code> indicating state names. Ignored unless <code>states</code> is provided. |
| colors | Colours argument for <code>geom_raster</code> . Default: <code>c("darkblue", "lightblue")</code> . |

Examples

```
## Not run:
stepDist <- "gamma"
angleDist <- "vm"

# plot simulated data over forest raster automatically loaded with the package
spatialCov<-list(forest=forest)
data <- simData(nbAnimals=2,nbStates=2,dist=list(step=stepDist,angle=angleDist),
               Par=list(step=c(100,1000,50,100),angle=c(0,0,0.1,5)),
               beta=matrix(c(5,-10,-25,50),nrow=2,ncol=2,byrow=TRUE),
               formula=~forest,spatialCovs=spatialCov,
               obsPerAnimal=225,states=TRUE)

plotSpatialCov(data,forest,states=data$states)

## End(Not run)
```

plotStates

Plot states

Description

Plot the states and states probabilities.

Usage

```
plotStates(m, animals = NULL, ask = TRUE)
```


Arguments

| | |
|---------|---|
| m | A momentuHMM , momentuHierHMM , miHMM , or miSum object |
| animals | Vector of indices or IDs of animals for which states will be plotted. |
| ask | If TRUE, the execution pauses between each plot. |

Examples

```
# m is a momentuHMM object (as returned by fitHMM), automatically loaded with the package
m <- example$m

# plot states for first and second animals
plotStates(m, animals=c(1,2))
```

| | |
|----------------|--|
| plotStationary | <i>Plot stationary state probabilities</i> |
|----------------|--|

Description

Plot stationary state probabilities

Usage

```
plotStationary(
  model,
  covs = NULL,
  col = NULL,
  plotCI = FALSE,
  alpha = 0.95,
  return = FALSE,
  ...
)
```

Arguments

| | |
|--------|--|
| model | momentuHMM , momentuHierHMM , miHMM , or miSum object |
| covs | Optional data frame consisting of a single row indicating the covariate values to be used in plots. If none are specified, the means of any covariates appearing in the model are used (unless covariate is a factor, in which case the first factor in the data is used). |
| col | Vector or colors for the states (one color per state). |
| plotCI | Logical indicating whether to include confidence intervals in plots (default: FALSE) |
| alpha | Significance level of the confidence intervals (if plotCI=TRUE). Default: 0.95 (i.e. 95% CIs). |

return Logical indicating whether to return a list containing estimates, SEs, CIs, and covariate values used to create the plots for each mixture and state. Ignored if `plotCI=FALSE`. Default: `FALSE`.

... Additional arguments passed to `graphics::plot`. These can currently include `cex.axis`, `cex.lab`, `cex.legend`, `cex.main`, `legend.pos`, and `lwd`. See [par](#). `legend.pos` can be a single keyword from the list “bottomright”, “bottom”, “bottomleft”, “left”, “topleft”, “top”, “topright”, “right”, and “center”.

Examples

```
# m is a momentuHMM object (as returned by fitHMM), automatically loaded with the package
m <- example$m

plotStationary(m)
```

| | |
|----------|--|
| prepCTDS | <i>Preprocessing of continuous-time discrete-space (CTDS) movement HMMs using ctmcmove</i> |
|----------|--|

Description

This wrapper function for [path2ctmc](#) and [ctmc2glm](#) converts a `data.frame` of coordinates, other data streams, and non-spatial covariates to a `momentuHMMData` object that can be passed directly to [fitCTHMM](#) (or as a list to [MIfitCTHMM](#)).

Usage

```
prepCTDS(data, ...)

## Default S3 method:
prepCTDS(
  data,
  Time.unit = "auto",
  rast,
  directions = 4,
  zero.idx = integer(),
  print.iter = FALSE,
  interpMethod = "ShortestPath",
  spatialCovs = NULL,
  spatialCovs.grad = NULL,
  crw = TRUE,
  normalize.gradients = FALSE,
  grad.point.decreasing = FALSE,
  covNames = NULL,
  ncores = 1,
  ...
```

```

)

## S3 method for class 'hierarchical'
prepCTDS(
  data,
  Time.unit = "auto",
  rast,
  directions = 4,
  zero.idx = integer(),
  print.iter = FALSE,
  interpMethod = "ShortestPath",
  spatialCovs = NULL,
  spatialCovs.grad = NULL,
  crw = TRUE,
  normalize.gradients = FALSE,
  grad.point.decreasing = FALSE,
  covNames = NULL,
  ncores = 1,
  hierLevels,
  coordLevel,
  ...
)

```

Arguments

| | |
|------------|---|
| data | Either a <code>data.frame</code> of data streams or a <code>crwData</code> (or <code>crwHierData</code>) object (as returned by <code>crawlWrap</code>). If a <code>data.frame</code> , it must include entries for the x coordinate (x), y coordinate (y), and time stamp (time). An ID entry must also be included if data includes multiple individuals. |
| ... | further arguments passed to or from other methods |
| Time.unit | Character string indicating units for time difference between observations (e.g. 'auto', 'secs', 'mins', 'hours', 'days', 'weeks'). Ignored unless <code>data\$time</code> is of class <code>date-time</code> or <code>date</code> . Default: 'auto', but note that if there are multiple individuals, then the units are determined based on the time stamps for the first individual. |
| rast | A raster object or raster stack object that will define the discrete-space grid cells for the CTMC movement path. <code>spatialCovs</code> and <code>spatialCovs.grad</code> must have the same extent, number of rows and columns, projection, resolution, and origin as <code>rast</code> . |
| directions | Integer. Either 4 (indicating a "Rook's neighborhood" of 4 neighboring grid cells) or 8 (indicating a "King's neighborhood" of 8 neighboring grid cells). |
| zero.idx | Integer vector of the indices of raster cells that are not passable and should be excluded. These are cells where movement should be impossible. Default is <code>zero.idx=integer()</code> . |
| print.iter | Logical. If true, then the progress stepping through each observed location in data will be output in the terminal. |

| | |
|------------------------------------|---|
| <code>interpMethod</code> | Specifies interpolation method. Either "ShortestPath", which uses the shortest graphical path on the raster graph, or "LinearInterp", which linearly interpolates between observed locations. "ShortestPath" is slower, slightly more accurate, and allows for impassible barriers specified through "zero.idx". "LinearInterp" is faster but does not allow for impassible barriers. |
| <code>spatialCovs</code> | List of <code>raster</code> objects for spatio-temporally referenced covariates. Covariates specified by <code>spatialCovs</code> are extracted from the raster layer(s) based on the location data (and the z values for a raster <code>stack</code> or <code>brick</code>) for each time step. If an element of <code>spatialCovs</code> is a raster <code>stack</code> or <code>brick</code> , then z values must be set using <code>raster::setZ</code> and data must include column(s) of the corresponding z value(s) for each observation (e.g., 'Date'). |
| <code>spatialCovs.grad</code> | List of <code>raster</code> objects for spatio-temporally referenced covariates, where a directional gradient is to be calculated internally using <code>rast.grad</code> . Gradient-based covariates specified by <code>spatialCovs.grad</code> are extracted from the raster layer(s) based on the location data (and the z values for a raster <code>stack</code> or <code>brick</code>) for each time step. If an element of <code>spatialCovs.grad</code> is a raster <code>stack</code> or <code>brick</code> , then z values must be set using <code>raster::setZ</code> and data must include column(s) of the corresponding z value(s) for each observation (e.g., 'Date'). |
| <code>crw</code> | Logical. If TRUE (default), an autocovariate is created for each cell visited in the CTMC movement path. The autocovariate is a unit-length directional vector pointing from the center of the most recent grid cell to the center of the current grid cell. |
| <code>normalize.gradients</code> | Logical. Default is FALSE. If TRUE, then all gradient covariates for <code>spatialCovs.grad</code> are normalized by dividing by the length of the gradient vector at each point. |
| <code>grad.point.decreasing</code> | Logical. Default is FALSE. If TRUE, then the gradient covariates are positive in the direction of decreasing values of the covariate. If FALSE, then the gradient covariates are positive in the direction of increasing values of the covariate (like a true gradient). |
| <code>covNames</code> | Character vector indicating the names of any covariates in data. Any variables in data (other than ID, x, y, and time) that are not identified in <code>covNames</code> are assumed to be additional data streams (i.e., missing values will not be accounted for). |
| <code>ncores</code> | Number of cores to use for parallel processing. Default: 1 (no parallel processing). |
| <code>hierLevels</code> | Character vector indicating the levels of the hierarchy and their order, from top (coarsest scale) to bottom (finest scale), that are included in <code>data\$level</code> . For example, for a 2-level hierarchy then <code>hierLevels=c("1", "2i", "2")</code> indicates <code>data\$level</code> for each observation can be one of three factor levels: "1" (coarse scale), "2i" (initial fine scale), and "2" (fine scale). Ignored if data is a <code>crwHierData</code> object. |
| <code>coordLevel</code> | Character string indicating the level of the hierarchy for the location data. If specified, then data must include a 'level' field indicating the level of the hierarchy for each observation. Ignored if <code>coordNames</code> is NULL or data is a <code>crwHierData</code> object. |

Details

- Any moves to adjacent cells (as defined by [directions](#); see [adjacent](#)) between times t and $t+1$ are assumed to occur at time $t+1$ (where $\tau = t+1 - t$), regardless of the length of the time step (τ) and where in the current cell or in the neighboring cell that the corresponding (continuous-space) locations reside. This is done to facilitate the temporal alignment of the discrete-space movement process with other data streams and spatio-temporal covariates. The appropriateness of this simplifying assumption will depend on τ , the scale of movement, and the raster resolution.
- If there are move(s) across multiple cells within a time step, data stream(s) other than z (the categorical CTDS data stream) are set to NA for these time step(s). These NA data stream values must be manually set based on the time spent in each cell if they are to be included in subsequent analysis. Time-varying spatial covariates for these time step(s) are set based on the z -value for the initial cell and, if different, these must also be set manually based on z -value(s) at the time cell(s) were crossed. All such instances are indicated wherever the 'cellCross' field is > 0 .
- If data is a [crwData](#) object, the [momentuHMMData](#) object created by prepCTDS is based on the best predicted locations (i.e., `crwData$crwPredict$mu.x` and `crwData$crwPredict$mu.y`). Prior to using prepCTDS, additional data streams or covariates unrelated to location (including z -values associated with `spatialCovs` and `spatialCovs.grad` raster stacks or bricks) can be merged with the `crwData` object using [crawlMerge](#).

Value

A [momentuHMMData](#) object of class `ctds` that can be passed to [fitCTHMM](#) (or as a list to [MIfitCTHMM](#)), where:

| | |
|------------------------|--|
| <code>ID</code> | The ID(s) of the observed animal(s) |
| <code>time</code> | Time stamp for each observation |
| <code>x</code> | Easting coordinate of the current cell |
| <code>y</code> | Northing coordinate of the current cell |
| <code>z</code> | Categorical CTDS data stream indicating which cell was moved to, where $z = \text{directions} + 1$ indicates no movement from the current cell. When <code>directions=4</code> , $z=1$ indicates a move to the left cell, $z=2$ right cell, $z=3$ upward cell, and $z=4$ downward cell. When <code>directions=8</code> , $z=1$ indicates top-left cell, $z=2$ middle-left cell, $z=3$ bottom-left cell, $z=4$ top-right cell, $z=5$ middle-right cell, $z=6$ bottom-right cell, $z=7$ top-middle cell, and $z=8$ bottom-middle cell. |
| <code>tau</code> | Time difference (in <code>Time.unit</code>) between successive observations |
| <code>cellCross</code> | Integer indexing move(s) across multiple cells within a time step (if any) |
| <code>...</code> | Additional data streams (if any) |
| <code>...</code> | Covariates (if any). Covariates are needed for all neighboring cells and are indexed by $1, 2, \dots, \text{directions}$ using a suffix (e.g. <code>cov.1</code> , <code>cov.2</code> , <code>cov.3</code> , and <code>cov.4</code> for a covariate named 'cov' with <code>directions=4</code>). Additionally, a covariate named <code>noMove</code> is automatically included that indicates when no cell transition occurred (hence no transition out of the current state); the <code>noMove</code> covariate can be used as a state transition probability covariate to forbid transitions from the current state when there is no cell movement. |

References

Hanks E. M., Hooten M. B., and Alldredge M. W. 2015. Continuous-time Discrete-space Models for Animal Movement. *The Annals of Applied Statistics* 9:145-165

```
prepData
```

Preprocessing of the data streams and covariates

Description

Preprocessing of the data streams, including calculation of step length, turning angle, and covariates from location data to be suitable for analysis using [fitHMM](#).

Usage

```
prepData(data, ...)

## Default S3 method:
prepData(
  data,
  type = c("UTM", "LL"),
  coordNames = c("x", "y"),
  covNames = NULL,
  spatialCovs = NULL,
  centers = NULL,
  centroids = NULL,
  angleCovs = NULL,
  altCoordNames = NULL,
  gradient = FALSE,
  CT = FALSE,
  Time.name = "time",
  Time.unit = "auto",
  ...
)

## S3 method for class 'hierarchical'
prepData(
  data,
  type = c("UTM", "LL"),
  coordNames = c("x", "y"),
  covNames = NULL,
  spatialCovs = NULL,
  centers = NULL,
  centroids = NULL,
  angleCovs = NULL,
  altCoordNames = NULL,
  gradient = FALSE,
```

```

CT = FALSE,
Time.name = "time",
Time.unit = "auto",
hierLevels,
coordLevel,
...
)

```

Arguments

| | |
|-------------|--|
| data | Either a data frame of data streams or a <code>crwData</code> (or <code>crwHierData</code>) object (as returned by <code>crawlWrap</code>). If data is a data frame, it can optionally include a field ID (identifiers for the observed individuals), coordinates from which step length ('step') and turning angle ('angle') are calculated, and any covariates (with names matching <code>covNames</code> and/or <code>angleCovs</code>). If step length and turning angle are to be calculated from coordinates, the <code>coordNames</code> argument must identify the names for the x- (longitudinal) and y- (latitudinal) coordinates, and, for hierarchical data, the <code>coordLevel</code> argument must identify the level of the hierarchy at which the location data are obtained. With the exception of ID, <code>coordNames</code> , and, for hierarchical data, <code>level</code> , all variables in data are treated as data streams unless identified as covariates in <code>covNames</code> and/or <code>angleCovs</code> . |
| ... | further arguments passed to or from other methods |
| type | 'UTM' if easting/northing provided (the default), 'LL' if longitude/latitude. If type='LL' then step lengths are calculated in kilometers and turning angles are based on initial bearings (see turnAngle). Ignored if data is a <code>crwData</code> object. |
| coordNames | Names of the columns of coordinates in the data data frame. Default: <code>c("x", "y")</code> . If <code>coordNames=NULL</code> then step lengths, turning angles, and location covariates (i.e., those specified by <code>spatialCovs</code> , <code>centers</code> , and <code>angleCovs</code>) are not calculated. Ignored if data is a <code>crwData</code> object. |
| covNames | Character vector indicating the names of any covariates in data dataframe. Any variables in data (other than ID) that are not identified in <code>covNames</code> and/or <code>angleCovs</code> are assumed to be data streams (i.e., missing values will not be accounted for). |
| spatialCovs | List of <code>raster</code> objects for spatio-temporally referenced covariates. Covariates specified by <code>spatialCovs</code> are extracted from the raster layer(s) based on the location data (and the z values for a raster <code>stack</code> or <code>brick</code>) for each time step. If an element of <code>spatialCovs</code> is a raster <code>stack</code> or <code>brick</code> , then z values must be set using <code>raster::setZ</code> and data must include column(s) of the corresponding z value(s) for each observation (e.g., 'time'). |
| centers | 2-column matrix providing the x-coordinates (column 1) and y-coordinates (column 2) for any activity centers (e.g., potential centers of attraction or repulsion) from which distance and angle covariates will be calculated based on the location data. If no row names are provided, then generic names are generated for the distance and angle covariates (e.g., 'center1.dist', 'center1.angle', 'center2.dist', 'center2.angle'); otherwise the covariate names are derived from the row names of centers as <code>paste0(rep(rownames(centers), each=2), c(".dist", ".angle"))</code> . As with covariates identified in <code>angleCovs</code> , note that the angle covariates for |

| | |
|----------------------------|---|
| | each activity center are calculated relative to the previous movement direction (instead of standard direction relative to the x-axis); this is to allow the mean turning angle to be modelled as a function of these covariates using circular-circular regression in <code>fitHMM</code> or <code>MIfitHMM</code> . |
| <code>centroids</code> | List where each element is a data frame containing the x-coordinates ('x'), y-coordinates ('y'), and times (with user-specified name, e.g., 'time') for centroids (i.e., dynamic activity centers where the coordinates can change over time) from which distance and angle covariates will be calculated based on the location data. If any centroids are specified, then data must include a column indicating the time of each observation, and this column name must match the corresponding user-specified name of the time column in <code>centroids</code> (e.g. 'time'). Times can be numeric or POSIXt. If no list names are provided, then generic names are generated for the distance and angle covariates (e.g., 'centroid1.dist', 'centroid1.angle', 'centroid2.dist', 'centroid2.angle'); otherwise the covariate names are derived from the list names of centroids as <code>paste0(rep(names(centroids), each=2), c(".dist", ".angle"))</code> . As with covariates identified in <code>angleCovs</code> , note that the angle covariates for each centroid are calculated relative to the previous movement direction (instead of standard direction relative to the x-axis); this is to allow the mean turning angle to be modelled as a function of these covariates using circular-circular regression in <code>fitHMM</code> or <code>MIfitHMM</code> . |
| <code>angleCovs</code> | Character vector indicating the names of any circular-circular regression angular covariates in data or <code>spatialCovs</code> that need conversion from standard direction (in radians relative to the x-axis) to turning angle (relative to previous movement direction) using <code>circAngles</code> . |
| <code>altCoordNames</code> | Character string indicating an alternative name for the returned location data. If provided, then <code>prepData</code> will return easting (or longitude) coordinate names as <code>paste0(altCoordNames, ".x")</code> and northing (or latitude) as <code>paste0(altCoordNames, ".y")</code> instead of x and y, respectively. This can be useful for location data that are intended to be modeled using a bivariate normal distribution (see <code>fitHMM</code>). Ignored unless <code>coordNames</code> are provided. |
| <code>gradient</code> | Logical indicating whether or not to calculate gradients of <code>spatialCovs</code> using bilinear interpolation (e.g. for inclusion in potential functions). Default: FALSE. If TRUE, the gradients are returned with ".x" (easting gradient) and ".y" (northing gradient) suffixes added to the names of <code>spatialCovs</code> . For example, if <code>cov1</code> is the name of a spatial covariate, then the returned <code>momentuHMMData</code> object will include the fields "cov1.x" and "cov1.y". |
| <code>CT</code> | Logical indicating whether or not data is for continuous-time models. Default: FALSE (discrete time). |
| <code>Time.name</code> | Character string indicating name of the time column in data (for continuous-time HMMs). Default: "time". Ignored if <code>CT=FALSE</code> or, if <code>CT=TRUE</code> , when data is a <code>crwData</code> object returned by <code>crawlWrap</code> . |
| <code>Time.unit</code> | Character string indicating units for time difference between observations (e.g. 'auto', 'secs', 'mins', 'hours', 'days', 'weeks'). Ignored unless <code>CT=TRUE</code> and <code>data[[Time.name]]</code> is of class <code>date-time</code> or <code>date</code> . Default: 'auto'. |
| <code>hierLevels</code> | Character vector indicating the levels of the hierarchy and their order, from top (coarsest scale) to bottom (finest scale), that are included in <code>data\$level</code> . |

For example, for a 2-level hierarchy then `hierLevels=c("1", "2i", "2")` indicates `data$level` for each observation can be one of three factor levels: "1" (coarse scale), "2i" (initial fine scale), and "2" (fine scale). Ignored if data is a [crwHierData](#) object.

`coordLevel` Character string indicating the level of the hierarchy for the location data. If specified, then data must include a 'level' field indicating the level of the hierarchy for each observation. Ignored if `coordNames` is NULL or data is a [crwHierData](#) object.

Details

- If data is a [crwData](#) (or [crwHierData](#)) object, the [momentuHMMDData](#) (or [momentuHierHMMDData](#)) object created by `prepData` includes step lengths and turning angles calculated from the best predicted locations (i.e., `crwData$crwPredict$mu.x` and `crwData$crwPredict$mu.y`). Prior to using `prepData`, additional data streams or covariates unrelated to location (including z-values associated with `spatialCovs` raster stacks or bricks) can be merged with the `crwData` (or `crwHierData`) object using [crawlMerge](#).
- For continuous-time data (i.e. `CT=TRUE`), if data is not a `crwData` object returned by [crawlWrap](#), then data must include a 'Time.name' field indicating the time column in data.
- For hierarchical data, data must include a 'level' field indicating the level of the hierarchy for each observation, and, for location data identified by `coordNames`, the `coordLevel` argument must indicate the level of the hierarchy at which the location data are obtained.

Value

An object [momentuHMMDData](#) or [momentuHierHMMDData](#), i.e., a dataframe of:

| | |
|-----|--|
| ID | The ID(s) of the observed animal(s) |
| ... | Data streams (e.g., 'step', 'angle', etc.) |
| x | Either easting or longitude (if <code>coordNames</code> is specified or data is a <code>crwData</code> object) |
| y | Either northing or latitude (if <code>coordNames</code> is specified or data is a <code>crwData</code> object) |
| ... | Covariates (if any) |

See Also

[crawlMerge](#), [crawlWrap](#), [crwData](#)
[crwHierData](#)

Examples

```
coord1 <- c(1,2,3,4,5,6,7,8,9,10)
coord2 <- c(1,1,1,2,2,2,1,1,1,2)
cov1 <- rnorm(10)

data <- data.frame(coord1=coord1, coord2=coord2, cov1=cov1)
d <- prepData(data, coordNames=c("coord1", "coord2"), covNames="cov1")
```

```

# include additional data stream named 'omega'
omega <- rbeta(10,1,1)
data <- data.frame(coord1=coord1,coord2=coord2,omega=omega,cov1=cov1)
d <- prepData(data,coordNames=c("coord1","coord2"),covNames="cov1")

# include 'forest' example raster layer as covariate
data <- data.frame(coord1=coord1*1000,coord2=coord2*1000)
spatialCov <- list(forest=forest)
d <- prepData(data,coordNames=c("coord1","coord2"),spatialCovs=spatialCov)

# include 2 activity centers
data <- data.frame(coord1=coord1,coord2=coord2,cov1=cov1)
d <- prepData(data,coordNames=c("coord1","coord2"),covNames="cov1",
              centers=matrix(c(0,10,0,10),2,2,dimnames=list(c("c1","c2"),NULL)))

# include centroid
data <- data.frame(coord1=coord1,coord2=coord2,cov1=cov1,time=1:10)
d <- prepData(data,coordNames=c("coord1","coord2"),covNames="cov1",
              centroid=list(centroid=data.frame(x=coord1+rnorm(10),
                                                y=coord2+rnorm(10),
                                                time=1:10)))

# Include angle covariate that needs conversion to
# turning angle relative to previous movement direction
u <- rnorm(10) # horizontal component
v <- rnorm(10) # vertical component
cov2 <- atan2(v,u)
data <- data.frame(coord1=coord1,coord2=coord2,cov1=cov1,cov2=cov2)
d <- prepData(data,coordNames=c("coord1","coord2"),covNames="cov1",
              angleCovs="cov2")

```

```
print.miHMM
```

```
Print miHMM
```

Description

Print miHMM

Usage

```
## S3 method for class 'miHMM'
print(x, ...)
```

Arguments

| | |
|-----|--|
| x | A miHMM object. |
| ... | Currently unused. For compatibility with generic method. |

Examples

```
## Not run:
# Extract data from miExample
obsData <- miExample$obsData

# error ellipse model
err.model <- list(x= ~ ln.sd.x - 1, y = ~ ln.sd.y - 1, rho = ~ error.corr)

# Fit crawl to obsData
crwOut <- crawlWrap(obsData,theta=c(4,0),fixPar=c(1,1,NA,NA),
                    err.model=err.model)

# Fit four imputations
bPar <- miExample$bPar
HMMfits <- MIfitHMM(crwOut,nSims=4,poolEstimates=FALSE,
                   nbStates=2,dist=list(step="gamma",angle="vm"),
                   Par0=bPar$Par,beta0=bPar$beta,
                   formula=~cov1+cos(cov2),
                   estAngleMean=list(angle=TRUE),
                   covNames=c("cov1","cov2"))

miHMM <- momentuHMM:::miHMM(list(miSum=MIPool(HMMfits),HMMfits=HMMfits))
print(miHMM)

## End(Not run)
```

print.miSum

Print miSum

Description

Print miSum

Usage

```
## S3 method for class 'miSum'
print(x, ...)
```

Arguments

```
x          A miSum object.
...        Currently unused. For compatibility with generic method.
```

Examples

```
## Not run:
# Extract data from miExample
obsData <- miExample$obsData
```

```

# error ellipse model
err.model <- list(x= ~ ln.sd.x - 1, y = ~ ln.sd.y - 1, rho = ~ error.corr)

# Fit crawl to obsData
crwOut <- crawlWrap(obsData, theta=c(4,0), fixPar=c(1,1,NA,NA),
                    err.model=err.model)

# Fit four imputations
bPar <- miExample$bPar
HMMfits <- MIfitHMM(crwOut, nSims=4, poolEstimates=FALSE,
                    nbStates=2, dist=list(step="gamma", angle="vm"),
                    Par0=bPar$Par, beta0=bPar$beta,
                    formula=~cov1+cos(cov2),
                    estAngleMean=list(angle=TRUE),
                    covNames=c("cov1", "cov2"))

# Pool estimates
miSum <- MIPool(HMMfits)
print(miSum)

## End(Not run)

```

```
print.momentuHMM      Print momentuHMM
```

Description

Print momentuHMM

Usage

```

## S3 method for class 'momentuHMM'
print(x, ...)

## S3 method for class 'momentuHierHMM'
print(x, ...)

```

Arguments

x A momentuHMM object.
 ... Currently unused. For compatibility with generic method.

Examples

```

# m is a momentuHMM object (as returned by fitHMM), automatically loaded with the package
m <- example$m

print(m)

```

| | |
|-----------|-------------------------|
| pseudoRes | <i>Pseudo-residuals</i> |
|-----------|-------------------------|

Description

The pseudo-residuals of `momentuHMM` models, as described in Zucchini and McDonad (2009).

Usage

```
pseudoRes(m, ncores = 1)
```

Arguments

| | |
|---------------------|---|
| <code>m</code> | A <code>momentuHMM</code> , <code>miHMM</code> , <code>HMMfits</code> , or <code>miSum</code> object. |
| <code>ncores</code> | number of cores to use for parallel processing |

Details

If some turning angles in the data are equal to π , the corresponding pseudo-residuals will not be included. Indeed, given that the turning angles are defined on $(-\pi, \pi]$, an angle of π results in a pseudo-residual of $+\text{Inf}$ (check Section 6.2 of reference for more information on the computation of pseudo-residuals).

A continuity adjustment (adapted from Harte 2017) is made for discrete probability distributions. When the data are near the boundary (e.g. 0 for “pois”; 0 and 1 for “bern”), then the pseudo residuals can be a poor indicator of lack of fit.

For multiple imputation analyses, if `m` is a `miHMM` object or a list of `momentuHMM` objects, then the pseudo-residuals are individually calculated for each model fit. Note that pseudo-residuals for `miSum` objects (as returned by `MIPool`) are based on pooled parameter estimates and the means of the data values across all imputations (and therefore may not be particularly meaningful).

Value

If `m` is a `momentuHMM`, `miHMM`, or `miSum` object, a list of pseudo-residuals for each data stream (e.g., ‘stepRes’, ‘angleRes’) is returned. If `m` is a list of `momentuHMM` objects, then a list of length `length(m)` is returned where each element is a list of pseudo-residuals for each data stream.

References

- Harte, D. 2017. HiddenMarkov: Hidden Markov Models. R package version 1.8-8.
- Zucchini, W. and MacDonal, I.L. 2009. Hidden Markov Models for Time Series: An Introduction Using R. Chapman & Hall (London).

Examples

```
# m is a momentuHMM object (as returned by fitHMM), automatically loaded with the package
m <- example$m
res <- pseudoRes(m)
stats::qqnorm(res$stepRes)
stats::qqnorm(res$angleRes)
```

randomEffects

Random effects estimation

Description

Approximate individual-level random effects estimation for state transition probabilities based on Burnham & White (2002)

Usage

```
randomEffects(
  m,
  Xformula = ~1,
  alpha = 0.95,
  ncores = 1,
  nlmPar = list(),
  fit = TRUE,
  retryFits = 0,
  retrySD = NULL,
  optMethod = "nlm",
  control = list(),
  modelName = NULL,
  ...
)
```

Arguments

| | |
|-----------|---|
| m | A momentuHMM object. |
| Xformula | Formula for the design matrix of the random effects model. The default Xformula=~1 specifies an intercept-only model with no additional individual covariate effects. |
| alpha | Significance level of the confidence intervals. Default: 0.95 (i.e. 95% CIs). |
| ncores | number of cores to use for parallel processing |
| nlmPar | List of parameters to pass to the optimization function nlm . See fitHMM . |
| fit | TRUE if the HMM should be re-fitted at the shrinkage estimates, FALSE otherwise. |
| retryFits | Non-negative integer indicating the number of times to attempt to iteratively fit the model using random perturbations of the current parameter estimates as the initial values for likelihood optimization. See fitHMM . |

| | |
|-----------|--|
| retrySD | An optional list of scalars or vectors indicating the standard deviation to use for normal perturbations of each working scale parameter when <code>retryFits>0</code> . See fithMM . |
| optMethod | The optimization method to be used. See fithMM . |
| control | A list of control parameters to be passed to <code>optim</code> (ignored unless <code>optMethod="Nelder-Mead"</code> or <code>optMethod="SANN"</code>). |
| modelName | An optional character string providing a name for the fitted model. See fithMM . |
| ... | further arguments passed to or from other methods. Not currently used. |

Value

A `randomEffects` model similar to a [momentuHMM](#) object, but including the additional random effect components:

| | |
|---------|---|
| varcomp | A list of length <code>nbStates*(nbStates-1)</code> with each element containing the random effect mean coefficient(s) (<code>mu</code>), random effect variance (<code>sigma</code>), and logit-scale shrinkage estimates for the state transition probability parameters (<code>ztilde</code>). |
| traceG | The trace of the projection matrix for each random effect. |

References

Burnham, K.P. and White, G.C. 2002. Evaluation of some random effects methodology applicable to bird ringing data. *Journal of Applied Statistics* 29: 245-264.

McClintock, B.T. 2021. Worth the effort? A practical examination of random effects in hidden Markov models for animal telemetry data. *Methods in Ecology and Evolution* [doi:10.1111/2041-210X.13619](https://doi.org/10.1111/2041-210X.13619).

Examples

```
## Not run:
# simulated data with normal random effects
# and binary individual covariate

nbAnimals <- 5 # should be larger for random effects estimation
obsPerAnimal <- 110
indCov <- rbinom(nbAnimals,1,0.5) # individual covariate
betaCov <- c(-0.5,0.5) # covariate effects
mu <- c(-0.1,0.1) # mean for random effects
sigma <- c(0.2,0.4) # sigma for random effects
beta0 <- cbind(rnorm(nbAnimals,mu[1],sigma[1]),
              rnorm(nbAnimals,mu[2],sigma[2]))

reData <- simData(nbAnimals=nbAnimals,obsPerAnimal=obsPerAnimal,nbStates=2,
                 dist=list(step="gamma"),formula=~0+ID+indCov,
                 Par=list(step=c(1,10,1,2)),
                 beta=rbind(beta0,betaCov),
                 covs=data.frame(indCov=rep(indCov,each=obsPerAnimal)))
```

```

# fit null model
nullFit <- fitHMM(reData,nbStates=2,
                 dist=list(step="gamma"),
                 Par0=list(step=c(1,10,1,2)))

# fit covariate model
covFit <- fitHMM(reData,nbStates=2,
                 dist=list(step="gamma"),formula=~indCov,
                 Par0=list(step=c(1,10,1,2)),
                 beta0=rbind(mu,betaCov))

# fit fixed effects model
fixFit <- fitHMM(reData,nbStates=2,
                 dist=list(step="gamma"),formula=~0+ID,
                 Par0=list(step=c(1,10,1,2)),
                 beta0=beta0)

# fit random effect model
reFit <- randomEffects(fixFit)

# fit random effect model with individual covariate
reCovFit <- randomEffects(fixFit, Xformula=~indCov)

# compare by AICc
AIC(nullFit,covFit,fixFit,reFit,reCovFit, n=nrow(reData))

## End(Not run)

```

| | |
|--------------|--|
| setModelName | <i>Set modelName for a momentuHMM, miHMM, HMMfits, or miSum object</i> |
|--------------|--|

Description

Set modelName for a momentuHMM, miHMM, HMMfits, or miSum object

Usage

```
setModelName(model, modelName)
```

Arguments

| | |
|-----------|--|
| model | momentuHMM, miHMM, HMMfits, or miSum object |
| modelName | Character string providing a name for the model. See fitHMM and MIfitHMM . |

Value

model object with new modelName field

Examples

```
m <- example$m
mName <- setModelName(m, modelName="example")
```

| | |
|---------------|---|
| setStateNames | <i>Set stateNames for a momentuHMM, miHMM, HMMfits, or miSum object</i> |
|---------------|---|

Description

Set stateNames for a momentuHMM, miHMM, HMMfits, or miSum object

Usage

```
setStateNames(model, stateNames)
```

Arguments

model [momentuHMM](#), [miHMM](#), [HMMfits](#), or [miSum](#) object
stateNames Character string providing state names for the model. See [fitHMM](#) and [MIfitHMM](#).

Value

model object with new stateNames field

Examples

```
m <- example$m
mName <- setStateNames(m, stateNames=c("encamped", "exploratory"))
```

| | |
|---------|------------------------|
| simCTDS | <i>Simulation tool</i> |
|---------|------------------------|

Description

Simulates data from a (multivariate) continuous-time discrete-space hidden Markov model based on Blackwell et al. (2016), where specification of kappa determines the potential times of state switches when formula includes covariates (larger kappa means potential switches are more frequent). Note that state transitions can only occur when there is a cell transition (unless moveState is set to FALSE), and time-varying covariates are assumed piece-wise constant between observations. Movement data are assumed to be in Cartesian coordinates (not longitude/latitude) and can be generated with or without observation error attributable to location measurement error.

Usage

```

simCTDS(
  nbAnimals = 1,
  nbStates = 2,
  dist,
  Par,
  beta = NULL,
  delta = NULL,
  formula = ~1,
  formulaDelta = NULL,
  mixtures = 1,
  formulaPi = NULL,
  covs = NULL,
  nbCovs = 0,
  rast,
  spatialCovs = NULL,
  spatialCovs.grad = NULL,
  directions = 4,
  normalize.gradients = FALSE,
  grad.point.decreasing = FALSE,
  zero.idx = integer(),
  moveState = FALSE,
  obsPerAnimal = c(500, 1500),
  initialPosition = c(0, 0),
  DM = NULL,
  userBounds = NULL,
  workBounds = NULL,
  betaRef = NULL,
  stateNames = NULL,
  model = NULL,
  matchModelObs = TRUE,
  states = FALSE,
  lambda = 1,
  errorEllipse = NULL,
  ncores = 1,
  export = NULL,
  keepSwitch = FALSE,
  kappa = NULL
)

```

Arguments

| | |
|------------------------|--|
| <code>nbAnimals</code> | Number of observed individuals to simulate. |
| <code>nbStates</code> | Number of behavioural states to simulate. |
| <code>dist</code> | A named list indicating the probability distributions of the data streams. A data stream named <code>z</code> must be included, and it must be assigned the "ctds" distribution. |

| | |
|--------------|---|
| Par | <p>A named list containing vectors of initial state-dependent probability distribution parameters for each data stream specified in <code>dist</code>. The parameters should be in the order expected by the pdfs of <code>dist</code>.</p> <p>If <code>DM</code> is not specified for a given data stream, then <code>Par</code> is on the natural (i.e., real) scale of the parameters. However, if <code>DM</code> is specified for a given data stream, then <code>Par</code> must be on the working (i.e., beta) scale of the parameters, and the length of <code>Par</code> must match the number of columns in the design matrix. See details below.</p> |
| beta | Matrix of regression parameters for the transition rates. |
| delta | <p>Initial value for the initial distribution of the HMM. Default: <code>rep(1/nbStates, nbStates)</code>.</p> <p>If <code>formulaDelta</code> includes a formula, then <code>delta</code> must be specified as a $k \times (nbStates-1)$ matrix, where k is the number of covariates and the columns correspond to states 2:nbStates.</p> |
| formula | <p>Regression formula for the transition rate covariates. Default: <code>~1</code> (no covariate effect). In addition to allowing standard functions in R formulas (e.g., <code>cos(cov)</code>, <code>cov1*cov2</code>, <code>I(cov^2)</code>), special functions include <code>cosinor(cov, period)</code> for modeling cyclical patterns, spline functions (<code>bs</code>, <code>ns</code>, <code>bSpline</code>, <code>cSpline</code>, <code>iSpline</code>, and <code>mSpline</code>), and state- or parameter-specific formulas (see details). Any formula terms that are not state- or parameter-specific are included on all of the transition rates.</p> |
| formulaDelta | <p>Regression formula for the initial distribution. Default: <code>NULL</code> (no covariate effects and <code>delta</code> is specified on the real scale). Standard functions in R formulas are allowed (e.g., <code>cos(cov)</code>, <code>cov1*cov2</code>, <code>I(cov^2)</code>). When any formula is provided, then <code>delta</code> must be specified on the working scale.</p> |
| mixtures | Number of mixtures for the state transition probabilities (i.e. discrete random effects <i>sensu</i> DeRuiter et al. 2017). Default: <code>mixtures=1</code> . |
| formulaPi | <p>Regression formula for the mixture distribution probabilities. Default: <code>NULL</code> (no covariate effects; both <code>beta\$pi</code> and <code>fixPar\$pi</code> are specified on the real scale). Standard functions in R formulas are allowed (e.g., <code>cos(cov)</code>, <code>cov1*cov2</code>, <code>I(cov^2)</code>). When any formula is provided, then both <code>beta\$pi</code> and <code>fixPar\$pi</code> are specified on the working scale. Note that only the covariate values corresponding to the first time step for each individual ID are used (i.e. time-varying covariates cannot be used for the mixture probabilities).</p> |
| covs | <p>Covariate values to include in the simulated data, as a dataframe. The names of any covariates specified by <code>covs</code> can be included in <code>formula</code> and/or <code>DM</code>. Covariates can also be simulated according to a standard normal distribution, by setting <code>covs</code> to <code>NULL</code> (the default), and specifying <code>nbCovs>0</code>.</p> |
| nbCovs | <p>Number of covariates to simulate (0 by default). Does not need to be specified if <code>covs</code> is specified. Simulated covariates are provided generic names (e.g., <code>'cov1'</code> and <code>'cov2'</code> for <code>nbCovs=2</code>) and can be included in <code>formula</code> and/or <code>DM</code>.</p> |
| rast | <p>A raster object or raster stack object that will define the discrete-space grid cells for the CTMC movement path. <code>spatialCovs</code> and <code>spatialCovs.grad</code> must have the same extent, number of rows and columns, projection, resolution, and origin as <code>rast</code>.</p> |
| spatialCovs | <p>List of <code>raster</code> objects for spatio-temporally referenced covariates. Covariates specified by <code>spatialCovs</code> are extracted from the raster layer(s) based on the</p> |

location data (and the z values for a raster `stack` or `brick`) for each time step. If an element of `spatialCovs` is a raster `stack` or `brick`, then z values must be set using `raster::setZ` and data must include column(s) of the corresponding z value(s) for each observation (e.g., 'Date'). In the `momentuHMMData` object returned by `prepCTDS`, covariates for the current position (e.g. \ for use in formula or DM) are named with a `.cur` suffix (e.g. `cov1.cur`).

`spatialCovs.grad`

List of `raster` objects for spatio-temporally referenced covariates, where a directional gradient is to be calculated internally using `rast.grad`. Gradient-based covariates specified by `spatialCovs.grad` are extracted from the raster layer(s) based on the location data (and the z values for a raster `stack` or `brick`) for each time step. If an element of `spatialCovs.grad` is a raster `stack` or `brick`, then z values must be set using `raster::setZ` and data must include column(s) of the corresponding z value(s) for each observation (e.g., 'Date').

`directions`

Integer. Either 4 (indicating a "Rook's neighborhood" of 4 neighboring grid cells) or 8 (indicating a "King's neighborhood" of 8 neighboring grid cells).

`normalize.gradients`

Logical. Default is `FALSE`. If `TRUE`, then all gradient covariates for `spatialCovs.grad` are normalized by dividing by the length of the gradient vector at each point.

`grad.point.decreasing`

Logical. If `TRUE`, then the gradient covariates are positive in the direction of decreasing values of the covariate. If `FALSE`, then the gradient covariates are positive in the direction of increasing values of the covariate (like a true gradient).

`zero.idx`

Integer vector of the indices of raster cells that are not passable and should be excluded. These are cells where movement should be impossible. Default is `zero.idx=integer()`.

`moveState`

Logical indicating whether or not transitions out of the current state are forbidden when the animal does not move out of the current cell. Default: `FALSE`. Note that if `moveState` is `TRUE`, then the realized state transition rates will not accurately reflect beta.

`obsPerAnimal`

Either the number of observations per animal (if single value) or the bounds of the number of observations per animal (if vector of two values). In the latter case, the numbers of observations generated for each animal are uniformly picked from this interval. Alternatively, `obsPerAnimal` can be specified as a list of length `nbAnimals` with each element providing the number of observations (if single value) or the bounds (if vector of two values) for each individual. Default: `c(500,1500)`.

`initialPosition`

2-vector providing the x- and y-coordinates of the initial position for all animals. Alternatively, `initialPosition` can be specified as a list of length `nbAnimals` with each element a 2-vector providing the x- and y-coordinates of the initial position for each individual. Default: `c(0,0)`. If `mvnCoord` corresponds to a data stream with "mvnorm3" or "rw_mvnorm3" probability distributions, then `initialPosition` must be composed of 3-vector(s) for the x-, y-, and z-coordinates.

| | |
|---------------|---|
| DM | An optional named list indicating the design matrices to be used for the probability distribution parameters of each data stream. Each element of DM can either be a named list of regression formulas or a “pseudo” design matrix. |
| userBounds | An optional named list of 2-column matrices specifying bounds on the natural (i.e., real) scale of the probability distribution parameters for each data stream. |
| workBounds | An optional named list of 2-column matrices specifying bounds on the working scale of the probability distribution, transition probability, and initial distribution parameters. For each matrix, the first column pertains to the lower bound and the second column the upper bound. For data streams, each element of workBounds should be a $k \times 2$ matrix with the same name of the corresponding element of Par, where k is the number of parameters. For transition rate parameters, the corresponding element of workBounds must be a $k \times 2$ matrix named “beta”, where $k = \text{length}(\text{beta})$. For initial distribution parameters, the corresponding element of workBounds must be a $k \times 2$ matrix named “delta”, where $k = \text{length}(\text{delta})$. workBounds is ignored for any given data stream unless DM is also specified. |
| betaRef | Numeric vector of length nbStates indicating the reference elements for the state transition rate matrix. Default: NULL, in which case the diagonal elements of the transition rate matrix are the reference. |
| stateNames | Optional character vector of length nbStates indicating state names. |
| model | A <code>momentuHMM</code> , <code>miHMM</code> , or <code>miSum</code> object. This option can be used to simulate from a fitted model. Default: NULL. Note that, if this argument is specified, most other arguments will be ignored – except for <code>nbAnimals</code> , <code>obsPerAnimal</code> , <code>states</code> , <code>initialPosition</code> , <code>lambda</code> , <code>errorEllipse</code> , and, if covariate values different from those in the data should be specified, <code>covs</code> , and <code>spatialCovs</code> . It is not appropriate to simulate movement data from a model that was fitted to latitude/longitude data (because <code>simData</code> assumes Cartesian coordinates). |
| matchModelObs | If <code>model</code> is provided, logical indicating whether to match <code>nbAnimals</code> , <code>obsPerAnimal</code> , and observation times to the fitted model data. If TRUE, then <code>nbAnimals</code> , <code>obsPerAnimal</code> , and <code>lambda</code> are ignored. Default: TRUE. |
| states | TRUE if the simulated states should be returned, FALSE otherwise (default). |
| lambda | Observation rate. <code>lambda</code> is the rate parameter of the exponential distribution for the waiting times between successive observations, i.e., $1/\text{lambda}$ is the expected time between successive location observations. If <code>model</code> is specified and <code>model\$data</code> time column is of class <code>date-time</code> or <code>date</code> , <code>lambda</code> has the same units as the <code>Time.unit</code> argument in <code>prepCTDS</code> . Default: 1. |
| errorEllipse | List providing the upper bound for the semi-major axis (M ; on scale of x - and y -coordinates), semi-minor axis (m ; on scale of x - and y -coordinates), and orientation (r ; in degrees) of location error ellipses. If NULL (the default), no location measurement error is simulated. If <code>errorEllipse</code> is specified, then each observed location is subject to bivariate normal errors as described in McClintock et al. (2015), where the components of the error ellipse for each location are randomly drawn from <code>runif(1, min(errorEllipse\$M), max(errorEllipse\$M))</code> , <code>runif(1, min(errorEllipse\$m), max(errorEllipse\$m))</code> , and <code>runif(1, min(errorEllipse\$r), max(errorEllipse\$r))</code> . If only a single value is provided for any of the error ellipse elements, then the |

| | |
|------------|--|
| | corresponding component is fixed to this value for each location. Only coordinate data streams are subject to location measurement error; any other data streams are observed without error. |
| ncores | Number of cores to use for parallel processing. Default: 1 (no parallel processing). |
| export | Character vector of the names of any additional objects or functions in the global environment that are used in DM, formula, formulaDelta, and/or formulaPi. Only necessary if ncores>1 so that the needed items will be exported to the workers. |
| keepSwitch | Logical indicating whether or not to return the (typically unobserved) data at the times when potential state switches could have occurred. Default: FALSE. If set to TRUE, an additional logical field named isObs is returned, where TRUE indicates observations and FALSE indicates state switches. |
| kappa | List of the form <code>list(method=c("all", "random", "quantile"), nspCov=NA, spCov=NA)</code> defining the method for obtaining the upper bound for the transition rate out of the current state (see Blackwell et al. 2016). The list can include up to three named objects: 1) method, a character string indicating the method for calculating the upper bound based on the covariates in the model ("all", "random", or "quantile"); 2) nspCov, a positive scalar for subsampling the non-spatial covariates (when method="random" or method="quantile"); and spCov, a positive scalar for subsampling the spatial covariates (when method="random" or method="quantile"). Default method is "all", in which case kappa is calculated based on all of the observed covariate values (note this can be slow and/or memory could become an issue for large datasets and/or rasters). For method="random", the observed covariates are subsampled with up to nspCov samples of any non-spatial covariates and up to spCov samples of any spatial covariates (defaults are 1000 for nspCov and 10000 for spCov). For method="quantile", all combinations of 100-length sequences spanning the (nspCov/2, 1-nspCov/2) and (spCov/2, 1-spCov/2) quantiles of the covariates are used (defaults are 0.05 for both nspCov and spCov). Ignored unless covariates are included in formula. Alternatively, kappa can be manually specified as a finite positive scalar (instead of a list) indicating the maximum allowed value for the row sums of the off-diagonal elements in the state transition rate matrix, such that the minimum value for the diagonal elements is -kappa. In this case, the transition rate parameters (beta) are specified on the logit scale (instead of the log scale). If model is provided and kappa is NULL, then kappa is set to <code>model\$conditions\$kappa</code> (see fitCTHMM). |

Details

- simCTDS assumes the snapshot property applies to all data stream distributions (i.e. observations are "instantaneous") except for the continuous-time discrete-space (ctds), (multivariate) normal random walk (`rw_norm`, `rw_mvnorm2`, `rw_mvnorm3`), and Poisson (`pois`) distributions. For these particular distributions, the observed data are not "instantaneous"; they depend on the time interval between observations (Δ_t) and, hence, the state sequence during the entire interval. If fitting with [fitCTHMM](#) (or [MIFitCTHMM](#)), it is critical that the frequency of observations (specified by `lambda`) is high relative to the serial correlation in the hidden state process

(specified by `beta`) in order for the discrete-time approximation of `fitCTHMM` to be reasonably accurate for these distributions.

- If the length of covariate values passed (either through `'covs'`, or `'model'`) is not the same as the number of observations suggested by `'nbAnimals'` and `'obsPerAnimal'`, then the series of covariates is either shortened (removing last values - if too long) or extended (starting over from the first values - if too short).
- When covariates are not included in `formulaDelta` (i.e. `formulaDelta=NULL`), then `delta` is specified as a vector of length `nbStates` that sums to 1. When covariates are included in `formulaDelta`, then `delta` must be specified as a $k \times (\text{nbStates}-1)$ matrix of working parameters, where k is the number of regression coefficients and the columns correspond to states 2:nbStates. For example, in a 3-state HMM with `formulaDelta=~cov1+cov2`, the matrix `delta` has three rows (intercept + two covariates) and 2 columns (corresponding to states 2 and 3). The initial distribution working parameters are transformed to the real scale as $\exp(\text{covsDelta} * \text{Delta}) / \text{rowSums}(\exp(\text{covsDelta} * \text{Delta}))$, where `covsDelta` is the $N \times k$ design matrix, `Delta=cbind(rep(0,k),delta)` is a $k \times \text{nbStates}$ matrix of working parameters, and $N=\text{length}(\text{unique}(\text{data}\$ID))$.

Value

If the simulated data have no measurement error (i.e., `errorEllipse=NULL`), a `momentuHMMData` object, i.e., a dataframe of:

| | |
|------|--|
| ID | The ID(s) of the observed animal(s) |
| time | Numeric time of each observed observation |
| ... | Data streams as specified by <code>dist</code> |
| x | Easting location cell centroid |
| y | Northing location cell centroid |
| ... | Covariates (if any). If <code>moveState=TRUE</code> , then a covariate named <code>noMove</code> is included that indicates when no cell transition occurred (hence no transition out of the current state); the <code>noMove</code> covariate can then be used as a state transition probability covariate to forbid transitions from the current state when there is no cell movement. |

If simulated location data include measurement error (i.e., `errorEllipse!=NULL`), a dataframe of:

| | |
|------|---|
| ID | The ID(s) of the observed animal(s) |
| time | Numeric time of each observed (and missing) observation |
| z | Categorical index indicating observed cell movement (where $z=(\text{directions}+1)$ indicates no movement) |
| x | Easting observed location cell centroid |
| y | Northing observed location cell centroid |
| tau | Time difference between consecutive observations |
| ... | Data streams that are not derived from location (if applicable) |

| | |
|---------------------------|--|
| ... | Covariates at true (mux,muy) locations (if any) and neighboring cell locations (with suffixes indicating neighbor, e.g., cov.1, cov.2, ..., cov.directions). If moveState=TRUE, then a covariate named paste0("z", (directions+1)) is included that indicates when no cell transition occurred (hence no transition out of the current state). |
| mux | Easting true location cell centroid |
| muy | Northingtrue location cell centroid |
| error_semimajor_axis | error ellipse semi-major axis (if applicable) |
| error_semiminor_axis | error ellipse semi-minor axis (if applicable) |
| error_ellipse_orientation | error ellipse orientation (if applicable) |
| ln.sd.x | log of the square root of the x-variance of bivariate normal error (if applicable; required for error ellipse models in crawlWrap) |
| ln.sd.y | log of the square root of the y-variance of bivariate normal error (if applicable; required for error ellipse models in crawlWrap) |
| error.corr | correlation term of bivariate normal error (if applicable; required for error ellipse models in crawlWrap) |

simCTHMM

Simulation tool

Description

Simulates data from a (multivariate) continuous-time hidden Markov model based on Blackwell et al. (2016), where specification of kappa determines the potential times of state switches when formula includes covariates (larger kappa means potential switches are more frequent). Note that any time-varying covariates are assumed piece-wise constant between observations. Movement data are assumed to be in Cartesian coordinates (not longitude/latitude) and can be generated with or without observation error attributable to location measurement error.

Usage

```
simCTHMM(
  nbAnimals = 1,
  nbStates = 2,
  dist,
  Par,
  beta = NULL,
  delta = NULL,
  formula = ~1,
  formulaDelta = NULL,
  mixtures = 1,
  formulaPi = NULL,
```



```

covs = NULL,
nbCovs = 0,
spatialCovs = NULL,
obsPerAnimal = c(500, 1500),
initialPosition = c(0, 0),
DM = NULL,
userBounds = NULL,
workBounds = NULL,
betaRef = NULL,
mvnCoords = NULL,
stateNames = NULL,
model = NULL,
matchModelObs = FALSE,
states = FALSE,
retrySims = 0,
lambda = 1,
errorEllipse = NULL,
ncores = 1,
export = NULL,
gradient = FALSE,
keepSwitch = FALSE,
kappa = NULL,
TMB = FALSE
)

```

Arguments

| | |
|-----------|---|
| nbAnimals | Number of observed individuals to simulate. |
| nbStates | Number of behavioural states to simulate. |
| dist | A named list indicating the probability distributions of the data streams. |
| Par | <p>A named list containing vectors of initial state-dependent probability distribution parameters for each data stream specified in <code>dist</code>. The parameters should be in the order expected by the pdfs of <code>dist</code>.</p> <p>If <code>DM</code> is not specified for a given data stream, then <code>Par</code> is on the natural (i.e., real) scale of the parameters. However, if <code>DM</code> is specified for a given data stream, then <code>Par</code> must be on the working (i.e., beta) scale of the parameters, and the length of <code>Par</code> must match the number of columns in the design matrix. See details below.</p> |
| beta | Matrix of regression parameters for the transition rates. |
| delta | Initial distribution of the HMM. Default: <code>rep(1/nbStates, nbStates)</code> . If <code>formulaDelta</code> includes a formula, then <code>delta</code> must be specified as a $k \times (nbStates-1)$ matrix, where k is the number of covariates and the columns correspond to states 2:nbStates. |
| formula | Regression formula for the transition rate covariates. Default: <code>~1</code> (no covariate effect). In addition to allowing standard functions in R formulas (e.g., <code>cos(cov)</code> , <code>cov1*cov2</code> , <code>I(cov^2)</code>), special functions include <code>cosinor(cov, period)</code> for modeling cyclical patterns, spline functions (<code>bs</code> , <code>ns</code> , <code>bSpline</code> , <code>cSpline</code> , <code>iSpline</code> , |

and `mSpline`), and state- or parameter-specific formulas (see details). Any formula terms that are not state- or parameter-specific are included on all of the transition rates.

| | |
|------------------------------|--|
| <code>formulaDelta</code> | Regression formula for the initial distribution. Default: NULL (no covariate effects and <code>delta</code> is specified on the real scale). Standard functions in R formulas are allowed (e.g., <code>cos(cov)</code> , <code>cov1*cov2</code> , <code>I(cov^2)</code>). When any formula is provided, then <code>delta</code> must be specified on the working scale. |
| <code>mixtures</code> | Number of mixtures for the state transition probabilities (i.e. discrete random effects <i>sensu</i> DeRuiter et al. 2017). Default: <code>mixtures=1</code> . |
| <code>formulaPi</code> | Regression formula for the mixture distribution probabilities. Default: NULL (no covariate effects; both <code>beta\$pi</code> and <code>fixPar\$pi</code> are specified on the real scale). Standard functions in R formulas are allowed (e.g., <code>cos(cov)</code> , <code>cov1*cov2</code> , <code>I(cov^2)</code>). When any formula is provided, then both <code>beta\$pi</code> and <code>fixPar\$pi</code> are specified on the working scale. Note that only the covariate values corresponding to the first time step for each individual ID are used (i.e. time-varying covariates cannot be used for the mixture probabilities). |
| <code>covs</code> | Covariate values to include in the simulated data, as a dataframe. The names of any covariates specified by <code>covs</code> can be included in <code>formula</code> and/or <code>DM</code> . Covariates can also be simulated according to a standard normal distribution, by setting <code>covs</code> to NULL (the default), and specifying <code>nbCovs>0</code> . |
| <code>nbCovs</code> | Number of covariates to simulate (0 by default). Does not need to be specified if <code>covs</code> is specified. Simulated covariates are provided generic names (e.g., <code>'cov1'</code> and <code>'cov2'</code> for <code>nbCovs=2</code>) and can be included in <code>formula</code> and/or <code>DM</code> . |
| <code>spatialCovs</code> | List of <code>raster</code> objects for spatio-temporally referenced covariates. Covariates specified by <code>spatialCovs</code> are extracted from the raster layer(s) based on any simulated location data (and the z values for a raster <code>stack</code> or <code>brick</code>) for each time step. If an element of <code>spatialCovs</code> is a raster <code>stack</code> or <code>brick</code> , then z values must be set using <code>raster::setZ</code> and <code>covs</code> must include column(s) of the corresponding z value(s) for each observation (e.g., <code>'time'</code>). The names of the raster layer(s) can be included in <code>formula</code> and/or <code>DM</code> . Note that <code>simCTHMM</code> usually takes longer to generate simulated data when <code>spatialCovs</code> is specified. |
| <code>obsPerAnimal</code> | Either the number of observations per animal (if single value) or the bounds of the number of observations per animal (if vector of two values). In the latter case, the numbers of observations generated for each animal are uniformly picked from this interval. Alternatively, <code>obsPerAnimal</code> can be specified as a list of length <code>nbAnimals</code> with each element providing the number of observations (if single value) or the bounds (if vector of two values) for each individual. Default: <code>c(500, 1500)</code> . |
| <code>initialPosition</code> | 2-vector providing the x- and y-coordinates of the initial position for all animals. Alternatively, <code>initialPosition</code> can be specified as a list of length <code>nbAnimals</code> with each element a 2-vector providing the x- and y-coordinates of the initial position for each individual. Default: <code>c(0, 0)</code> . If <code>mvnCoord</code> corresponds to a data stream with <code>"mvnrm3"</code> or <code>"rw_mvnorm3"</code> probability distributions, then <code>initialPosition</code> must be composed of 3-vector(s) for the x-, y-, and z-coordinates. |

| | |
|---------------|--|
| DM | An optional named list indicating the design matrices to be used for the probability distribution parameters of each data stream. Each element of DM can either be a named list of regression formulas or a “pseudo” design matrix. |
| userBounds | An optional named list of 2-column matrices specifying bounds on the natural (i.e, real) scale of the probability distribution parameters for each data stream. |
| workBounds | An optional named list of 2-column matrices specifying bounds on the working scale of the probability distribution, transition probability, and initial distribution parameters. For each matrix, the first column pertains to the lower bound and the second column the upper bound. For data streams, each element of workBounds should be a k x 2 matrix with the same name of the corresponding element of Par, where k is the number of parameters. For transition rate parameters, the corresponding element of workBounds must be a k x 2 matrix named “beta”, where k=length(beta). For initial distribution parameters, the corresponding element of workBounds must be a k x 2 matrix named “delta”, where k=length(delta). workBounds is ignored for any given data stream unless DM is also specified. |
| betaRef | Numeric vector of length nbStates indicating the reference elements for the state transition rate matrix. Default: NULL, in which case the diagonal elements of the transition rate matrix are the reference. |
| mvnCoords | Character string indicating the name of location data that are to be simulated using a multivariate normal distribution. For example, if mu="rw_mvnorm2" was included in dist and (mu.x, mu.y) are intended to be location data, then mvnCoords="mu" needs to be specified in order for these data to be treated as such. |
| stateNames | Optional character vector of length nbStates indicating state names. |
| model | A <code>momentuHMM</code> , <code>miHMM</code> , or <code>miSum</code> object. This option can be used to simulate from a fitted model. Default: NULL. Note that, if this argument is specified, most other arguments will be ignored – except for <code>nbAnimals</code> , <code>obsPerAnimal</code> , <code>states</code> , <code>initialPosition</code> , <code>lambda</code> , <code>errorEllipse</code> , and, if covariate values different from those in the data should be specified, <code>covs</code> , and <code>spatialCovs</code> . It is not appropriate to simulate movement data from a model that was fitted to latitude/longitude data (because simCTHMM assumes Cartesian coordinates). |
| matchModelObs | If model is provided, logical indicating whether to match <code>nbAnimals</code> , <code>obsPerAnimal</code> , and observation times to the fitted model data. If TRUE, then <code>nbAnimals</code> , <code>obsPerAnimal</code> , and <code>lambda</code> are ignored. Furthermore, if TRUE and <code>initialPosition</code> is not compatible with any <code>spatialCovs</code> , then the initial position for each animal from the fitted model data is used. Default: FALSE. |
| states | TRUE if the simulated states should be returned, FALSE otherwise (default). |
| retrySims | Number of times to attempt to simulate data within the spatial extent of <code>spatialCovs</code> . If <code>retrySims=0</code> (the default), an error is returned if the simulated tracks(s) move beyond the extent(s) of the raster layer(s). Instead of relying on <code>retrySims</code> , in many cases it might be better to simply expand the extent of the raster layer(s) and/or adjust the movement parameters. Ignored if <code>spatialCovs=NULL</code> . |
| lambda | Observation rate. <code>lambda</code> is the rate parameter of the exponential distribution for the waiting times between successive observations, i.e., $1/\lambda$ is the expected time between successive location observations. If model is specified and |

| | |
|--------------|--|
| | <p>model\$data time column is of class <code>date-time</code> or <code>date</code>, lambda has the same units as the <code>Time.unit</code> argument in <code>prepData</code>. Default: 1. Alternatively lambda can be specified as a list of length <code>nbAnimals</code> providing the exact observation times for each individual.</p> |
| errorEllipse | <p>List providing the upper bound for the semi-major axis (M; on scale of x- and y-coordinates), semi-minor axis (m; on scale of x- and y-coordinates), and orientation (r; in degrees) of location error ellipses. If NULL (the default), no location measurement error is simulated. If <code>errorEllipse</code> is specified, then each observed location is subject to bivariate normal errors as described in McClintock et al. (2015), where the components of the error ellipse for each location are randomly drawn from <code>runif(1,min(errorEllipse\$M),max(errorEllipse\$M))</code>, <code>runif(1,min(errorEllipse\$m),max(errorEllipse\$m))</code>, and <code>runif(1,min(errorEllipse\$r),max(errorEllipse\$r))</code>. If only a single value is provided for any of the error ellipse elements, then the corresponding component is fixed to this value for each location. Only coordinate data streams are subject to location measurement error; any other data streams are observed without error.</p> |
| ncores | <p>Number of cores to use for parallel processing. Default: 1 (no parallel processing).</p> |
| export | <p>Character vector of the names of any additional objects or functions in the global environment that are used in <code>DM</code>, <code>formula</code>, <code>formulaDelta</code>, and/or <code>formulaPi</code>. Only necessary if <code>ncores>1</code> so that the needed items will be exported to the workers.</p> |
| gradient | <p>Logical indicating whether or not to calculate gradients of <code>spatialCovs</code> using bilinear interpolation (e.g. for inclusion in potential functions). Default: FALSE. If TRUE, the gradients are returned with “.x” (easting gradient) and “.y” (northing gradient) suffixes added to the names of <code>spatialCovs</code>. For example, if <code>cov1</code> is the name of a spatial covariate, then the returned <code>momentuHMMData</code> object will include the fields “cov1.x” and “cov1.y”.</p> |
| keepSwitch | <p>Logical indicating whether or not to return the (typically unobserved) data at the times when potential state switches could have occurred. Default: FALSE. If set to TRUE, an additional logical field named <code>isObs</code> is returned, where TRUE indicates observations and FALSE indicates state switches.</p> |
| kappa | <p>List of the form <code>list(method=c("all", "random", "quantile"), nspCov=NA, spCov=NA)</code> defining the method for obtaining the upper bound for the transition rate out of the current state (see Blackwell et al. 2016). The list can include up to three named objects: 1) <code>method</code>, a character string indicating the method for calculating the upper bound based on the covariates in the model (“all”, “random”, or “quantile”); 2) <code>nspCov</code>, a positive scalar for subsampling the non-spatial covariates (when <code>method="random"</code> or <code>method="quantile"</code>); and <code>spCov</code>, a positive scalar for subsampling the spatial covariates (when <code>method="random"</code> or <code>method="quantile"</code>). Default method is “all”, in which case <code>kappa</code> is calculated based on all of the observed covariate values (note this can be slow and/or memory could become an issue for large datasets and/or rasters). For <code>method="random"</code>, the observed covariates are subsampled with up to <code>nspCov</code> samples of any non-spatial covariates and up to <code>spCov</code> samples of any spatial covariates (defaults are 1000 for <code>nspCov</code> and 10000 for <code>spCov</code>). For <code>method="quantile"</code>, all combinations of 100-length sequences spanning the (<code>nspCov/2</code>, <code>1-nspCov/2</code>)</p> |

and $(\text{spCov}/2, 1-\text{spCov}/2)$ quantiles of the covariates are used (defaults are 0.05 for both `nspCov` and `spCov`). Ignored unless covariates are included in `formula`. Alternatively, `kappa` can be manually specified as a finite positive scalar (instead of a list) indicating the maximum allowed value for the row sums of the off-diagonal elements in the state transition rate matrix, such that the minimum value for the diagonal elements is $-\text{kappa}$. In this case, the transition rate parameters (`beta`) are specified on the logit scale (instead of the log scale).

If `model` is provided and `kappa` is `NULL`, then `kappa` is set to `model$conditions$kappa` (see `fitCTHMM`).

TMB Logical indicating whether or not data should be simulated based on TMB model specifications. Default: `FALSE`. See `optMethod` argument in `fitCTHMM`. Ignored if `model` is specified.

Details

- `simCTHMM` assumes the snapshot property applies to all data stream distributions (i.e. observations are "instantaneous") except for the (multivariate) normal random walk (`rw_norm`, `rw_mvnorm2`, `rw_mvnorm3`) and Poisson (`pois`) distributions. For these particular distributions, the observed data are not "instantaneous"; they depend on the time interval between observations (Δ_t) and, hence, the state sequence during the entire interval. If fitting with `fitCTHMM` (or `MIfitCTHMM`), it is critical that the frequency of observations (specified by `lambda`) is high relative to the serial correlation in the hidden state process (specified by `beta`) in order for the discrete-time approximation of `fitCTHMM` to be reasonably accurate for these distributions.
- If the length of covariate values passed (either through `'covs'`, or `'model'`) is not the same as the number of observations suggested by `'nbAnimals'` and `'obsPerAnimal'`, then the series of covariates is either shortened (removing last values - if too long) or extended (starting over from the first values - if too short).
- When covariates are not included in `formulaDelta` (i.e. `formulaDelta=NULL`), then `delta` is specified as a vector of length `nbStates` that sums to 1. When covariates are included in `formulaDelta`, then `delta` must be specified as a $k \times (\text{nbStates}-1)$ matrix of working parameters, where k is the number of regression coefficients and the columns correspond to states 2:nbStates. For example, in a 3-state HMM with `formulaDelta=~cov1+cov2`, the matrix `delta` has three rows (intercept + two covariates) and 2 columns (corresponding to states 2 and 3). The initial distribution working parameters are transformed to the real scale as $\exp(\text{covsDelta} * \text{Delta}) / \text{rowSums}(\exp(\text{covsDelta} * \text{Delta}))$, where `covsDelta` is the $N \times k$ design matrix, `Delta=cbind(rep(0,k),delta)` is a $k \times \text{nbStates}$ matrix of working parameters, and $N=\text{length}(\text{unique}(\text{data}\$ID))$.

Value

If the simulated data have no measurement error (i.e., `errorEllipse=NULL`), a `momentuHMMData` object, i.e., a dataframe of:

| | |
|-------------------|--|
| <code>ID</code> | The ID(s) of the observed animal(s) |
| <code>time</code> | Numeric time of each observed observation |
| <code>...</code> | Data streams as specified by <code>dist</code> |

| | |
|-----|--|
| x | Either easting or longitude (if data streams include valid non-negative distribution for 'step') |
| y | Either northing or latitude (if data streams include valid non-negative distribution for 'step') |
| ... | Covariates (if any) |

If simulated location data include measurement error (i.e., `errorEllipse!=NULL`), a dataframe of:

| | |
|---------------------------|---|
| ID | The ID(s) of the observed animal(s) |
| time | Numeric time of each observed (and missing) observation |
| x | Either easting or longitude observed location |
| y | Either northing or latitude observed location |
| ... | Data streams that are not derived from location (if applicable) |
| ... | Covariates at true (<code>mux,muy</code>) locations (if any) |
| mux | Either easting or longitude true location |
| muy | Either northing or latitude true location |
| error_semimajor_axis | error ellipse semi-major axis (if applicable) |
| error_semiminor_axis | error ellipse semi-minor axis (if applicable) |
| error_ellipse_orientation | error ellipse orientation (if applicable) |
| ln.sd.x | log of the square root of the x-variance of bivariate normal error (if applicable; required for error ellipse models in crawlWrap) |
| ln.sd.y | log of the square root of the y-variance of bivariate normal error (if applicable; required for error ellipse models in crawlWrap) |
| error.corr | correlation term of bivariate normal error (if applicable; required for error ellipse models in crawlWrap) |

References

Blackwell, P.G., Niu, M., Lambert, M.S. and LaPoint, S.D., 2016. Exact Bayesian inference for animal movement in continuous time. *Methods in Ecology and Evolution*, 7 (2), 184-195.

simData

Simulation tool

Description

Simulates data from a (multivariate) hidden Markov model. Movement data are assumed to be in Cartesian coordinates (not longitude/latitude) and can be generated with or without observation error attributable to temporal irregularity or location measurement error.

Usage

```
simData(  
  nbAnimals = 1,  
  nbStates = 2,  
  dist,  
  Par,  
  beta = NULL,  
  delta = NULL,  
  formula = ~1,  
  formulaDelta = NULL,  
  mixtures = 1,  
  formulaPi = NULL,  
  covs = NULL,  
  nbCovs = 0,  
  spatialCovs = NULL,  
  zeroInflation = NULL,  
  oneInflation = NULL,  
  circularAngleMean = NULL,  
  centers = NULL,  
  centroids = NULL,  
  angleCovs = NULL,  
  obsPerAnimal = c(500, 1500),  
  initialPosition = c(0, 0),  
  DM = NULL,  
  userBounds = NULL,  
  workBounds = NULL,  
  betaRef = NULL,  
  mvnCoords = NULL,  
  stateNames = NULL,  
  model = NULL,  
  matchModelObs = FALSE,  
  states = FALSE,  
  retrySims = 0,  
  lambda = NULL,  
  errorEllipse = NULL,  
  ncores = 1,  
  export = NULL,  
  gradient = FALSE,  
  TMB = FALSE,  
  ...  
)  
  
simHierData(  
  nbAnimals = 1,  
  hierStates,  
  hierDist,  
  Par,  
  hierBeta = NULL,
```

```

hierDelta = NULL,
hierFormula = NULL,
hierFormulaDelta = NULL,
mixtures = 1,
formulaPi = NULL,
covs = NULL,
nbHierCovs = NULL,
spatialCovs = NULL,
zeroInflation = NULL,
oneInflation = NULL,
circularAngleMean = NULL,
centers = NULL,
centroids = NULL,
angleCovs = NULL,
obsPerLevel,
initialPosition = c(0, 0),
DM = NULL,
userBounds = NULL,
workBounds = NULL,
mvnCoords = NULL,
model = NULL,
matchModelObs = FALSE,
states = FALSE,
retrySims = 0,
lambda = NULL,
errorEllipse = NULL,
ncores = 1,
export = NULL,
gradient = FALSE,
TMB = FALSE,
...
)

```

Arguments

| | |
|------------------------|--|
| <code>nbAnimals</code> | Number of observed individuals to simulate. |
| <code>nbStates</code> | Number of behavioural states to simulate. |
| <code>dist</code> | A named list indicating the probability distributions of the data streams. Currently supported distributions are 'bern', 'beta', 'cat', 'exp', 'gamma', 'lnorm', 'logis', 'negbinom', 'norm', 'mvnorm2' (bivariate normal distribution), 'mvnorm3' (trivariate normal distribution), 'pois', 'rw_norm' (normal random walk), 'rw_mvnorm2' (bivariate normal random walk), 'rw_mvnorm3' (trivariate normal random walk), 'vm', 'vmConsensus', 'weibull', and 'wrpcauchy'. For example, <code>dist=list(step='gamma', angle='vm', dives='pois')</code> indicates 3 data streams ('step', 'angle', and 'dives') and their respective probability distributions ('gamma', 'vm', and 'pois'). |
| <code>Par</code> | A named list containing vectors of initial state-dependent probability distribution parameters for each data stream specified in <code>dist</code> . The parameters should be in the order expected by the pdfs of <code>dist</code> , and any zero-mass and/or one-mass |

parameters should be the last (if both are present, then zero-mass parameters must precede one-mass parameters).

If DM is not specified for a given data stream, then Par is on the natural (i.e., real) scale of the parameters. However, if DM is specified for a given data stream, then Par must be on the working (i.e., beta) scale of the parameters, and the length of Par must match the number of columns in the design matrix. See details below.

| | |
|--------------|---|
| beta | Matrix of regression parameters for the transition probabilities (more information in "Details"). |
| delta | Initial distribution of the HMM. Default: <code>rep(1/nbStates, nbStates)</code> . If <code>formulaDelta</code> includes a formula, then <code>delta</code> must be specified as a $k \times (nbStates-1)$ matrix, where k is the number of covariates and the columns correspond to states 2:nbStates. See details below. |
| formula | Regression formula for the transition probability covariates. Default: <code>~1</code> (no covariate effect). In addition to allowing standard functions in R formulas (e.g., <code>cos(cov)</code> , <code>cov1*cov2</code> , <code>I(cov^2)</code>), special functions include <code>cosinor(cov, period)</code> for modeling cyclical patterns, spline functions (<code>bs</code> , <code>ns</code> , <code>bSpline</code> , <code>cSpline</code> , <code>iSpline</code> , and <code>mSpline</code>), and state- or parameter-specific formulas (see details). Any formula terms that are not state- or parameter-specific are included on all of the transition probabilities. |
| formulaDelta | Regression formula for the initial distribution. Default: NULL (no covariate effects and <code>delta</code> is specified on the real scale). Standard functions in R formulas are allowed (e.g., <code>cos(cov)</code> , <code>cov1*cov2</code> , <code>I(cov^2)</code>). When any formula is provided, then <code>delta</code> must be specified on the working scale. |
| mixtures | Number of mixtures for the state transition probabilities (i.e. discrete random effects *sensu* DeRuiter et al. 2017). Default: <code>mixtures=1</code> . |
| formulaPi | Regression formula for the mixture distribution probabilities. Default: NULL (no covariate effects; both <code>beta\$pi</code> and <code>fixPar\$pi</code> are specified on the real scale). Standard functions in R formulas are allowed (e.g., <code>cos(cov)</code> , <code>cov1*cov2</code> , <code>I(cov^2)</code>). When any formula is provided, then both <code>beta\$pi</code> and <code>fixPar\$pi</code> are specified on the working scale. Note that only the covariate values corresponding to the first time step for each individual ID are used (i.e. time-varying covariates cannot be used for the mixture probabilities). |
| covs | Covariate values to include in the simulated data, as a dataframe. The names of any covariates specified by <code>covs</code> can be included in <code>formula</code> and/or DM. Covariates can also be simulated according to a standard normal distribution, by setting <code>covs</code> to NULL (the default), and specifying <code>nbCovs>0</code> . |
| nbCovs | Number of covariates to simulate (0 by default). Does not need to be specified if <code>covs</code> is specified. Simulated covariates are provided generic names (e.g., <code>'cov1'</code> and <code>'cov2'</code> for <code>nbCovs=2</code>) and can be included in <code>formula</code> and/or DM. |
| spatialCovs | List of <code>raster</code> objects for spatio-temporally referenced covariates. Covariates specified by <code>spatialCovs</code> are extracted from the raster layer(s) based on any simulated location data (and the z values for a raster <code>stack</code> or <code>brick</code>) for each time step. If an element of <code>spatialCovs</code> is a raster <code>stack</code> or <code>brick</code> , then z values must be set using <code>raster::setZ</code> and <code>covs</code> must include column(s) of the corresponding z value(s) for each observation (e.g., <code>'time'</code>). The names of the raster layer(s) can be included in <code>formula</code> and/or DM. Note that <code>simData</code> usually takes longer to generate simulated data when <code>spatialCovs</code> is specified. |

- zeroInflation** A named list of logicals indicating whether the probability distributions of the data streams should be zero-inflated. If `zeroInflation` is TRUE for a given data stream, then values for the zero-mass parameters should be included in the corresponding element of `Par`.
- oneInflation** A named list of logicals indicating whether the probability distributions of the data streams should be one-inflated. If `oneInflation` is TRUE for a given data stream, then values for the one-mass parameters should be included in the corresponding element of `Par`.
- circularAngleMean**
 An optional named list indicating whether to use circular-linear (FALSE) or circular-circular (TRUE) regression on the mean of circular distributions ('vm' and 'wrpcauchy') for turning angles. For example, `circularAngleMean=list(angle=TRUE)` indicates the angle mean is to be estimated for 'angle' using circular-circular regression. Whenever circular-circular regression is used for an angular data stream, a corresponding design matrix (DM) must be specified for the data stream, and the previous movement direction (i.e., a turning angle of zero) is automatically used as the reference angle (i.e., the intercept). Default is NULL, which assumes circular-linear regression is used for any angular distributions. Any `circularAngleMean` elements corresponding to data streams that do not have angular distributions are ignored. `circularAngleMean` is also ignored for any 'vmConsensus' data streams (because the consensus model is a circular-circular regression model).
 Alternatively, `circularAngleMean` can be specified as a numeric scalar, where the value specifies the coefficient for the reference angle (i.e., directional persistence) term in the circular-circular regression model. For example, setting `circularAngleMean` to 0 specifies a circular-circular regression model with no directional persistence term (thus specifying a biased random walk instead of a biased correlated random walk). Setting `circularAngleMean` to 1 is equivalent to setting it to TRUE, i.e., a circular-circular regression model with a coefficient of 1 for the directional persistence reference angle.
- centers** 2-column matrix providing the x-coordinates (column 1) and y-coordinates (column 2) for any activity centers (e.g., potential centers of attraction or repulsion) from which distance and angle covariates will be calculated based on the simulated location data. These distance and angle covariates can be included in `formula` and `DM` using the row names of `centers`. If no row names are provided, then generic names are generated for the distance and angle covariates (e.g., 'center1.dist', 'center1.angle', 'center2.dist', 'center2.angle'); otherwise the covariate names are derived from the row names of `centers` as `paste0(rep(rownames(centers), each=2), c(".dist", ".angle"))`. Note that the angle covariates for each activity center are calculated relative to the previous movement direction instead of standard directions relative to the x-axis; this is to allow turning angles to be simulated as a function of these covariates using circular-circular regression.
- centroids** List where each element is a data frame consisting of at least `max(unlist(obsPerAnimal))` rows that provides the x-coordinates ('x') and y-coordinates ('y') for centroids (i.e., dynamic activity centers where the coordinates can change for each time step) from which distance and angle covariates will be calculated based on the

For example, for a 2-state model using the wrapped Cauchy (`'wrpcauchy'`) distribution for a data stream named `'angle'` with `estAngleMean$angle=TRUE`), `userBounds=list(angle=matrix(c(-pi,-pi,-1,-1,pi,pi,1,1),4,2,dimnames=list(c("mean_1"`

| | |
|---------------|---|
| workBounds | An optional named list of 2-column matrices specifying bounds on the working scale of the probability distribution, transition probability, and initial distribution parameters. For each matrix, the first column pertains to the lower bound and the second column the upper bound. For data streams, each element of workBounds should be a k x 2 matrix with the same name of the corresponding element of Par, where k is the number of parameters. For transition probability parameters, the corresponding element of workBounds must be a k x 2 matrix named “beta”, where k=length(beta). For initial distribution parameters, the corresponding element of workBounds must be a k x 2 matrix named “delta”, where k=length(delta). workBounds is ignored for any given data stream unless DM is also specified. |
| betaRef | Numeric vector of length nbStates indicating the reference elements for the t.p.m. multinomial logit link. Default: NULL, in which case the diagonal elements of the t.p.m. are the reference. See fithMM . |
| mvnCoords | Character string indicating the name of location data that are to be simulated using a multivariate normal distribution. For example, if mu="rw_mvnorm2" was included in dist and (mu.x, mu.y) are intended to be location data, then mvnCoords="mu" needs to be specified in order for these data to be treated as such. |
| stateNames | Optional character vector of length nbStates indicating state names. |
| model | A momentuHMM , momentuHierHMM , miHMM , or miSum object. This option can be used to simulate from a fitted model. Default: NULL. Note that, if this argument is specified, most other arguments will be ignored – except for nbAnimals, obsPerAnimal, states, initialPosition, lambda, errorEllipse, and, if covariate values different from those in the data should be specified, covs, spatialCovs, centers, and centroids. It is not appropriate to simulate movement data from a model that was fitted to latitude/longitude data (because simData assumes Cartesian coordinates). |
| matchModelObs | If model is provided, logical indicating whether to match nbAnimals and obsPerAnimal to the fitted model data. If TRUE, then nbAnimals and obsPerAnimal are ignored. Furthermore, if TRUE and initialPosition is not compatible with any spatialCovs, then the initial position for each animal from the fitted model data is used. Default: FALSE. |
| states | TRUE if the simulated states should be returned, FALSE otherwise (default). |
| retrySims | Number of times to attempt to simulate data within the spatial extent of spatialCovs. If retrySims=0 (the default), an error is returned if the simulated tracks(s) move beyond the extent(s) of the raster layer(s). Instead of relying on retrySims, in many cases it might be better to simply expand the extent of the raster layer(s) and/or adjust the step length and turning angle probability distributions. Ignored if spatialCovs=NULL. |

| | |
|--------------|--|
| lambda | Observation rate for location data. If NULL (the default), location data are obtained at regular intervals. Otherwise lambda is the rate parameter of the exponential distribution for the waiting times between successive location observations, i.e., 1/lambda is the expected time between successive location observations. Only the 'step' and 'angle' data streams are subject to temporal irregularity; any other data streams are observed at temporally-regular intervals. Ignored unless a valid distribution for the 'step' data stream is specified. |
| errorEllipse | List providing the upper bound for the semi-major axis (M; on scale of x- and y-coordinates), semi-minor axis (m; on scale of x- and y-coordinates), and orientation (r; in degrees) of location error ellipses. If NULL (the default), no location measurement error is simulated. If errorEllipse is specified, then each observed location is subject to bivariate normal errors as described in McClintock et al. (2015), where the components of the error ellipse for each location are randomly drawn from <code>runif(1,min(errorEllipse\$M),max(errorEllipse\$M))</code> , <code>runif(1,min(errorEllipse\$m),max(errorEllipse\$m))</code> , and <code>runif(1,min(errorEllipse\$r),max(errorEllipse\$r))</code> . If only a single value is provided for any of the error ellipse elements, then the corresponding component is fixed to this value for each location. Only the 'step' and 'angle' data streams are subject to location measurement error; any other data streams are observed without error. Ignored unless a valid distribution for the 'step' data stream is specified. |
| ncores | Number of cores to use for parallel processing. Default: 1 (no parallel processing). |
| export | Character vector of the names of any additional objects or functions in the global environment that are used in DM, formula, formulaDelta, and/or formulaPi. Only necessary if ncores>1 so that the needed items will be exported to the workers. |
| gradient | Logical indicating whether or not to calculate gradients of spatialCovs using bilinear interpolation (e.g. for inclusion in potential functions). Default: FALSE. If TRUE, the gradients are returned with ".x" (easting gradient) and ".y" (northing gradient) suffixes added to the names of spatialCovs. For example, if cov1 is the name of a spatial covariate, then the returned <code>momentuHMMData</code> object will include the fields "cov1.x" and "cov1.y". |
| TMB | Logical indicating whether or not data should be simulated based on TMB model specifications. Default: FALSE. See <code>optMethod</code> argument in <code>fitHMM</code> . Ignored if model is specified. |
| ... | further arguments passed to or from other methods |
| hierStates | A hierarchical model structure <code>Node</code> for the states ('state'). See details. |
| hierDist | A hierarchical data structure <code>Node</code> for the data streams ('dist'). Currently supported distributions are 'bern', 'beta', 'exp', 'gamma', 'lnorm', 'norm', 'mvnorm2' (bivariate normal distribution), 'mvnorm3' (trivariate normal distribution), 'pois', 'rw_norm' (normal random walk), 'rw_mvnorm2' (bivariate normal random walk), 'rw_mvnorm3' (trivariate normal random walk), 'vm', 'vmConsensus', 'weibull', and 'wrpcauchy'. See details. |
| hierBeta | A hierarchical data structure <code>Node</code> for the matrix of regression coefficients for the transition probabilities at each level of the hierarchy ('beta'). See <code>fitHMM</code> . |

| | |
|------------------|--|
| hierDelta | A hierarchical data structure Node for the initial distribution at each level of the hierarchy ('delta'). See fitHMM . |
| hierFormula | A hierarchical formula structure for the transition probability covariates for each level of the hierarchy ('formula'). Default: NULL (only hierarchical-level effects, with no covariate effects). Any formula terms that are not state- or parameter-specific are included on all of the transition probabilities within a given level of the hierarchy. See details. |
| hierFormulaDelta | A hierarchical formula structure for the initial distribution covariates for each level of the hierarchy ('formulaDelta'). Default: NULL (no covariate effects and <code>fixPar\$delta</code> is specified on the working scale). |
| nbHierCovs | A hierarchical data structure Node for the number of covariates ('nbCovs') to simulate for each level of the hierarchy (0 by default). Does not need to be specified if <code>covs</code> is specified. Simulated covariates are provided generic names (e.g., 'cov1.1' and 'cov1.2' for <code>nbHierCovs\$level1\$nbCovs=2</code>) and can be included in <code>hierFormula</code> and/or <code>DM</code> . |
| obsPerLevel | A hierarchical data structure Node indicating the number of observations for each level of the hierarchy ('obs'). For each level, the 'obs' field can either be the number of observations per animal (if single value) or the bounds of the number of observations per animal (if vector of two values). In the latter case, the numbers of observations generated per level for each animal are uniformly picked from this interval. Alternatively, <code>obsPerLevel</code> can be specified as a list of length <code>nbAnimals</code> with each element providing the hierarchical data structure for the number of observations for each level of the hierarchy for each animal, where the 'obs' field can either be the number of observations (if single value) or the bounds of the number of observations (if vector of two values) for each individual. |

Details

- `simHierData` is very similar to [simData](#) except that instead of simply specifying the number of states (`nbStates`), distributions (`dist`), observations (`obsPerAnimal`), covariates (`nbCovs`), and a single t.p.m. formula (`formula`), the `hierStates` argument specifies the hierarchical nature of the states, the `hierDist` argument specifies the hierarchical nature of the data streams, the `obsPerLevel` argument specifies the number of observations for each level of the hierarchy, the `nbHierCovs` argument specifies the number of covariates for each level of the hierarchy, and the `hierFormula` argument specifies a t.p.m. formula for each level of the hierarchy. All of the hierarchical arguments in `simHierData` are specified as [Node](#) objects from the [data.tree](#) package.
- x- and y-coordinate location data are generated only if valid 'step' and 'angle' data streams are specified. Valid distributions for 'step' include 'gamma', 'weibull', 'exp', and 'lnorm'. Valid distributions for 'angle' include 'vm' and 'wrpcauchy'. If only a valid 'step' data stream is specified, then only x-coordinates are generated.
- If `DM` is specified for a particular data stream, then the initial values are specified on the working (i.e., beta) scale of the parameters. The working scale of each parameter is determined by the link function used. The function [getParDM](#) is intended to help with obtaining initial values on the working scale when specifying a design matrix and other parameter constraints.

- Simulated data that are temporally regular (i.e., `lambda=NULL`) and without location measurement error (i.e., `errorEllipse=NULL`) are returned as a `momentuHMMData` (or `momentuHierHMMData`) object suitable for analysis using `fitHMM`.
- Simulated location data that are temporally-irregular (i.e., `lambda>0`) and/or with location measurement error (i.e., `errorEllipse!=NULL`) are returned as a data frame suitable for analysis using `crawlWrap`.
- The matrix `beta` of regression coefficients for the transition probabilities has one row for the intercept, plus one row for each covariate, and one column for each non-diagonal element of the transition probability matrix. For example, in a 3-state HMM with 2 formula covariates, the matrix `beta` has three rows (intercept + two covariates) and six columns (six non-diagonal elements in the 3x3 transition probability matrix - filled in row-wise). In a covariate-free model (default), `beta` has one row, for the intercept.
- State-specific formulas can be specified in DM using special formula functions. These special functions can take the names `paste0("state", 1:nbStates)` (where the integer indicates the state-specific formula). For example, `DM=list(step=list(mean=~cov1+state1(cov2), sd=~cov2+state2(cov1)))` includes `cov1` on the mean parameter for all states, `cov2` on the mean parameter for state 1, `cov2` on the sd parameter for all states, and `cov1` on the sd parameter for state 2.
- State- and parameter-specific formulas can be specified for transition probabilities in formula using special formula functions. These special functions can take the names `paste0("state", 1:nbStates)` (where the integer indicates the current state from which transitions occur), `paste0("toState", 1:nbStates)` (where the integer indicates the state to which transitions occur), or `paste0("betaCol", nbStates*(nbStates-1))` (where the integer indicates the column of the beta matrix). For example with `nbStates=3`, `formula=~cov1+betaCol1(cov2)+state3(cov3)+toState1(cov4)` includes `cov1` on all transition probability parameters, `cov2` on the beta column corresponding to the transition from state 1->2, `cov3` on transition probabilities from state 3 (i.e., beta columns corresponding to state transitions 3->1 and 3->2), and `cov4` on transition probabilities to state 1 (i.e., beta columns corresponding to state transitions 2->1 and 3->1).
- Cyclical relationships (e.g., hourly, monthly) may be simulated using the `cosinor(x, period)` special formula function for covariate `x` and sine curve period of time length `period`. For example, if the data are hourly, a 24-hour cycle can be simulated using `~cosinor(cov1, 24)`, where the covariate `cov1` is a repeating series of integers `0, 1, ..., 23, 0, 1, ..., 23, 0, 1, ...` (note that `simData` will not do this for you, the appropriate covariate must be specified using the `covs` argument; see example below). The `cosinor(x, period)` function converts `x` to 2 covariates `cosinorCos(x)=cos(2*pi*x/period)` and `cosinorSin(x)=sin(2*pi*x/period)` for inclusion in the model (i.e., 2 additional parameters per state). The amplitude of the sine wave is thus `sqrt(B_cos^2 + B_sin^2)`, where `B_cos` and `B_sin` are the working parameters corresponding to `cosinorCos(x)` and `cosinorSin(x)`, respectively (e.g., see Cornelissen 2014).

When the circular-circular regression model is used, the special function `angleFormula(cov, strength, by)` can be used in DM for the mean of angular distributions (i.e. `'vm'`, `'vmConsensus'`, and `'wrpcauchy'`), where `cov` is an angle covariate (e.g. wind direction), `strength` is a positive real covariate (e.g. wind speed), and `by` is an optional factor variable for individual- or group-level effects (e.g. ID, sex). This allows angle covariates to be weighted based on their strength or importance at time step `t` as in Rivest et al. (2016).

- If the length of covariate values passed (either through `'covs'`, or `'model'`) is not the same as the number of observations suggested by `'nbAnimals'` and `'obsPerAnimal'` (or `'obsPerLevel'`

for `simHierData`), then the series of covariates is either shortened (removing last values - if too long) or extended (starting over from the first values - if too short).

- For `simData`, when covariates are not included in `formulaDelta` (i.e. `formulaDelta=NULL`), then `delta` is specified as a vector of length `nbStates` that sums to 1. When covariates are included in `formulaDelta`, then `delta` must be specified as a $k \times (\text{nbStates}-1)$ matrix of working parameters, where k is the number of regression coefficients and the columns correspond to states 2:`nbStates`. For example, in a 3-state HMM with `formulaDelta=~cov1+cov2`, the matrix `delta` has three rows (intercept + two covariates) and 2 columns (corresponding to states 2 and 3). The initial distribution working parameters are transformed to the real scale as $\exp(\text{covsDelta} \times \text{Delta}) / \text{rowSums}(\exp(\text{covsDelta} \times \text{Delta}))$, where `covsDelta` is the $N \times k$ design matrix, `Delta=cbind(rep(0,k),delta)` is a $k \times \text{nbStates}$ matrix of working parameters, and $N=\text{length}(\text{unique}(\text{data}\$ID))$.
- For `simHierData`, 'delta' in `hierDelta` must be specified as a $k \times (\text{nbStates}-1)$ matrix of working parameters, where k is the number of regression coefficients and the columns correspond to states 2:`nbStates`.

Value

If the simulated data are temporally regular (i.e., `lambda=NULL`) with no measurement error (i.e., `errorEllipse=NULL`), an object `momentuHMMData` (or `momentuHierHMMData`), i.e., a dataframe of:

| | |
|-----|--|
| ID | The ID(s) of the observed animal(s) |
| ... | Data streams as specified by <code>dist</code> (or <code>hierDist</code>) |
| x | Either easting or longitude (if data streams include valid non-negative distribution for 'step') |
| y | Either northing or latitude (if data streams include valid non-negative distribution for 'step') |
| ... | Covariates (if any) |

If simulated location data are temporally irregular (i.e., `lambda>0`) and/or include measurement error (i.e., `errorEllipse!=NULL`), a dataframe of:

| | |
|---------------------------|---|
| time | Numeric time of each observed (and missing) observation |
| ID | The ID(s) of the observed animal(s) |
| x | Either easting or longitude observed location |
| y | Either northing or latitude observed location |
| ... | Data streams that are not derived from location (if applicable) |
| ... | Covariates at temporally-regular true (<code>mux,muy</code>) locations (if any) |
| mux | Either easting or longitude true location |
| muy | Either northing or latitude true location |
| error_semimajor_axis | error ellipse semi-major axis (if applicable) |
| error_semiminor_axis | error ellipse semi-minor axis (if applicable) |
| error_ellipse_orientation | error ellipse orientation (if applicable) |

| | |
|------------|---|
| ln.sd.x | log of the square root of the x-variance of bivariate normal error (if applicable; required for error ellipse models in crawlWrap) |
| ln.sd.y | log of the square root of the y-variance of bivariate normal error (if applicable; required for error ellipse models in crawlWrap) |
| error.corr | correlation term of bivariate normal error (if applicable; required for error ellipse models in crawlWrap) |

References

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- McClintock BT, London JM, Cameron MF, Boveng PL. 2015. Modelling animal movement using the Argos satellite telemetry location error ellipse. *Methods in Ecology and Evolution* 6(3):266-277.
- Rivest, LP, Duchesne, T, Nicosia, A, Fortin, D, 2016. A general angular regression model for the analysis of data on animal movement in ecology. *Journal of the Royal Statistical Society: Series C (Applied Statistics)*, 65(3):445-463.
- Leos-Barajas, V., Gangloff, E.J., Adam, T., Langrock, R., van Beest, F.M., Nabe-Nielsen, J. and Morales, J.M. 2017. Multi-scale modeling of animal movement and general behavior data using hidden Markov models with hierarchical structures. *Journal of Agricultural, Biological and Environmental Statistics*, 22 (3), 232-248.

See Also

[prepData](#), [simObsData](#)

Examples

```
# 1. Pass a fitted model to simulate from
# (m is a momentuHMM object - as returned by fithMM - automatically loaded with the package)
# We keep the default nbAnimals=1.
m <- example$m
obsPerAnimal=c(50,100)
data <- simData(model=m,obsPerAnimal=obsPerAnimal)

## Not run:
# 2. Pass the parameters of the model to simulate from
stepPar <- c(1,10,1,5,0.2,0.3) # mean_1, mean_2, sd_1, sd_2, zeromass_1, zeromass_2
anglePar <- c(pi,0,0.5,2) # mean_1, mean_2, concentration_1, concentration_2
omegaPar <- c(1,10,10,1) # shape1_1, shape1_2, shape2_1, shape2_2
stepDist <- "gamma"
angleDist <- "vm"
omegaDist <- "beta"
data <- simData(nbAnimals=4,nbStates=2,dist=list(step=stepDist,angle=angleDist,omega=omegaDist),
               Par=list(step=stepPar,angle=anglePar,omega=omegaPar),nbCovs=2,
               zeroInflation=list(step=TRUE),
               obsPerAnimal=obsPerAnimal)

# 3. Include covariates
# (note that it is useless to specify "nbCovs", which are overruled
```

```

# by the number of columns of "cov")
cov <- data.frame(temp=log(rnorm(500,20,5)))
stepPar <- c(log(10),0.1,log(100),-0.1,log(5),log(25)) # working scale parameters for step DM
anglePar <- c(pi,0,0.5,2) # mean_1, mean_2, concentration_1, concentration_2
stepDist <- "gamma"
angleDist <- "vm"
data <- simData(nbAnimals=2,nbStates=2,dist=list(step=stepDist,angle=angleDist),
               Par=list(step=stepPar,angle=anglePar),
               DM=list(step=list(mean=~temp,sd=~1)),
               covs=cov,
               obsPerAnimal=obsPerAnimal)

# 4. Include example 'forest' spatial covariate raster layer
# nbAnimals and obsPerAnimal kept small to reduce example run time
spatialCov<-list(forest=forest)
data <- simData(nbAnimals=1,nbStates=2,dist=list(step=stepDist,angle=angleDist),
               Par=list(step=c(100,1000,50,100),angle=c(0,0,0.1,5)),
               beta=matrix(c(5,-10,-25,50),nrow=2,ncol=2,byrow=TRUE),
               formula=~forest,spatialCovs=spatialCov,
               obsPerAnimal=250,states=TRUE,
               retrySims=100)

# 5. Specify design matrix for 'omega' data stream
# natural scale parameters for step and angle
stepPar <- c(1,10,1,5) # shape_1, shape_2, scale_1, scale_2
anglePar <- c(pi,0,0.5,0.7) # mean_1, mean_2, concentration_1, concentration_2

# working scale parameters for omega DM
omegaPar <- c(log(1),0.1,log(10),-0.1,log(10),-0.1,log(1),0.1)

stepDist <- "weibull"
angleDist <- "wrpcauchy"
omegaDist <- "beta"

data <- simData(nbStates=2,dist=list(step=stepDist,angle=angleDist,omega=omegaDist),
               Par=list(step=stepPar,angle=anglePar,omega=omegaPar),nbCovs=2,
               DM=list(omega=list(shape1=~cov1,shape2=~cov2)),
               obsPerAnimal=obsPerAnimal,states=TRUE)

# 6. Include temporal irregularity and location measurement error
lambda <- 2 # expect 2 observations per time step
errorEllipse <- list(M=50,m=25,r=180)
obsData <- simData(model=m,obsPerAnimal=obsPerAnimal,
                  lambda=lambda, errorEllipse=errorEllipse)

# 7. Cosinor and state-dependent formulas
nbStates<-2
dist<-list(step="gamma")
Par<-list(step=c(100,1000,50,100))

# include 24-hour cycle on all transition probabilities
# include 12-hour cycle on transitions from state 2
formula=~cosinor(hour24,24)+state2(cosinor(hour12,12))

```

```

# specify appropriate covariates
covs<-data.frame(hour24=0:23, hour12=0:11)

beta<-matrix(c(-1.5,1,1,NA,NA,-1.5,-1,-1,1,1),5,2)
# row names for beta not required but can be helpful
rownames(beta)<-c("(Intercept)",
                 "cosinorCos(hour24, 24)",
                 "cosinorSin(hour24, 24)",
                 "cosinorCos(hour12, 12)",
                 "cosinorSin(hour12, 12)")
data.cos<-simData(nbStates=nbStates,dist=dist,Par=Par,
                 beta=beta,formula=formula,covs=covs)

# 8. Piecewise constant B-spline on step length mean and angle concentration
nObs <- 1000 # length of simulated track
cov <- data.frame(time=1:nObs) # time covariate for splines
dist <- list(step="gamma",angle="vm")
stepDM <- list(mean=~splines2::bSpline(time,df=2,degree=0),sd=~1)
angleDM <- list(mean=~1,concentration=~splines2::bSpline(time,df=2,degree=0))
DM <- list(step=stepDM,angle=angleDM)
Par <- list(step=c(log(1000),1,-1,log(100)),angle=c(0,log(10),2,-5))

data.spline<-simData(obsPerAnimal=nObs,nbStates=1,dist=dist,Par=Par,DM=DM,covs=cov)

# 9. Initial state (delta) based on covariate
nObs <- 100
dist <- list(step="gamma",angle="vm")
Par <- list(step=c(100,1000,50,100),angle=c(0,0,0.01,0.75))

# create sex covariate
cov <- data.frame(sex=factor(rep(c("F","M"),each=nObs))) # sex covariate
formulaDelta <- ~ sex + 0

# Female begins in state 1, male begins in state 2
delta <- matrix(c(-100,100),2,1,dimnames=list(c("sexF","sexM"),"state 2"))

data.delta<-simData(nbAnimals=2,obsPerAnimal=nObs,nbStates=2,dist=dist,Par=Par,
                  delta=delta,formulaDelta=formulaDelta,covs=cov,
                  beta=matrix(-1.5,1,2),states=TRUE)

## End(Not run)

```

Description

Simulates data from an approximate (multivariate) hierarchical continuous-time discrete-space hidden Markov model. Note that the state active at observation time t determines the (state-dependent)

observation distribution from observation time t to time $t+1$ (see Details) and time-varying covariates are assumed piece-wise constant between observations. Movement data are assumed to be in Cartesian coordinates (not longitude/latitude) and can be generated with or without observation error attributable to location measurement error.

Usage

```
simHierCTDS(
  nbAnimals = 1,
  hierStates,
  hierDist,
  Par,
  hierBeta = NULL,
  hierDelta = NULL,
  hierFormula = NULL,
  hierFormulaDelta = NULL,
  mixtures = 1,
  formulaPi = NULL,
  covs = NULL,
  nbHierCovs = NULL,
  rast,
  spatialCovs = NULL,
  spatialCovs.grad = NULL,
  directions = 4,
  normalize.gradients = FALSE,
  grad.point.decreasing = FALSE,
  zero.idx = integer(),
  moveState = FALSE,
  obsPerLevel,
  initialPosition = c(0, 0),
  DM = NULL,
  userBounds = NULL,
  workBounds = NULL,
  model = NULL,
  matchModelObs = TRUE,
  states = FALSE,
  lambda = 1,
  errorEllipse = NULL,
  ncores = 1,
  export = NULL
)
```

Arguments

| | |
|-------------------------|--|
| <code>nbAnimals</code> | Number of observed individuals to simulate. |
| <code>hierStates</code> | A hierarchical model structure Node for the states ('state'). See details. |
| <code>hierDist</code> | A hierarchical data structure Node for the data streams ('dist'). A data stream named <code>z</code> must be included in one level, and it must be assigned the "ctds" distribution. |

| | |
|------------------|---|
| Par | <p>A named list containing vectors of initial state-dependent probability distribution parameters for each data stream specified in <code>dist</code>. The parameters should be in the order expected by the pdfs of <code>dist</code>.</p> <p>If <code>DM</code> is not specified for a given data stream, then <code>Par</code> is on the natural (i.e., real) scale of the parameters. However, if <code>DM</code> is specified for a given data stream, then <code>Par</code> must be on the working (i.e., beta) scale of the parameters, and the length of <code>Par</code> must match the number of columns in the design matrix. See details below.</p> |
| hierBeta | <p>A hierarchical data structure Node for the matrix of initial values for the regression coefficients of the transition probabilities at each level of the hierarchy ('beta'). See fithMM.</p> |
| hierDelta | <p>A hierarchical data structure Node for the matrix of initial values for the regression coefficients of the initial distribution at each level of the hierarchy ('delta'). See fithMM.</p> |
| hierFormula | <p>A hierarchical formula structure for the transition probability covariates for each level of the hierarchy ('formula'). Default: NULL (only hierarchical-level effects, with no covariate effects). Any formula terms that are not state- or parameter-specific are included on all of the transition probabilities within a given level of the hierarchy. See details.</p> |
| hierFormulaDelta | <p>A hierarchical formula structure for the initial distribution covariates for each level of the hierarchy ('formulaDelta'). Default: NULL (no covariate effects and <code>fixPar\$delta</code> is specified on the working scale).</p> |
| mixtures | <p>Number of mixtures for the state transition probabilities (i.e. discrete random effects *sensu* DeRuiter et al. 2017). Default: <code>mixtures=1</code>.</p> |
| formulaPi | <p>Regression formula for the mixture distribution probabilities. Default: NULL (no covariate effects; both <code>beta\$pi</code> and <code>fixPar\$pi</code> are specified on the real scale). Standard functions in R formulas are allowed (e.g., <code>cos(cov)</code>, <code>cov1*cov2</code>, <code>I(cov^2)</code>). When any formula is provided, then both <code>beta\$pi</code> and <code>fixPar\$pi</code> are specified on the working scale. Note that only the covariate values corresponding to the first time step for each individual ID are used (i.e. time-varying covariates cannot be used for the mixture probabilities).</p> |
| covs | <p>Covariate values to include in the simulated data, as a dataframe. The names of any covariates specified by <code>covs</code> can be included in <code>formula</code> and/or <code>DM</code>. Covariates can also be simulated according to a standard normal distribution, by setting <code>covs</code> to NULL (the default), and specifying <code>nbCovs>0</code>.</p> |
| nbHierCovs | <p>A hierarchical data structure Node for the number of covariates ('nbCovs') to simulate for each level of the hierarchy (0 by default). Does not need to be specified if <code>covs</code> is specified. Simulated covariates are provided generic names (e.g., 'cov1.1' and 'cov1.2' for <code>nbHierCovs\$level1\$nbCovs=2</code>) and can be included in <code>hierFormula</code> and/or <code>DM</code>.</p> |
| rast | <p>A raster object or raster stack object that will define the discrete-space grid cells for the CTMC movement path. <code>spatialCovs</code> and <code>spatialCovs.grad</code> must have the same extent, number of rows and columns, projection, resolution, and origin as <code>rast</code>.</p> |
| spatialCovs | <p>List of raster objects for spatio-temporally referenced covariates. Covariates specified by <code>spatialCovs</code> are extracted from the raster layer(s) based on the</p> |

location data (and the z values for a raster `stack` or `brick`) for each time step. If an element of `spatialCovs` is a raster `stack` or `brick`, then z values must be set using `raster::setZ` and data must include column(s) of the corresponding z value(s) for each observation (e.g., 'Date'). In the `momentuHMMData` object returned by `prepCTDS`, covariates for the current position (e.g. \ for use in formula or DM) are named with a `.cur` suffix (e.g. `cov1.cur`).

`spatialCovs.grad`

List of `raster` objects for spatio-temporally referenced covariates, where a directional gradient is to be calculated internally using `rast.grad`. Gradient-based covariates specified by `spatialCovs.grad` are extracted from the raster layer(s) based on the location data (and the z values for a raster `stack` or `brick`) for each time step. If an element of `spatialCovs.grad` is a raster `stack` or `brick`, then z values must be set using `raster::setZ` and data must include column(s) of the corresponding z value(s) for each observation (e.g., 'Date').

`directions`

Integer. Either 4 (indicating a "Rook's neighborhood" of 4 neighboring grid cells) or 8 (indicating a "King's neighborhood" of 8 neighboring grid cells).

`normalize.gradients`

Logical. Default is FALSE. If TRUE, then all gradient covariates for `spatialCovs.grad` are normalized by dividing by the length of the gradient vector at each point.

`grad.point.decreasing`

Logical. If TRUE, then the gradient covariates are positive in the direction of decreasing values of the covariate. If FALSE, then the gradient covariates are positive in the direction of increasing values of the covariate (like a true gradient).

`zero.idx`

Integer vector of the indices of raster cells that are not passable and should be excluded. These are cells where movement should be impossible. Default is `zero.idx=integer()`.

`moveState`

Logical indicating whether or not transitions out of the current state are forbidden when the animal does not move out of the current cell. Default: FALSE. Note that if `moveState` is TRUE, then the realized state transition rates will not accurately reflect beta.

`obsPerLevel`

A hierarchical data structure `Node` indicating the number of observations for each level of the hierarchy ('obs'). For each level, the 'obs' field can either be the number of observations per animal (if single value) or the bounds of the number of observations per animal (if vector of two values). In the latter case, the numbers of observations generated per level for each animal are uniformly picked from this interval. Alternatively, `obsPerLevel` can be specified as a list of length `nbAnimals` with each element providing the hierarchical data structure for the number of observations for each level of the hierarchy for each animal, where the 'obs' field can either be the number of observations (if single value) or the bounds of the number of observations (if vector of two values) for each individual.

`initialPosition`

2-vector providing the x- and y-coordinates of the initial position for all animals. Alternatively, `initialPosition` can be specified as a list of length `nbAnimals` with each element a 2-vector providing the x- and y-coordinates of the initial position for each individual. Default: $c(0,0)$. If `mvnCoord` corresponds

| | |
|---------------|---|
| | to a data stream with “mvnorm3” or “rw_mvnorm3” probability distributions, then <code>initialPosition</code> must be composed of 3-vector(s) for the x-, y-, and z-coordinates. |
| DM | An optional named list indicating the design matrices to be used for the probability distribution parameters of each data stream. Each element of DM can either be a named list of regression formulas or a “pseudo” design matrix. |
| userBounds | An optional named list of 2-column matrices specifying bounds on the natural (i.e., real) scale of the probability distribution parameters for each data stream. |
| workBounds | An optional named list of 2-column matrices specifying bounds on the working scale of the probability distribution, transition probability, and initial distribution parameters. For each matrix, the first column pertains to the lower bound and the second column the upper bound. For data streams, each element of <code>workBounds</code> should be a $k \times 2$ matrix with the same name of the corresponding element of <code>Par</code> , where k is the number of parameters. For transition rate parameters, the corresponding element of <code>workBounds</code> must be a $k \times 2$ matrix named “beta”, where $k = \text{length}(\text{beta})$. For initial distribution parameters, the corresponding element of <code>workBounds</code> must be a $k \times 2$ matrix named “delta”, where $k = \text{length}(\text{delta})$. <code>workBounds</code> is ignored for any given data stream unless DM is also specified. |
| model | A <code>momentuHMM</code> , <code>miHMM</code> , or <code>miSum</code> object. This option can be used to simulate from a fitted model. Default: NULL. Note that, if this argument is specified, most other arguments will be ignored – except for <code>nbAnimals</code> , <code>obsPerAnimal</code> , <code>states</code> , <code>initialPosition</code> , <code>lambda</code> , <code>errorEllipse</code> , and, if covariate values different from those in the data should be specified, <code>covs</code> , and <code>spatialCovs</code> . It is not appropriate to simulate movement data from a model that was fitted to latitude/longitude data (because <code>simData</code> assumes Cartesian coordinates). |
| matchModelObs | If <code>model</code> is provided, logical indicating whether to match <code>nbAnimals</code> , <code>obsPerAnimal</code> , and observation times to the fitted model data. If TRUE, then <code>nbAnimals</code> , <code>obsPerAnimal</code> , and <code>lambda</code> are ignored. Default: TRUE. |
| states | TRUE if the simulated states should be returned, FALSE otherwise (default). |
| lambda | Observation rate. <code>lambda</code> is the rate parameter of the exponential distribution for the waiting times between successive observations, i.e., $1/\lambda$ is the expected time between successive location observations. Note that only a single state transition can occur between observations. If <code>model</code> is specified and <code>model\$data</code> time column is of class <code>date-time</code> or <code>date</code> , <code>lambda</code> has the same units as the <code>Time.unit</code> argument in <code>fitCTHMM</code> . Default: 1. |
| errorEllipse | List providing the upper bound for the semi-major axis (M ; on scale of x- and y-coordinates), semi-minor axis (m ; on scale of x- and y-coordinates), and orientation (r ; in degrees) of location error ellipses. If NULL (the default), no location measurement error is simulated. If <code>errorEllipse</code> is specified, then each observed location is subject to bivariate normal errors as described in McClintock et al. (2015), where the components of the error ellipse for each location are randomly drawn from <code>runif(1, min(errorEllipse\$M), max(errorEllipse\$M))</code> , <code>runif(1, min(errorEllipse\$m), max(errorEllipse\$m))</code> , and <code>runif(1, min(errorEllipse\$r), max(errorEllipse\$r))</code> . If only a single value is provided for any of the error ellipse elements, then the |

| | |
|--------|---|
| | corresponding component is fixed to this value for each location. Only coordinate data streams are subject to location measurement error; any other data streams are observed without error. |
| ncores | Number of cores to use for parallel processing. Default: 1 (no parallel processing). |
| export | Character vector of the names of any additional objects or functions in the global environment that are used in DM, formula, formulaDelta, and/or formulaPi. Only necessary if ncores>1 so that the needed items will be exported to the workers. |

Details

- Importantly, simHierCTDS assumes the state active at observation time t determines the (state-dependent) observation distribution from observation time t to time $t+1$ (i.e. state switches only occur at the times of observations). The snapshot property applies to all data stream distributions (i.e. observations are "instantaneous") except for the continuous-time discrete space (ctds), (multivariate) normal random walk (rw_norm, rw_mvnorm2, rw_mvnorm3), and Poisson (pois) distributions. For these particular distributions, the observed data are not "instantaneous"; they depend on the time interval between observations (Δ_t). It is critical that the frequency of observations (specified by lambda) is high relative to the serial correlation in the hidden state process (specified by hierBeta) in order for this discrete-time approximation to be reasonably accurate.
- Model specification in simHierCTDS is similar to simCTDS except that instead of simply specifying the number of states (nbStates), distributions (dist), observations (obsPerAnimal), covariates (nbCovs), and a single t.p.m. formula (formula), the hierStates argument specifies the hierarchical nature of the states, the hierDist argument specifies the hierarchical nature of the data streams, the obsPerLevel argument specifies the number of observations for each level of the hierarchy, the nbHierCovs argument specifies the number of covariates for each level of the hierarchy, and the hierFormula argument specifies a t.p.m. formula for each level of the hierarchy. All of the hierarchical arguments in simHierCTDS are specified as Node objects from the data.tree package.
- If the length of covariate values passed (either through 'covs', or 'model') is not the same as the number of observations suggested by 'nbAnimals' and 'obsPerLevel', then the series of covariates is either shortened (removing last values - if too long) or extended (starting over from the first values - if too short).
- In hierDelta, 'delta' must be specified as a $k \times (nbStates-1)$ matrix of working parameters, where k is the number of regression coefficients and the columns correspond to states 2:nbStates.

Description

Simulates data from an approximate (multivariate) hierarchical continuous-time hidden Markov model. Note that the state active at observation time t determines the (state-dependent) observation distribution from observation time t to time $t+1$ (see Details) and time-varying covariates are assumed piece-wise constant between observations. Movement data are assumed to be in Cartesian coordinates (not longitude/latitude) and can be generated with or without observation error attributable to location measurement error.

Usage

```
simHierCTHMM(
  nbAnimals = 1,
  hierStates,
  hierDist,
  Par,
  hierBeta = NULL,
  hierDelta = NULL,
  hierFormula = NULL,
  hierFormulaDelta = NULL,
  mixtures = 1,
  formulaPi = NULL,
  covs = NULL,
  nbHierCovs = NULL,
  spatialCovs = NULL,
  obsPerLevel,
  initialPosition = c(0, 0),
  DM = NULL,
  userBounds = NULL,
  workBounds = NULL,
  mvnCoords = NULL,
  model = NULL,
  matchModelObs = FALSE,
  states = FALSE,
  retrySims = 0,
  lambda = 1,
  errorEllipse = NULL,
  ncores = 1,
  export = NULL,
  gradient = FALSE,
  TMB = FALSE
)
```

Arguments

| | |
|------------|--|
| nbAnimals | Number of observed individuals to simulate. |
| hierStates | A hierarchical model structure Node for the states ('state'). See details. |
| hierDist | A hierarchical data structure Node for the data streams ('dist'). Currently supported distributions are 'bern', 'beta', 'exp', 'gamma', 'lnorm', 'norm', 'mvnorm2' |

| | |
|------------------|--|
| | (bivariate normal distribution), 'mvnorm3' (trivariate normal distribution), 'pois', 'rw_norm' (normal random walk), 'rw_mvnorm2' (bivariate normal random walk), 'rw_mvnorm3' (trivariate normal random walk), 'vm', 'vmConsensus', 'weibull', and 'wrpcauchy'. See details. |
| Par | A named list containing vectors of initial state-dependent probability distribution parameters for each data stream specified in <code>dist</code> . The parameters should be in the order expected by the pdfs of <code>dist</code> . If <code>DM</code> is not specified for a given data stream, then <code>Par</code> is on the natural (i.e., real) scale of the parameters. However, if <code>DM</code> is specified for a given data stream, then <code>Par</code> must be on the working (i.e., beta) scale of the parameters, and the length of <code>Par</code> must match the number of columns in the design matrix. See details below. |
| hierBeta | A hierarchical data structure Node for the matrix of regression coefficients for the transition rates at each level of the hierarchy ('beta'). See fitCTHMM . |
| hierDelta | A hierarchical data structure Node for the initial distribution at each level of the hierarchy ('delta'). See fitCTHMM . |
| hierFormula | A hierarchical formula structure for the transition probability covariates for each level of the hierarchy ('formula'). Default: NULL (only hierarchical-level effects, with no covariate effects). Any formula terms that are not state- or parameter-specific are included on all of the transition probabilities within a given level of the hierarchy. See details. |
| hierFormulaDelta | A hierarchical formula structure for the initial distribution covariates for each level of the hierarchy ('formulaDelta'). Default: NULL (no covariate effects and <code>fixPar\$delta</code> is specified on the working scale). |
| mixtures | Number of mixtures for the state transition probabilities (i.e. discrete random effects *sensu* DeRuiter et al. 2017). Default: <code>mixtures=1</code> . |
| formulaPi | Regression formula for the mixture distribution probabilities. Default: NULL (no covariate effects; both <code>beta\$pi</code> and <code>fixPar\$pi</code> are specified on the real scale). Standard functions in R formulas are allowed (e.g., <code>cos(cov)</code> , <code>cov1*cov2</code> , <code>I(cov^2)</code>). When any formula is provided, then both <code>beta\$pi</code> and <code>fixPar\$pi</code> are specified on the working scale. Note that only the covariate values corresponding to the first time step for each individual ID are used (i.e. time-varying covariates cannot be used for the mixture probabilities). |
| covs | Covariate values to include in the simulated data, as a dataframe. The names of any covariates specified by <code>covs</code> can be included in <code>formula</code> and/or <code>DM</code> . Covariates can also be simulated according to a standard normal distribution, by setting <code>covs</code> to NULL (the default), and specifying <code>nbCovs>0</code> . |
| nbHierCovs | A hierarchical data structure Node for the number of covariates ('nbCovs') to simulate for each level of the hierarchy (0 by default). Does not need to be specified if <code>covs</code> is specified. Simulated covariates are provided generic names (e.g., 'cov1.1' and 'cov1.2' for <code>nbHierCovs\$level1\$nbCovs=2</code>) and can be included in <code>hierFormula</code> and/or <code>DM</code> . |
| spatialCovs | List of raster objects for spatio-temporally referenced covariates. Covariates specified by <code>spatialCovs</code> are extracted from the raster layer(s) based on any simulated location data (and the z values for a raster stack or brick) for each |

| | |
|------------------------------|--|
| | time step. If an element of <code>spatialCovs</code> is a raster <code>stack</code> or <code>brick</code> , then <code>z</code> values must be set using <code>raster::setZ</code> and <code>covs</code> must include column(s) of the corresponding <code>z</code> value(s) for each observation (e.g., 'time'). The names of the raster layer(s) can be included in <code>formula</code> and/or <code>DM</code> . Note that <code>simHierCTHMM</code> usually takes longer to generate simulated data when <code>spatialCovs</code> is specified. |
| <code>obsPerLevel</code> | A hierarchical data structure <code>Node</code> indicating the number of observations for each level of the hierarchy ('obs'). For each level, the 'obs' field can either be the number of observations per animal (if single value) or the bounds of the number of observations per animal (if vector of two values). In the latter case, the numbers of observations generated per level for each animal are uniformly picked from this interval. Alternatively, <code>obsPerLevel</code> can be specified as a list of length <code>nbAnimals</code> with each element providing the hierarchical data structure for the number of observations for each level of the hierarchy for each animal, where the 'obs' field can either be the number of observations (if single value) or the bounds of the number of observations (if vector of two values) for each individual. |
| <code>initialPosition</code> | 2-vector providing the x- and y-coordinates of the initial position for all animals. Alternatively, <code>initialPosition</code> can be specified as a list of length <code>nbAnimals</code> with each element a 2-vector providing the x- and y-coordinates of the initial position for each individual. Default: <code>c(0,0)</code> . If <code>mvnCoord</code> corresponds to a data stream with "mvnorm3" or "rw_mvnorm3" probability distributions, then <code>initialPosition</code> must be composed of 3-vector(s) for the x-, y-, and z-coordinates. |
| <code>DM</code> | An optional named list indicating the design matrices to be used for the probability distribution parameters of each data stream. Each element of <code>DM</code> can either be a named list of regression formulas or a "pseudo" design matrix. |
| <code>userBounds</code> | An optional named list of 2-column matrices specifying bounds on the natural (i.e., real) scale of the probability distribution parameters for each data stream. |
| <code>workBounds</code> | An optional named list of 2-column matrices specifying bounds on the working scale of the probability distribution, transition probability, and initial distribution parameters. For each matrix, the first column pertains to the lower bound and the second column the upper bound. For data streams, each element of <code>workBounds</code> should be a $k \times 2$ matrix with the same name of the corresponding element of <code>Par</code> , where k is the number of parameters. For transition rate parameters, the corresponding element of <code>workBounds</code> must be a $k \times 2$ matrix named "beta", where $k = \text{length}(\text{beta})$. For initial distribution parameters, the corresponding element of <code>workBounds</code> must be a $k \times 2$ matrix named "delta", where $k = \text{length}(\text{delta})$. <code>workBounds</code> is ignored for any given data stream unless <code>DM</code> is also specified. |
| <code>mvnCoords</code> | Character string indicating the name of location data that are to be simulated using a multivariate normal distribution. For example, if <code>mu="rw_mvnorm2"</code> was included in <code>dist</code> and <code>(mu.x, mu.y)</code> are intended to be location data, then <code>mvnCoords="mu"</code> needs to be specified in order for these data to be treated as such. |
| <code>model</code> | A <code>momentuHMM</code> , <code>miHMM</code> , or <code>miSum</code> object. This option can be used to simulate from a fitted model. Default: <code>NULL</code> . Note that, if this argument is specified, |

most other arguments will be ignored – except for `nbAnimals`, `obsPerLevel`, `states`, `initialPosition`, `lambda`, `errorEllipse`, and, if covariate values different from those in the data should be specified, `covs`, and `spatialCovs`. It is not appropriate to simulate movement data from a model that was fitted to latitude/longitude data (because `simHierCTHMM` assumes Cartesian coordinates).

| | |
|----------------------------|---|
| <code>matchModelObs</code> | If <code>model</code> is provided, logical indicating whether to match <code>nbAnimals</code> , <code>obsPerAnimal</code> , and observation times to the fitted model data. If TRUE, then <code>nbAnimals</code> , <code>obsPerAnimal</code> , and <code>lambda</code> are ignored. Furthermore, if TRUE and <code>initialPosition</code> is not compatible with any <code>spatialCovs</code> , then the initial position for each animal from the fitted model data is used. Default: FALSE. |
| <code>states</code> | TRUE if the simulated states should be returned, FALSE otherwise (default). |
| <code>retrySims</code> | Number of times to attempt to simulate data within the spatial extent of <code>spatialCovs</code> . If <code>retrySims=0</code> (the default), an error is returned if the simulated tracks(s) move beyond the extent(s) of the raster layer(s). Instead of relying on <code>retrySims</code> , in many cases it might be better to simply expand the extent of the raster layer(s) and/or adjust the movement parameters. Ignored if <code>spatialCovs=NULL</code> . |
| <code>lambda</code> | Observation rate. <code>lambda</code> is the rate parameter of the exponential distribution for the waiting times between successive observations, i.e., $1/\lambda$ is the expected time between successive location observations. Note that only a single state transition can occur between observations. If <code>model</code> is specified and <code>model\$data</code> time column is of class <code>date-time</code> or <code>date</code> , <code>lambda</code> has the same units as the <code>Time.unit</code> argument in <code>prepData</code> . Default: 1. |
| <code>errorEllipse</code> | List providing the upper bound for the semi-major axis (<code>M</code> ; on scale of x- and y-coordinates), semi-minor axis (<code>m</code> ; on scale of x- and y-coordinates), and orientation (<code>r</code> ; in degrees) of location error ellipses. If NULL (the default), no location measurement error is simulated. If <code>errorEllipse</code> is specified, then each observed location is subject to bivariate normal errors as described in McClintock et al. (2015), where the components of the error ellipse for each location are randomly drawn from <code>runif(1, min(errorEllipse\$M), max(errorEllipse\$M))</code> , <code>runif(1, min(errorEllipse\$m), max(errorEllipse\$m))</code> , and <code>runif(1, min(errorEllipse\$r), max(errorEllipse\$r))</code> . If only a single value is provided for any of the error ellipse elements, then the corresponding component is fixed to this value for each location. Only coordinate data streams are subject to location measurement error; any other data streams are observed without error. |
| <code>ncores</code> | Number of cores to use for parallel processing. Default: 1 (no parallel processing). |
| <code>export</code> | Character vector of the names of any additional objects or functions in the global environment that are used in <code>DM</code> , <code>formula</code> , <code>formulaDelta</code> , and/or <code>formulaPi</code> . Only necessary if <code>ncores>1</code> so that the needed items will be exported to the workers. |
| <code>gradient</code> | Logical indicating whether or not to calculate gradients of <code>spatialCovs</code> using bilinear interpolation (e.g. for inclusion in potential functions). Default: FALSE. If TRUE, the gradients are returned with “.x” (easting gradient) and “.y” (northing gradient) suffixes added to the names of <code>spatialCovs</code> . For example, if <code>cov1</code> is the name of a spatial covariate, then the returned <code>momentuHMMData</code> object will include the fields “ <code>cov1.x</code> ” and “ <code>cov1.y</code> ”. |

| | |
|-----|--|
| TMB | Logical indicating whether or not data should be simulated based on TMB model specifications. Default: FALSE. See optMethod argument in <code>fitCTHMM</code> . Ignored if model is specified. |
|-----|--|

Details

- Importantly, `simHierCTHMM` assumes the state active at observation time t determines the (state-dependent) observation distribution from observation time t to time $t+1$ (i.e. state switches only occur at the times of observations). The snapshot property applies to all data stream distributions (i.e. observations are "instantaneous") except for the (multivariate) normal random walk (`rw_norm`, `rw_mvnorm2`, `rw_mvnorm3`) and Poisson (`pois`) distributions. For these particular distributions, the observed data are not "instantaneous"; they depend on the time interval between observations (Δ_t). It is critical that the frequency of observations (specified by `lambda`) is high relative to the serial correlation in the hidden state process (specified by `hierBeta`) in order for this discrete-time approximation to be reasonably accurate.
- Model specification in `simHierCTHMM` is similar to `simCTHMM` except that instead of simply specifying the number of states (`nbStates`), distributions (`dist`), observations (`obsPerAnimal`), covariates (`nbCovs`), and a single t.p.m. formula (`formula`), the `hierStates` argument specifies the hierarchical nature of the states, the `hierDist` argument specifies the hierarchical nature of the data streams, the `obsPerLevel` argument specifies the number of observations for each level of the hierarchy, the `nbHierCovs` argument specifies the number of covariates for each level of the hierarchy, and the `hierFormula` argument specifies a t.p.m. formula for each level of the hierarchy. All of the hierarchical arguments in `simHierCTHMM` are specified as `Node` objects from the `data.tree` package.
- If the length of covariate values passed (either through `'covs'`, or `'model'`) is not the same as the number of observations suggested by `'nbAnimals'` and `'obsPerLevel'`, then the series of covariates is either shortened (removing last values - if too long) or extended (starting over from the first values - if too short).
- In `hierDelta`, `'delta'` must be specified as a $k \times (nbStates-1)$ matrix of working parameters, where k is the number of regression coefficients and the columns correspond to states 2:nbStates.

References

Leos-Barajas, V., Gangloff, E.J., Adam, T., Langrock, R., van Beest, F.M., Nabe-Nielsen, J. and Morales, J.M. 2017. Multi-scale modeling of animal movement and general behavior data using hidden Markov models with hierarchical structures. *Journal of Agricultural, Biological and Environmental Statistics*, 22 (3), 232-248.

simObsData

Observation error simulation tool

Description

Simulates observed location data subject to temporal irregularity and/or location measurement error

Usage

```
simObsData(data, lambda, errorEllipse, ...)

## S3 method for class 'momentuHMMDData'
simObsData(data, lambda, errorEllipse, ...)

## S3 method for class 'momentuHierHMMDData'
simObsData(data, lambda, errorEllipse, coordLevel, ...)
```

Arguments

| | |
|--------------|---|
| data | A momentuHMMDData or momentuHierHMMDData object with necessary fields 'x' (easting/longitudinal coordinates) and 'y' (northing/latitudinal coordinates) |
| lambda | Observation rate for location data. If NULL, location data are kept at temporally-regular intervals. Otherwise lambda is the rate parameter of the exponential distribution for the waiting times between successive location observations, i.e., $1/\lambda$ is the expected time between successive location observations. Only the 'step' and 'angle' data streams (or multivariate normal data streams identified by mvnCoords) are subject to temporal irregularity; any other data streams are kept at temporally-regular intervals. Ignored unless a valid distribution for the 'step' (or 'mvnCoord') data stream has been specified. |
| errorEllipse | List providing the bounds for the semi-major axis (M; on scale of x- and y-coordinates), semi-minor axis (m; on scale of x- and y-coordinates), and orientation (r; in degrees) of location error ellipses. If NULL, no location measurement error is simulated. If errorEllipse is specified, then each observed location is subject to bivariate normal errors as described in McClintock et al. (2015), where the components of the error ellipse for each location are randomly drawn from $\text{runif}(1, \min(\text{errorEllipse}\$M), \max(\text{errorEllipse}\$M))$, $\text{runif}(1, \min(\text{errorEllipse}\$m), \max(\text{errorEllipse}\$m))$, and $\text{runif}(1, \min(\text{errorEllipse}\$r), \max(\text{errorEllipse}\$r))$. If only a single value is provided for any of the error ellipse elements, then the corresponding component is fixed to this value for each location. Only the 'step' and 'angle' data streams are subject to location measurement error; any other data streams are observed without error. Ignored unless a valid distribution for the 'step' data stream is specified. |
| ... | further arguments passed to or from other methods |
| coordLevel | Level of the hierarchy in which the location data are obtained |

Details

Simulated location data that are temporally-irregular (i.e., $\lambda > 0$) and/or with location measurement error (i.e., $\text{errorEllipse} \neq \text{NULL}$) are returned as a data frame suitable for analysis using [crawlWrap](#).

Value

A dataframe of:

| | |
|------|---|
| time | Numeric time of each observed (and missing) observation |
|------|---|

| | |
|---------------------------|---|
| ID | The ID(s) of the observed animal(s) |
| x | Either easting or longitude observed location |
| y | Either northing or latitude observed location |
| ... | Data streams that are not derived from location (if applicable) |
| ... | Covariates at temporally-regular true (mux,muy) locations (if any) |
| mux | Either easting or longitude true location |
| muy | Either northing or latitude true location |
| error_semimajor_axis | error ellipse semi-major axis (if applicable) |
| error_semiminor_axis | error ellipse semi-minor axis (if applicable) |
| error_ellipse_orientation | error ellipse orientation (if applicable) |
| ln.sd.x | log of the square root of the x-variance of bivariate normal error (if applicable; required for error ellipse models in crawlWrap) |
| ln.sd.y | log of the square root of the y-variance of bivariate normal error (if applicable; required for error ellipse models in crawlWrap) |
| error.corr | correlation term of bivariate normal error (if applicable; required for error ellipse models in crawlWrap) |

References

McClintock BT, London JM, Cameron MF, Boveng PL. 2015. Modelling animal movement using the Argos satellite telemetry location error ellipse. *Methods in Ecology and Evolution* 6(3):266-277.

See Also

[crawlWrap](#), [prepData](#), [simData](#)
[simHierData](#)

Examples

```
# extract momentuHMMData example
data <- example$m$data
lambda <- 2 # expect 2 observations per time step
errorEllipse <- list(M=c(0,50),m=c(0,50),r=c(0,180))
obsData1 <- simObsData(data,lambda=lambda,errorEllipse=errorEllipse)

errorEllipse <- list(M=50,m=50,r=180)
obsData2 <- simObsData(data,lambda=lambda,errorEllipse=errorEllipse)
```

| | |
|------------|----------------------------|
| stateProbs | <i>State probabilities</i> |
|------------|----------------------------|

Description

For a given model, computes the probability of the process being in the different states at each time point.

Usage

```
stateProbs(m, hierarchical = FALSE)
```

Arguments

| | |
|---------------------------|--|
| <code>m</code> | A <code>momentuHMM</code> or <code>momentuHierHMM</code> object. |
| <code>hierarchical</code> | Logical indicating whether or not to return a list of state probabilities for each level of a hierarchical HMM. Ignored unless <code>m</code> is a <code>momentuHierHMM</code> object. |

Value

The matrix of state probabilities, with element `[i,j]` the probability of being in state `j` in observation `i`.

References

Zucchini, W. and MacDonald, I.L. 2009. Hidden Markov Models for Time Series: An Introduction Using R. Chapman & Hall (London).

Examples

```
# m is a momentuHMM object (as returned by fitHMM), automatically loaded with the package
m <- example$m

sp <- stateProbs(m)
```

| | |
|------------|---------------------------------------|
| stationary | <i>Stationary state probabilities</i> |
|------------|---------------------------------------|

Description

Calculates the stationary probabilities of each state based on covariate values.

Usage

```
stationary(model, covs, covIndex)
```


Arguments

| | |
|----------|--|
| model | momentuHMM, miHMM, or miSum object |
| covs | Either a data frame or a design matrix of covariates. If covs is not provided, then the stationary probabilities are calculated based on the covariate data for each time step. |
| covIndex | Integer vector indicating specific rows of the data to be used in the calculations. This can be useful for reducing unnecessarily long computation times, e.g., when formula includes factor covariates (such as ID) but no temporal covariates. Ignored unless covs is missing. |

Value

A list of length `model$conditions$mixtures` where each element is a matrix of stationary state probabilities for each mixture. For each matrix, each row corresponds to a row of `covs`, and each column corresponds to a state.

Examples

```
# m is a momentuHMM object (as returned by fitHMM), automatically loaded with the package
m <- example$m

# data frame of covariates
stationary(m, covs = data.frame(cov1 = 0, cov2 = 0))

# design matrix (each column corresponds to row of m$mle$beta)
stationary(m, covs = matrix(c(1,0,cos(0)),1,3))

# get stationary distribution for first 3 observations
stationary(m, covIndex = c(1,2,3))
```

stationary_rcpp

Stationary distribution for a continuous-time Markov chain

Description

Written in C++.

Usage

```
stationary_rcpp(A)
```

Arguments

A transition rate matrix (of dimension `nbStates` x `nbStates`)

Value

row vector of stationary distribution probabilities

```
summary.momentuHMMData
```

Summary momentuHMMData

Description

Summary momentuHMMData

Usage

```
## S3 method for class 'momentuHMMData'
summary(object, dataNames = c("step", "angle"), animals = NULL, ...)

## S3 method for class 'momentuHierHMMData'
summary(object, dataNames = c("step", "angle", "level"), animals = NULL, ...)
```

Arguments

| | |
|-----------|---|
| object | A momentuHMMData or momentuHierHMMData object. |
| dataNames | Names of the variables to summarize. Default is <code>dataNames=c("step","angle")</code> . |
| animals | Vector of indices or IDs of animals for which data will be summarized. Default: NULL ; data for all animals are summarized. |
| ... | Currently unused. For compatibility with generic method. |

Examples

```
# data is a momentuHMMData object (as returned by prepData), automatically loaded with the package
data <- example$m$data

summary(data,dataNames=c("step","angle","cov1","cov2"))
```

| | |
|--------------|--|
| timeInStates | <i>Calculate proportion of time steps assigned to each state (i.e. "activity budgets")</i> |
|--------------|--|

Description

Calculate proportion of time steps assigned to each state (i.e. "activity budgets")

Usage

```
timeInStates(m, by = NULL, alpha = 0.95, ncores = 1)

## S3 method for class 'momentuHMM'
timeInStates(m, by = NULL, alpha = 0.95, ncores = 1)

## S3 method for class 'HMMfits'
timeInStates(m, by = NULL, alpha = 0.95, ncores = 1)

## S3 method for class 'miHMM'
timeInStates(m, by = NULL, alpha = 0.95, ncores = 1)
```

Arguments

| | |
|---------------------|--|
| <code>m</code> | A momentuHMM , miHMM , or HMMfits object. |
| <code>by</code> | A character vector indicating any groupings by which to calculate the proportions, such as individual (“ID”) or group-level (e.g. sex or age class) covariates. Default is NULL (no groupings are used). |
| <code>alpha</code> | Significance level for calculating confidence intervals of pooled estimates. Default: 0.95. Ignored unless <code>m</code> is a miHMM or HMMfits object. |
| <code>ncores</code> | Number of cores to use for parallel processing. Default: 1 (no parallel processing). Ignored unless <code>m</code> is a miHMM or HMMfits object. |

Details

If `m` is a continuous-time HMM, then the time in states is calculated based on the actual amount of time that was spent in each state (based on `m$data$dt`) instead of the proportion of time steps assigned to each state.

Value

If `m` is a [momentuHMM](#) object, a data frame containing the estimated activity budgets for each state (grouped according to `by`). If `m` is a [miHMM](#) or [HMMfits](#) object, a list containing the activity budget estimates, standard errors, lower bounds, and upper bounds across all imputations.

Examples

```
# m is a momentuHMM object (as returned by fitHMM), automatically loaded with the package
m <- example$m
timeInStates(m)
timeInStates(m, by = "ID")
```

trMatrix_rcpp

*Transition probability matrix***Description**

Computation of the transition probability matrix, as a function of the covariates and the regression parameters. Written in C++. Used in [viterbi](#).

Usage

```
trMatrix_rcpp(
  nbStates,
  beta,
  covs,
  betaRef,
  CT = FALSE,
  dt = as.numeric(c()),
  aInd = as.integer(c()),
  rateMatrix = FALSE,
  kappa = NA_real_,
  check = TRUE
)
```

Arguments

| | |
|------------|---|
| nbStates | Number of states |
| beta | Matrix of regression parameters |
| covs | Matrix of covariate values |
| betaRef | Indices of reference elements for t.p.m. multinomial logit link. |
| CT | logical indicating discrete-time approximation of a continuous-time model |
| dt | numeric vector of length nrow(covs) indicating the time difference between observations. Ignored unless CT=TRUE. |
| aInd | Vector of indices of the rows at which the data (i.e. covs) switches to another animal. Ignored unless CT=TRUE. |
| rateMatrix | logical indicating whether or not to return the transition rate matrix. Ignored unless CT=TRUE. |
| kappa | maximum allowed value for the row sums of the off-diagonal elements in the state transition rate matrix, such that the minimum value for the diagonal elements is $-\text{kappa}$. Default: Inf. Setting less than Inf can help avoid numerical issues during optimization, in which case the transition rate parameters beta are on the logit scale (instead of the log scale). |
| check | logical indicating whether or not to check transition probability matrix for issues. Ignored unless CT=TRUE. |

Value

Three dimensional array `trMat`, such that `trMat[, , t]` is the transition matrix at time `t`.

| | |
|-----------|----------------------|
| turnAngle | <i>Turning angle</i> |
|-----------|----------------------|

Description

Used in [prepData](#) and [simData](#).

Usage

```
turnAngle(x, y, z, type = "UTM", angleCov = FALSE)
```

Arguments

| | |
|-----------------------|---|
| <code>x</code> | First point |
| <code>y</code> | Second point |
| <code>z</code> | Third point |
| <code>type</code> | 'UTM' if easting/northing provided (the default), 'LL' if longitude/latitude. If <code>type='LL'</code> then the geosphere package must be installed. |
| <code>angleCov</code> | logical indicating to not return NA when <code>x=y</code> or <code>y=z</code> . Default: FALSE (i.e. NA is returned if <code>x=y</code> or <code>y=z</code>). |

Value

The angle between vectors `(x,y)` and `(y,z)`.

If `type='LL'` then turning angle is calculated based on initial bearings using [bearing](#).

Examples

```
## Not run:
x <- c(0,0)
y <- c(4,6)
z <- c(10,7)
momentuHMM:::turnAngle(x,y,z)

## End(Not run)
```

| | |
|---------|--------------------------|
| viterbi | <i>Viterbi algorithm</i> |
|---------|--------------------------|

Description

For a given model, reconstructs the most probable states sequence, using the Viterbi algorithm.

Usage

```
viterbi(m, hierarchical = FALSE)
```

Arguments

| | |
|---------------------------|---|
| <code>m</code> | An object <code>momentuHMM</code> or <code>momentuHierHMM</code> |
| <code>hierarchical</code> | Logical indicating whether or not to return a list of Viterbi-decoded states for each level of a hierarchical HMM. Ignored unless <code>m</code> is a <code>momentuHierHMM</code> object. |

Value

The sequence of most probable states. If `hierarchical` is TRUE, then a list of the most probable states for each level of the hierarchy is returned.

References

Zucchini, W. and MacDonald, I.L. 2009. Hidden Markov Models for Time Series: An Introduction Using R. Chapman & Hall (London).

Examples

```
# m is a momentuHMM object (as returned by fitHMM), automatically loaded with the package
m <- example$m

# reconstruction of states sequence
states <- viterbi(m)
```

| | |
|-----|--|
| w2n | <i>Scaling function: working to natural parameters</i> |
|-----|--|

Description

Scales each parameter from the set of real numbers, back to its natural interval. Used during the optimization of the log-likelihood.

Usage

```
w2n(
  wpar,
  bounds,
  parSize,
  nbStates,
  nbCovs,
  estAngleMean,
  circularAngleMean,
  consensus,
  stationary,
  fullDM,
  Dmind,
  nbObs,
  dist,
  Bndind,
  nc,
  meanind,
  covsDelta,
  workBounds,
  covsPi,
  TMB = FALSE
)
```

Arguments

| | |
|-------------------|--|
| wpar | Vector of working parameters. |
| bounds | Named list of 2-column matrices specifying bounds on the natural (i.e, real) scale of the probability distribution parameters for each data stream. |
| parSize | Named list indicating the number of natural parameters of the data stream probability distributions |
| nbStates | The number of states of the HMM. |
| nbCovs | The number of beta covariates. |
| estAngleMean | Named list indicating whether or not to estimate the angle mean for data streams with angular distributions ('vm' and 'wrpcauchy'). |
| circularAngleMean | Named list indicating whether to use circular-linear or circular-circular regression on the mean of circular distributions ('vm' and 'wrpcauchy') for turning angles. See fitHMM . |
| consensus | Named list indicating whether to use the circular-circular regression consensus model |
| stationary | FALSE if there are time-varying covariates in formula or any covariates in formulaDelta. If TRUE, the initial distribution is considered equal to the stationary distribution. Default: FALSE. |
| fullDM | Named list containing the full (i.e. not shorthand) design matrix for each data stream. |

| | |
|------------|---|
| DMind | Named list indicating whether fullDM includes individual- and/or temporal-covariates for each data stream specifies (-1,1) bounds for the concentration parameters instead of the default [0,1) bounds. |
| nbObs | Number of observations in the data. |
| dist | Named list indicating the probability distributions of the data streams. |
| Bndind | Named list indicating whether DM is NULL with default parameter bounds for each data stream. |
| nc | indicator for zeros in fullDM |
| meanind | index for circular-circular regression mean angles with at least one non-zero entry in fullDM |
| covsDelta | data frame containing the delta model covariates |
| workBounds | named list of 2-column matrices specifying bounds on the working scale of the probability distribution, transition probability, and initial distribution parameters |
| covsPi | data frame containing the pi model covariates |
| TMB | logical indicating whether or not optMethod='TMB'. Default: FALSE. |

Value

A list of:

| | |
|-------|---|
| ... | Matrices containing the natural parameters for each data stream (e.g., 'step', 'angle', etc.) |
| beta | Matrix of regression coefficients of the transition probabilities |
| delta | Initial distribution |

Examples

```
## Not run:
m<-example$m
nbStates <- 2
nbCovs <- 2
parSize <- list(step=2,angle=2)
par <- list(step=c(t(m$mle$step)),angle=c(t(m$mle$angle)))
bounds <- m$conditions$bounds
beta <- matrix(rnorm(6),ncol=2,nrow=3)
delta <- c(0.6,0.4)

#working parameters
wpar <- momentuHMM:::w2n(par,bounds,list(beta=beta),log(delta[-1]/delta[1]),nbStates,
m$conditions$estAngleMean,NULL,m$conditions$Bndind,
m$conditions$dist)

#natural parameter
p <- momentuHMM:::w2n(wpar,bounds,parSize,nbStates,nbCovs,m$conditions$estAngleMean,
m$conditions$circularAngleMean,lapply(m$conditions$dist,function(x) x=="vmConsensus"),
m$conditions$stationary,m$conditions$fullDM,
m$conditions$DMind,1,m$conditions$dist,m$conditions$Bndind,
matrix(1,nrow=length(unique(m$data$ID)),ncol=1),covsDelta=m$covsDelta,
```



```
workBounds=m$conditions$workBounds)

## End(Not run)
```

XBloop_rcpp

Get XB

Description

Loop for computation of design matrix (X) times the working scale parameters (B). Written in C++.
Used in [w2n](#).

Usage

```
XBloop_rcpp(
  DM,
  Xvec,
  nbObs,
  nr,
  nc,
  circularAngleMean,
  consensus,
  rindex,
  cindex,
  nbStates,
  refCoeff = 1
)
```

Arguments

| | |
|-------------------|---|
| DM | design matrix |
| Xvec | working parameters |
| nbObs | number of observations |
| nr | number of rows in design matrix |
| nc | number of column in design matrix |
| circularAngleMean | indicator for whether or not circular-circular regression model |
| consensus | indicator for whether or not circular-circular regression consensus model |
| rindex | row index for design matrix |
| cindex | column index for design matrix |
| nbStates | number of states |
| refCoeff | intercept coefficient for circular-circular regression model |

Value

XB matrix

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